

ITRF2014: Preliminary results and ILRS contribution

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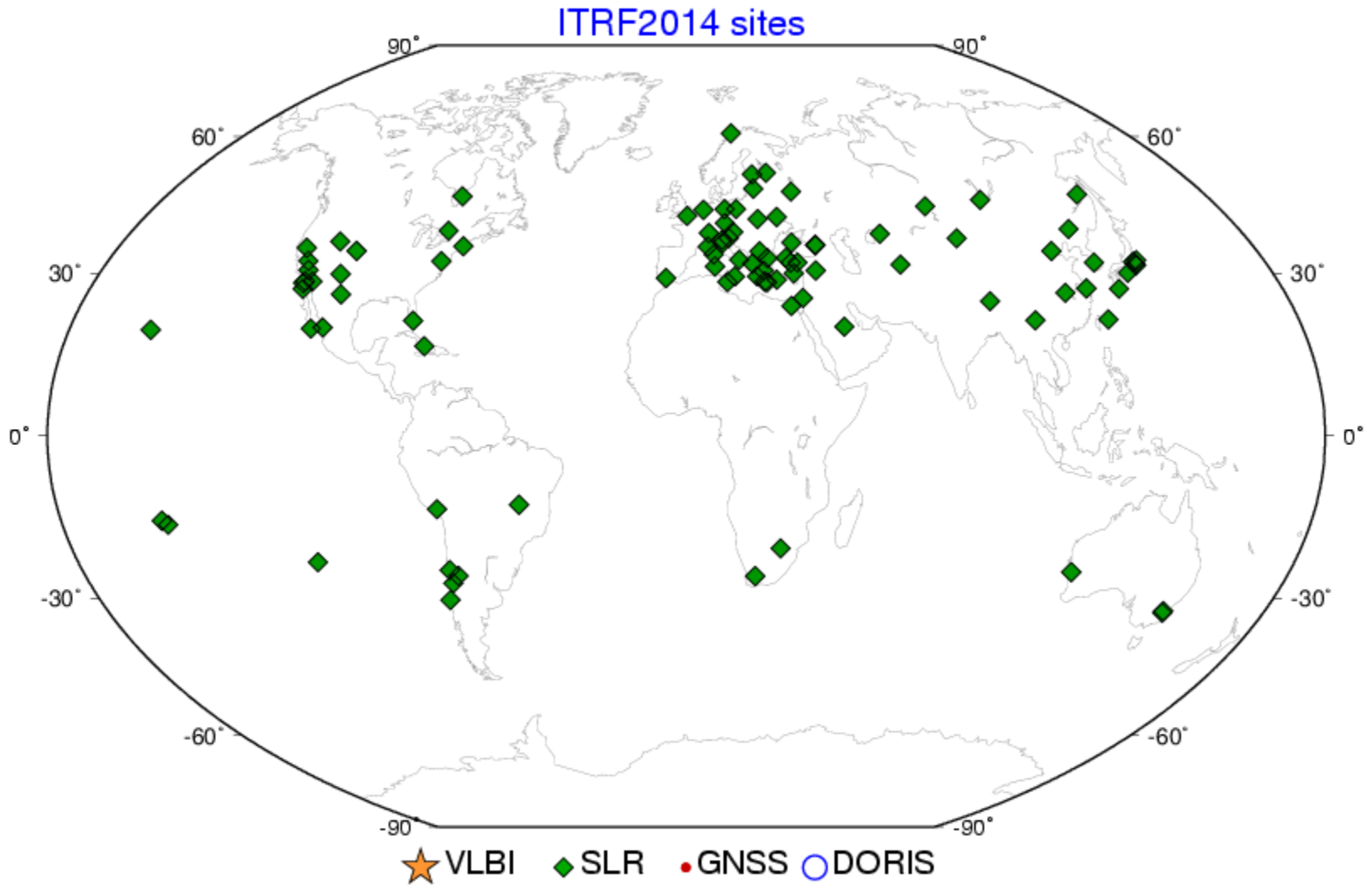
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Key Points of ITRF2014

- **Linear & Non-linear motions**
 - **Periodic signals: seasonals (e.g. annual, semi-annual)**
 - **Post-seismic deformation**

Preliminary results, but close to final

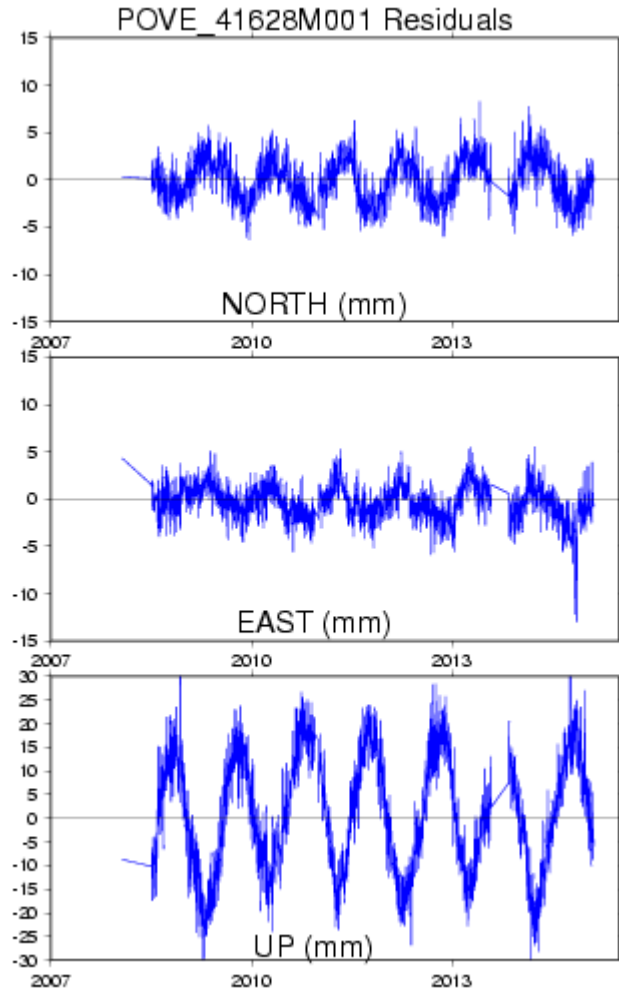
ITRF2014 : SLR



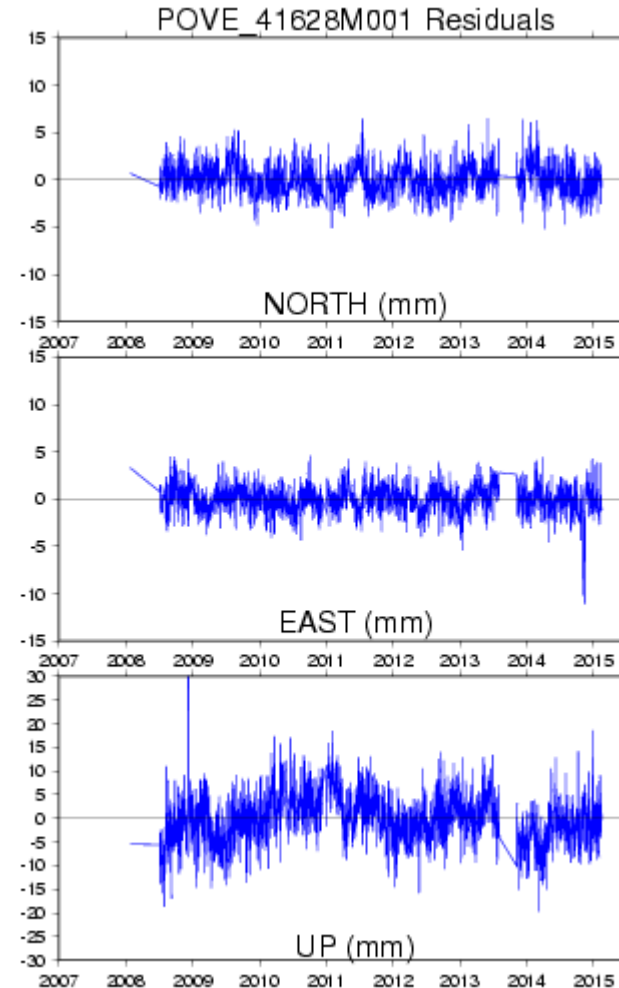
Periodic signals

POVE/ Brazil GNSS site

Standard residuals



Annual & semi-annual estimated

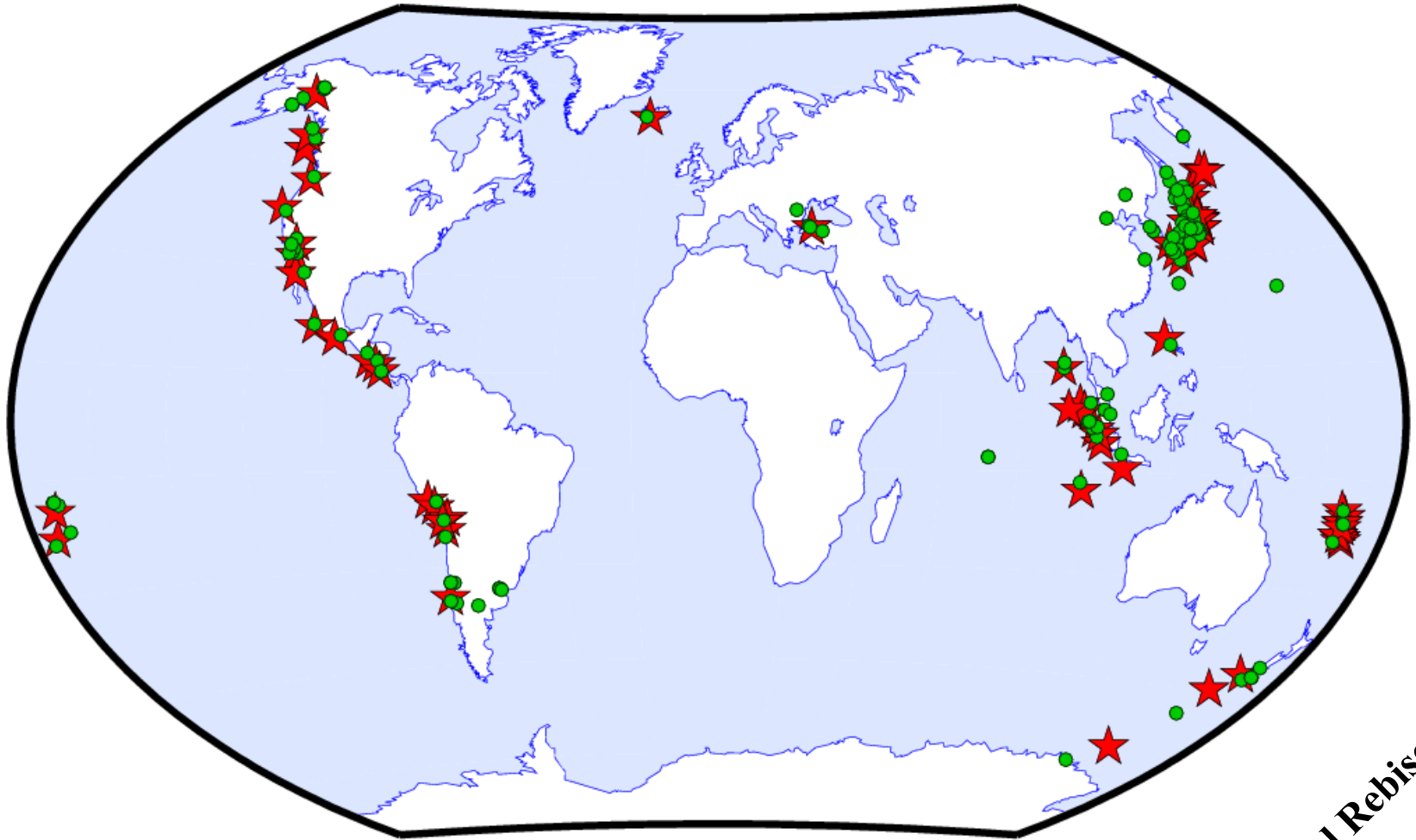


Post-Seismic Deformations

- **Fitting parametric models using GNSS/GPS data**
 - at all GNSS/GPS Earthquake sites
 - Apply these models for the 3 other techniques at Co-location EQ sites

- **Parametric models:**
 - **Logarithmic**
 - **Exponential**
 - **Log + EXP**
 - **Two EXP**

ITRF2014 Site affected by PSD



Red Stars: EQ Epicenters

Green circles: ITRF2014 sites

Artist: Paul Rebischung

Post seismic parametric models

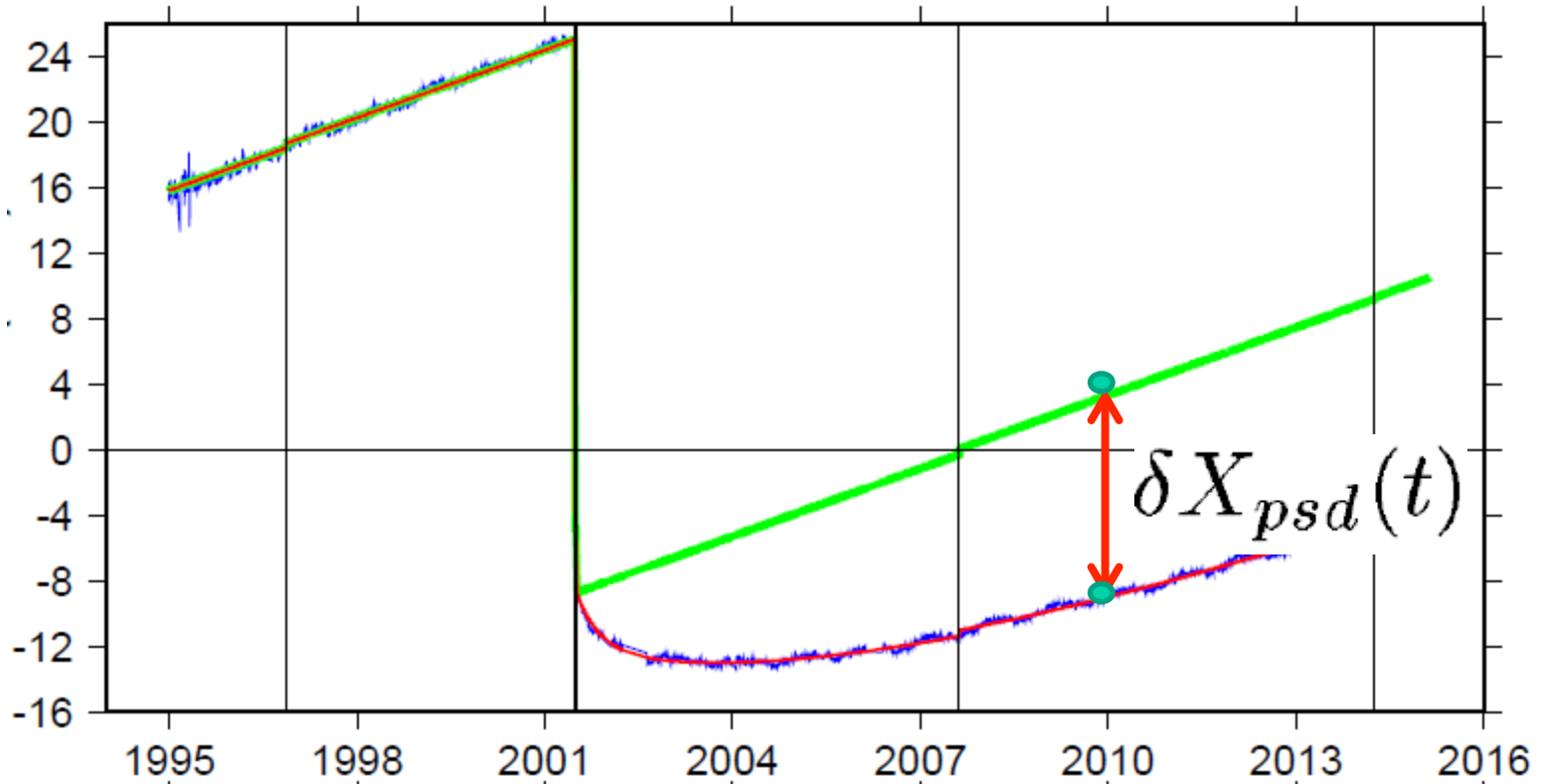
$$X(t) = X(t_0) + \dot{X}(t - t_0) + \delta X_{psd}(t)$$

$$X_{instantaneous}(t) = X(t_0) + \dot{X}(t - t_0) + \delta X_{psd}(t)$$

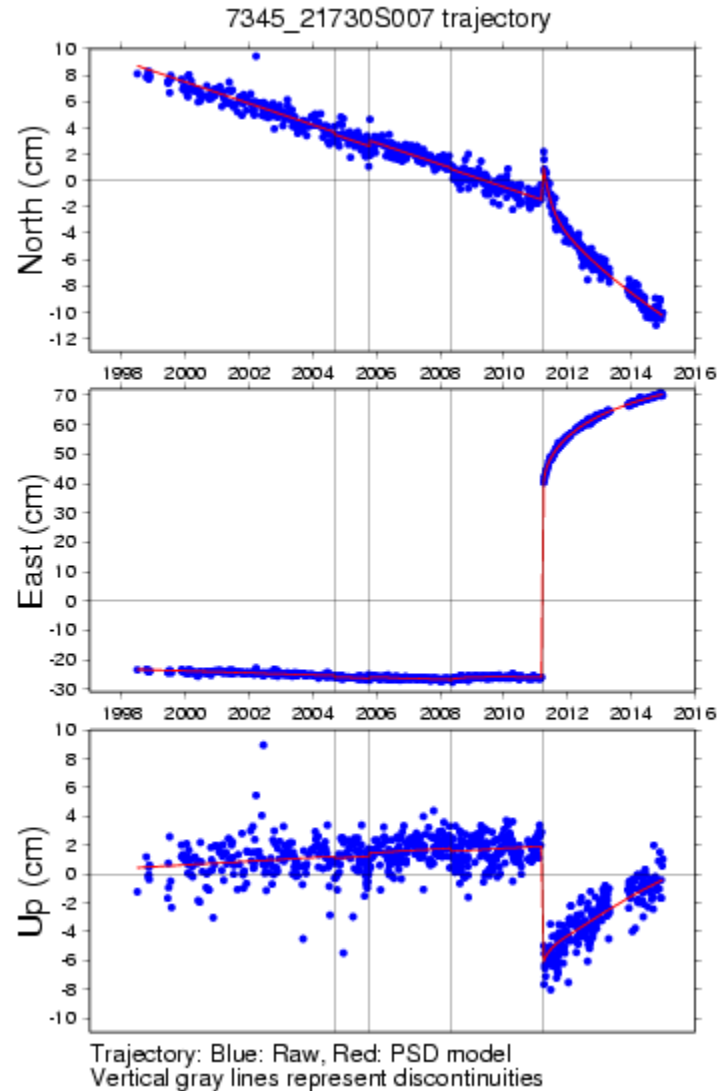
$$\delta L(t) = \sum_{i=1}^{n^l} A_i^l \log\left(1 + \frac{t - t_i^l}{\tau_i^l}\right) + \sum_{i=1}^{n^e} A_i^e \left(1 - e^{-\frac{t - t_i^e}{\tau_i^e}}\right)$$

- **Sum up all EQ contributions**
- **Applications:**
- Propagate ITRF2014 stations positions from \mathbf{t}_0 to \mathbf{t} : Should **Add (+)** the correction
- Apply the correction to a time series before stacking: Should **Subtract (-)** the correction

PSD Correction

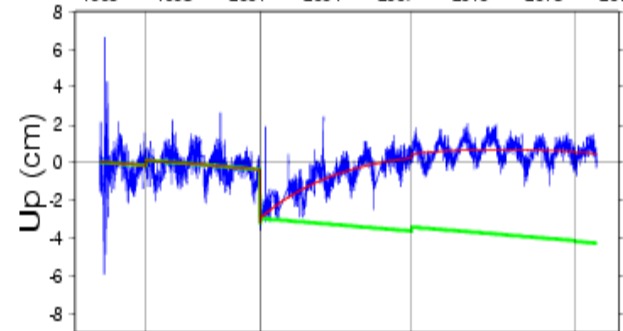
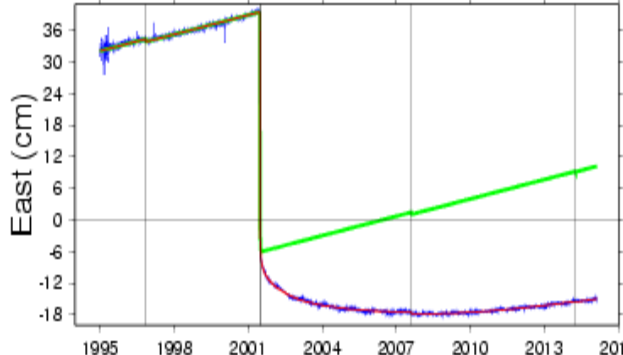
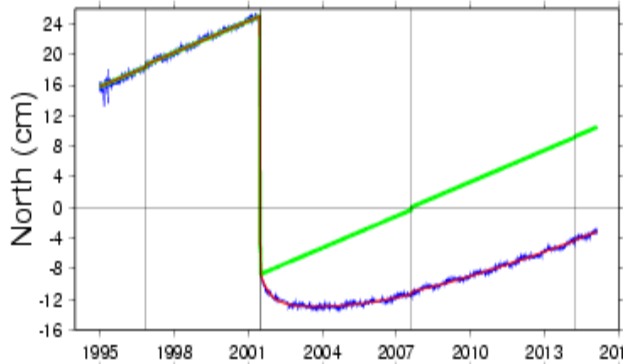


VLBI: Tsukuba PSD



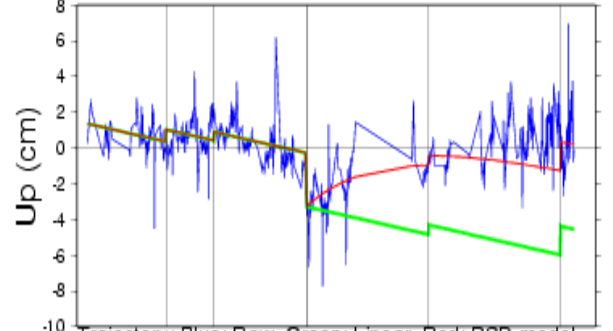
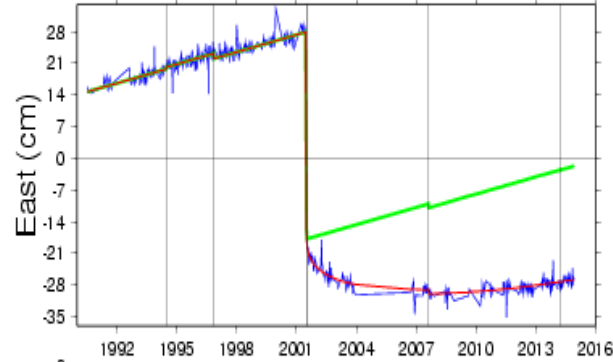
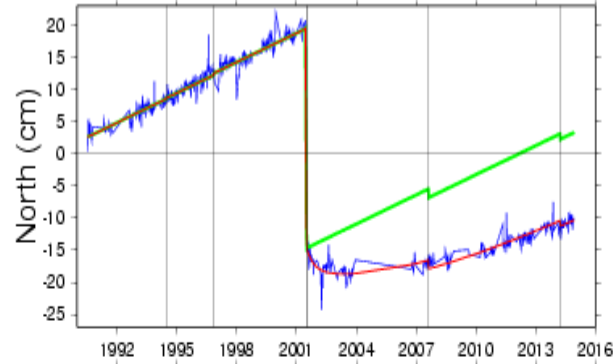
Arequipa-GPS, SLR & DORIS

AREQ_42202M005 trajectory



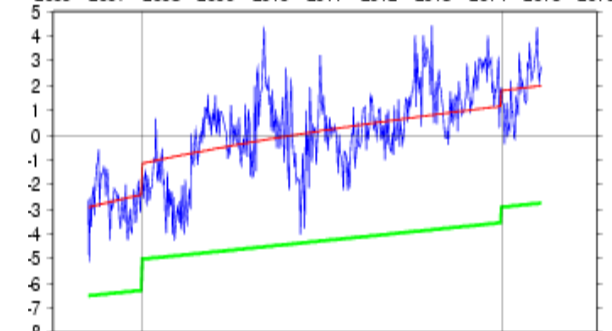
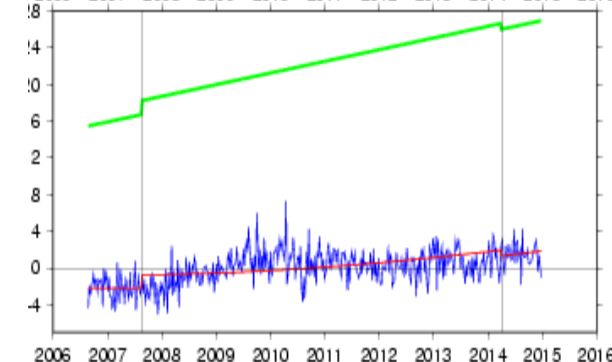
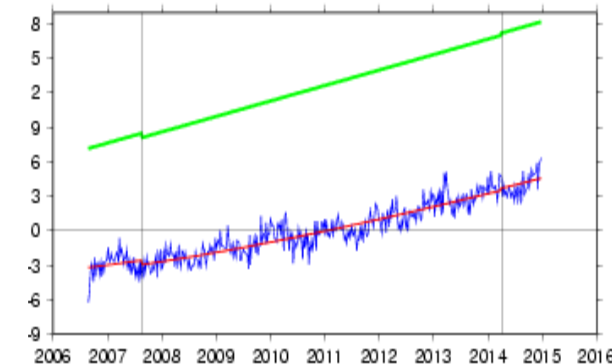
Trajectory: Blue: Raw, Green: Linear, Red: PSD model
Vertical gray lines represent discontinuities

7403_42202M003 trajectory



Trajectory: Blue: Raw, Green: Linear, Red: PSD model
Vertical gray lines represent discontinuities

ARFB_42202S007 trajectory

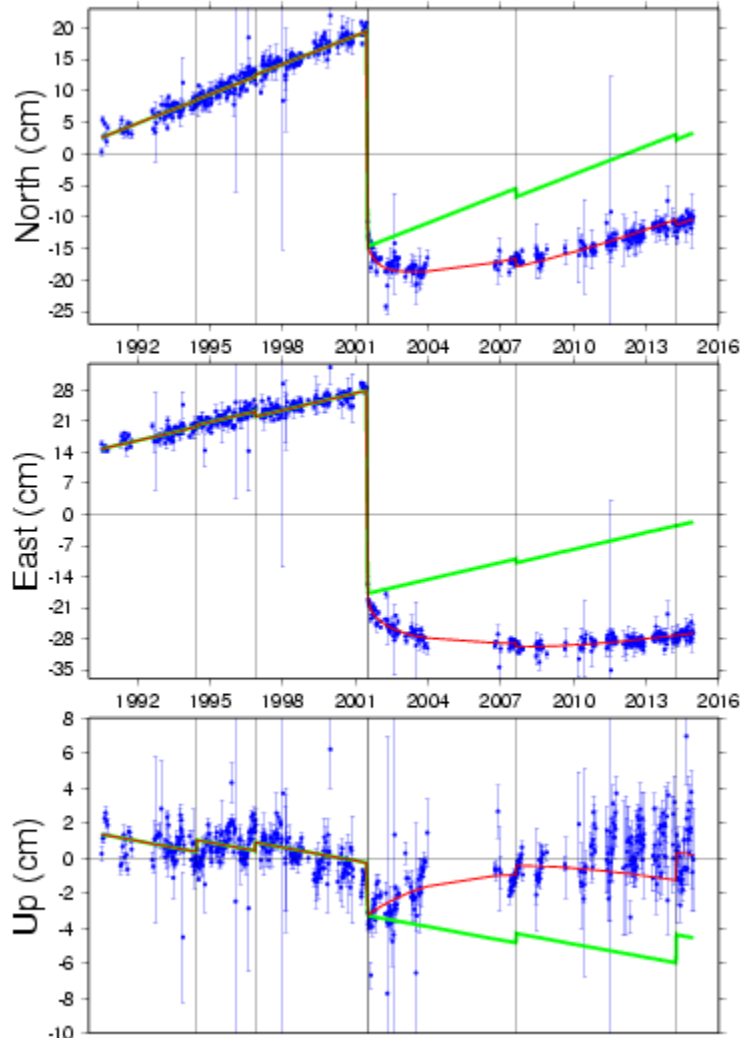


Trajectory: Blue: Raw, Green: Linear, Red: PSD model
Vertical gray lines represent discontinuities

SLR station Arequipa

Trajectory

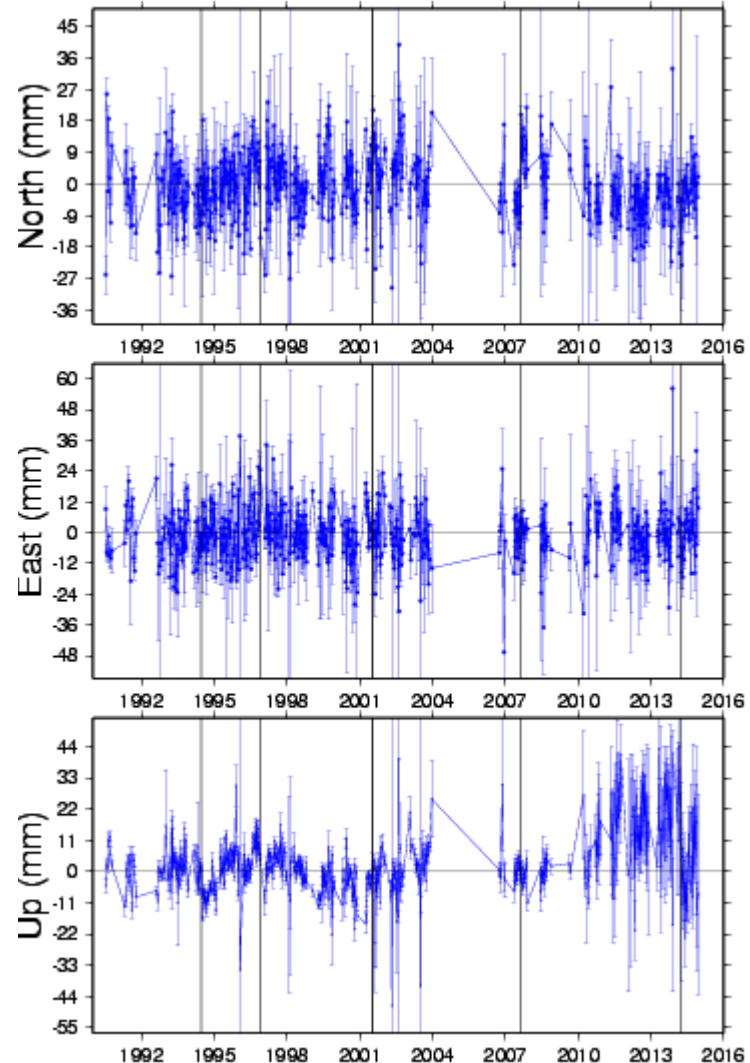
7403_42202M003 trajectory



Trajectory: Blue: Raw, Green: Linear, Red: PSD model
Vertical gray lines represent discontinuities

Residuals

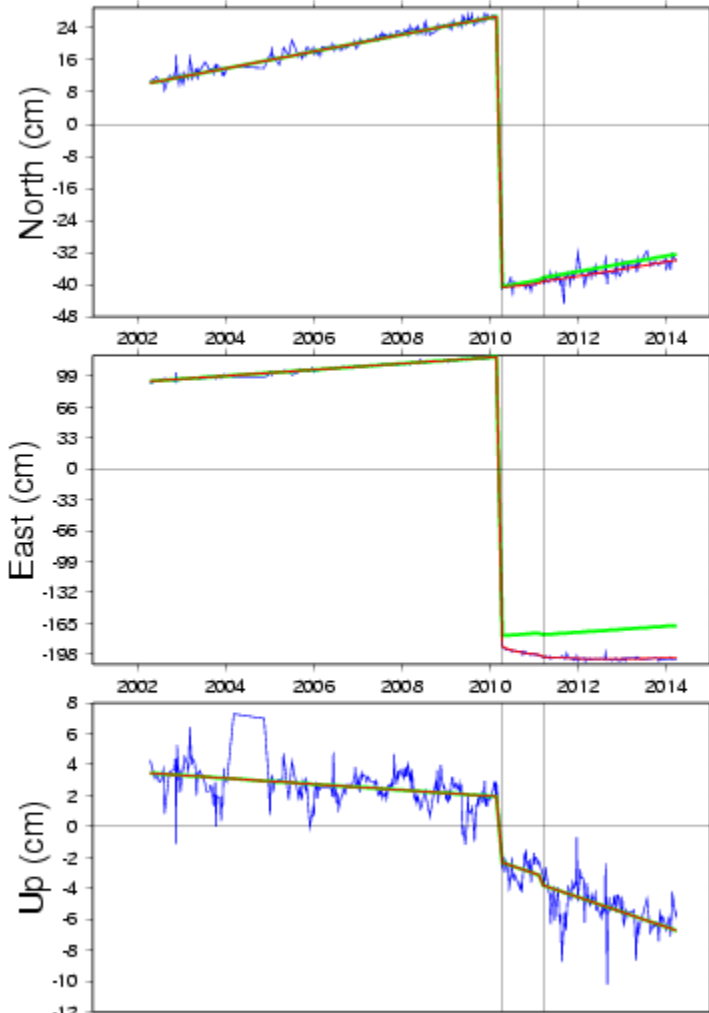
7403_42202M003 Residuals



SLR station Concepcion

Trajectory

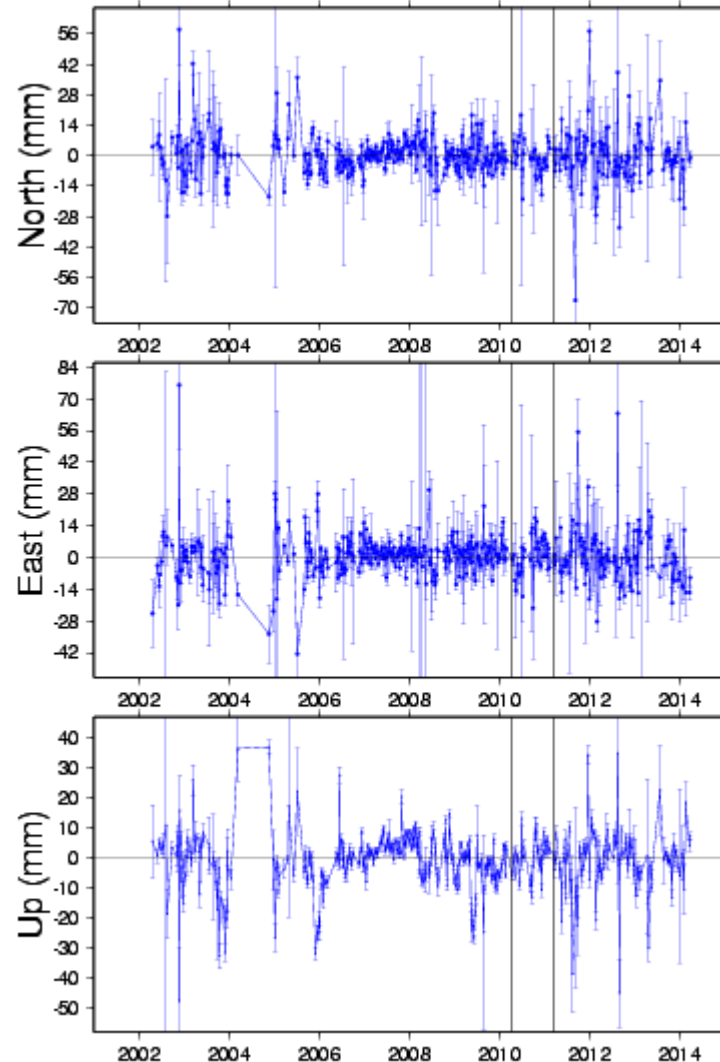
7405_41719M001 trajectory



Trajectory: Blue: Raw, Green: Linear, Red: PSD model
Vertical gray lines represent discontinuities

Residuals

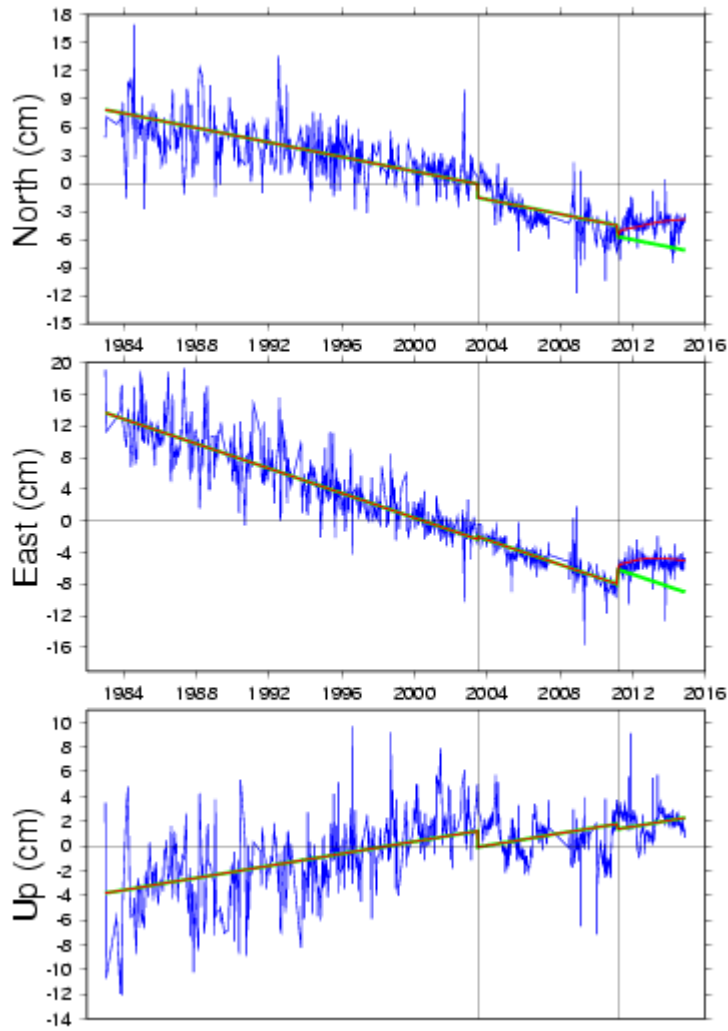
7405_41719M001 Residuals



SLR station Simosato

Trajectory

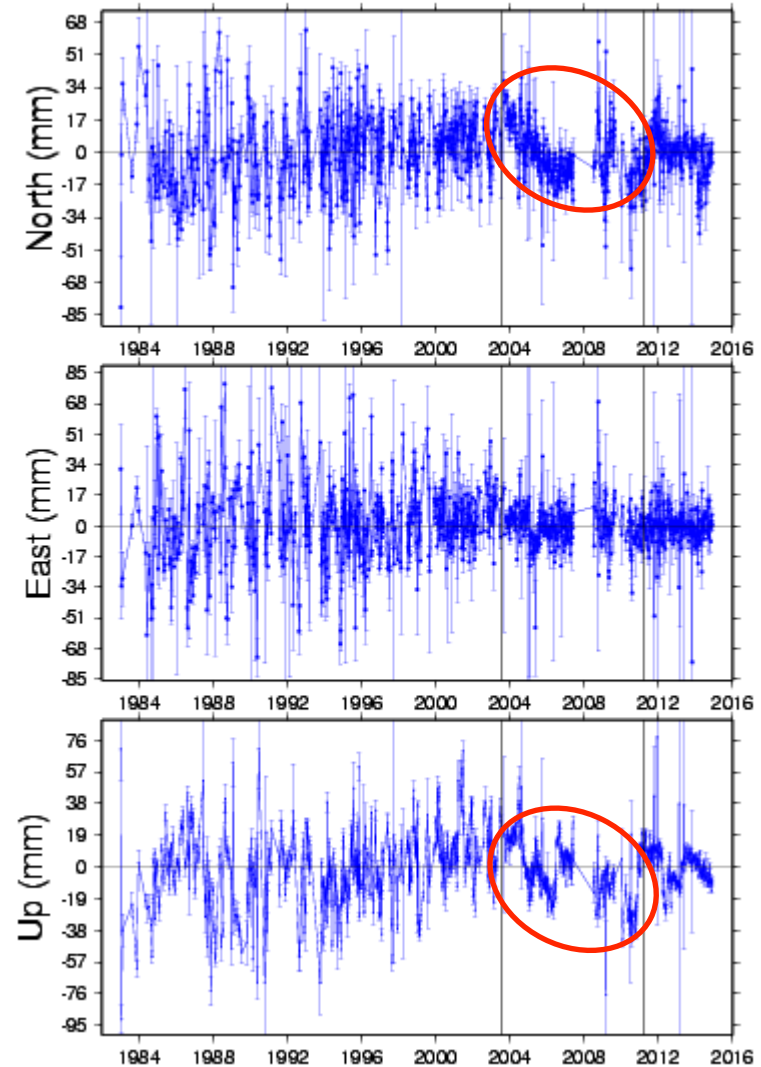
7838_21726S001 trajectory



Trajectory: Blue: Raw, Green: Linear, Red: PSD model
Vertical gray lines represent discontinuities

Residuals

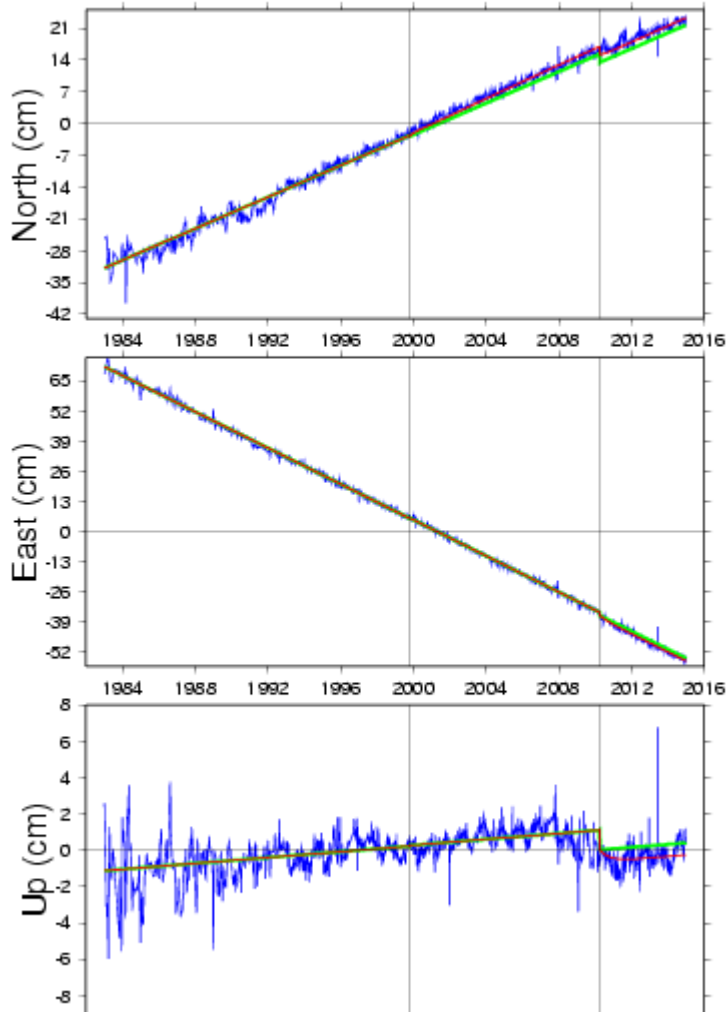
7838_21726S001 Residuals



SLR station Monument Peak

Trajectory

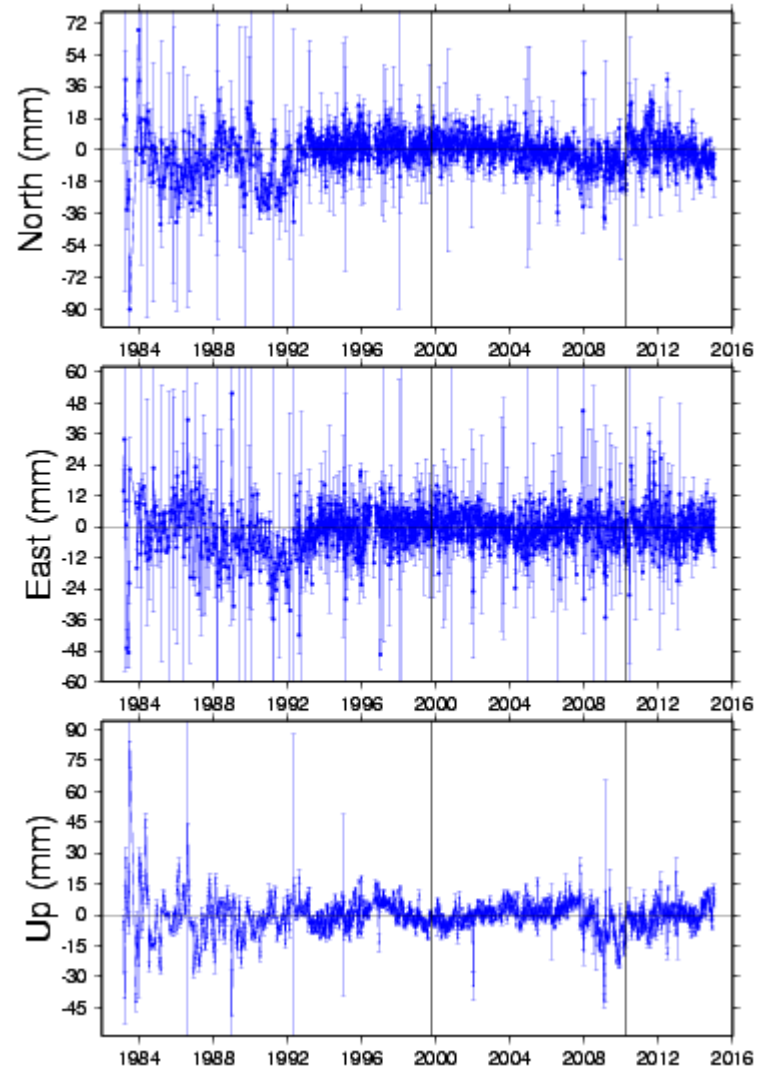
7110_40497M001 trajectory



Trajectory: Blue: Raw, Green: Linear, Red: PSD model
Vertical gray lines represent discontinuities

Residuals

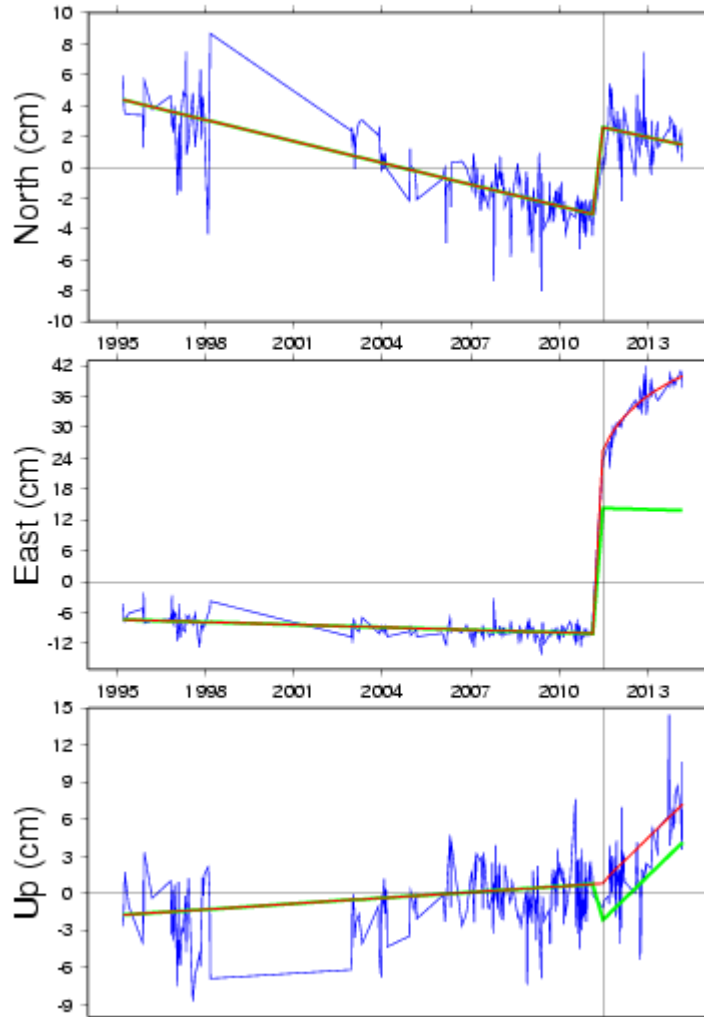
7110_40497M001 Residuals



SLR station Koganei

Trajectory

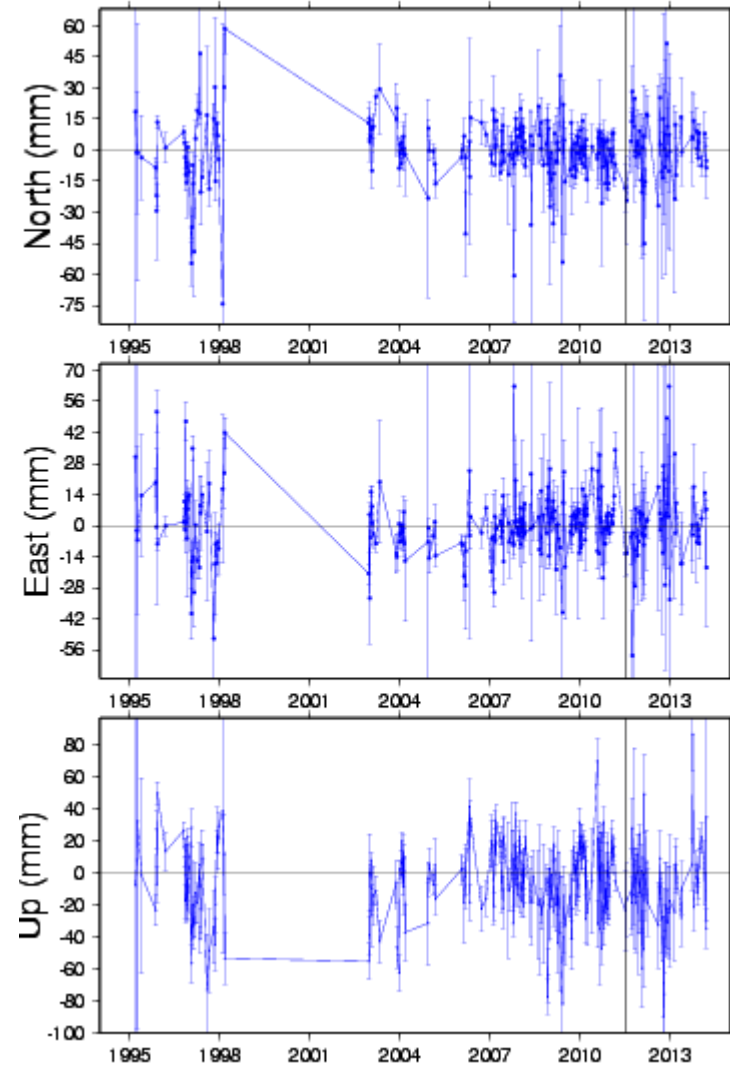
7308_21704S002 trajectory



Trajectory: Blue: Raw, Green: Linear, Red: PSD model
Vertical gray lines represent discontinuities

Residuals

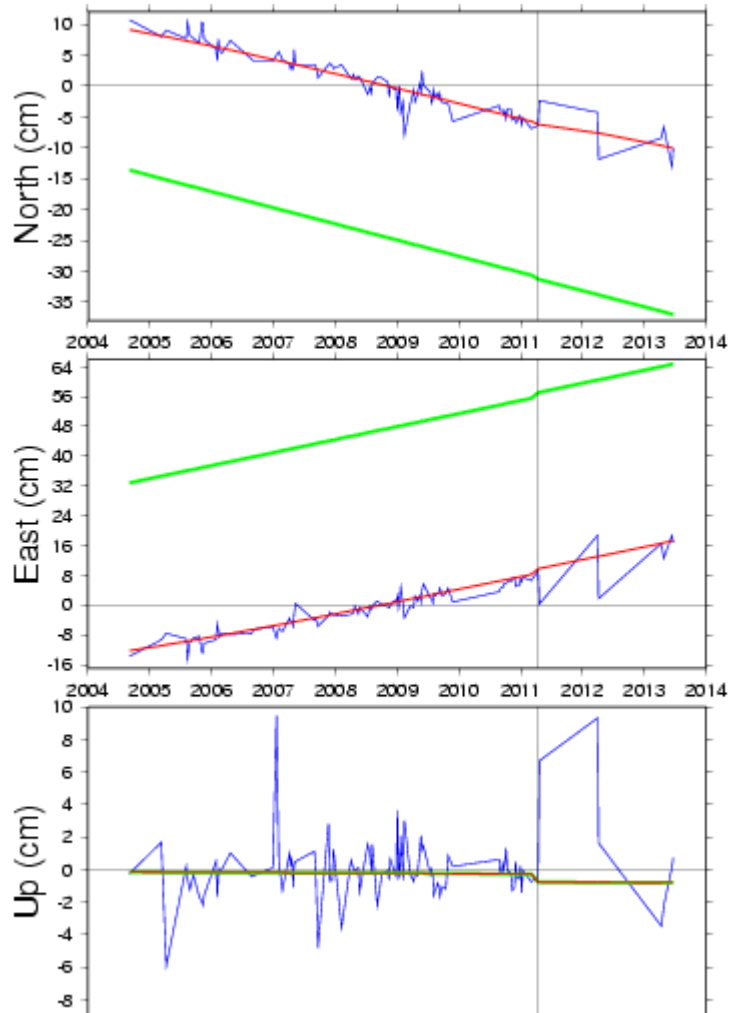
7308_21704S002 Residuals



SLR station Tanegashima Island

Trajectory

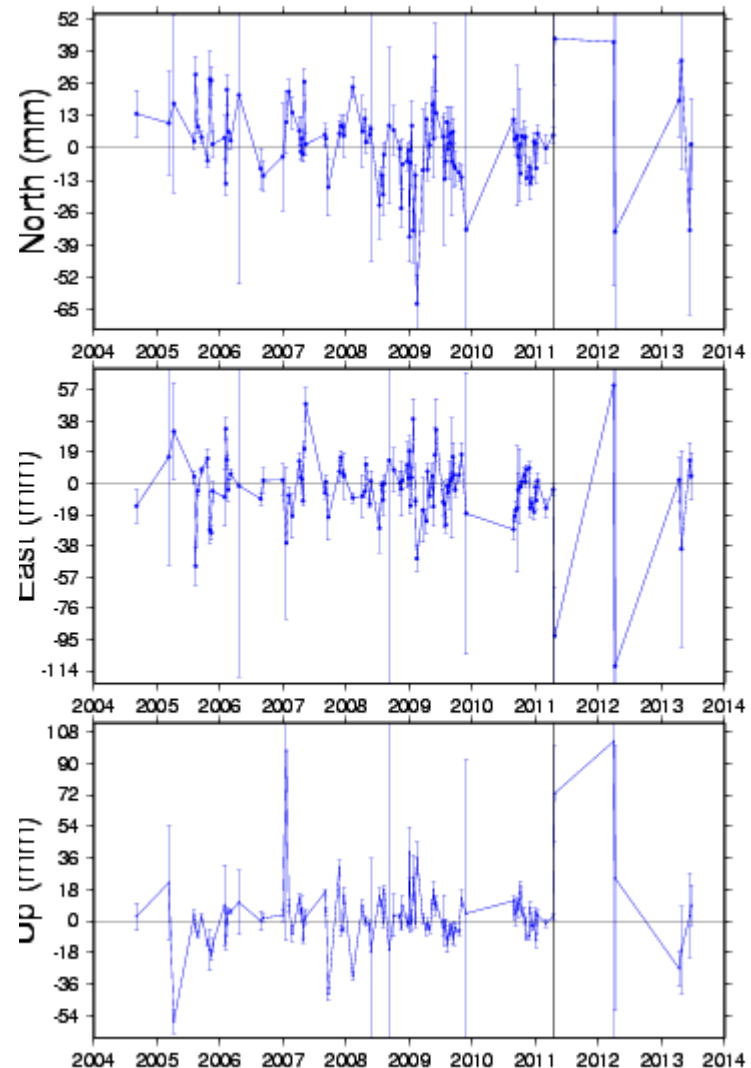
7358_21749S001 trajectory



Trajectory: Blue: Raw, Green: Linear, Red: PSD model
Vertical gray lines represent discontinuities

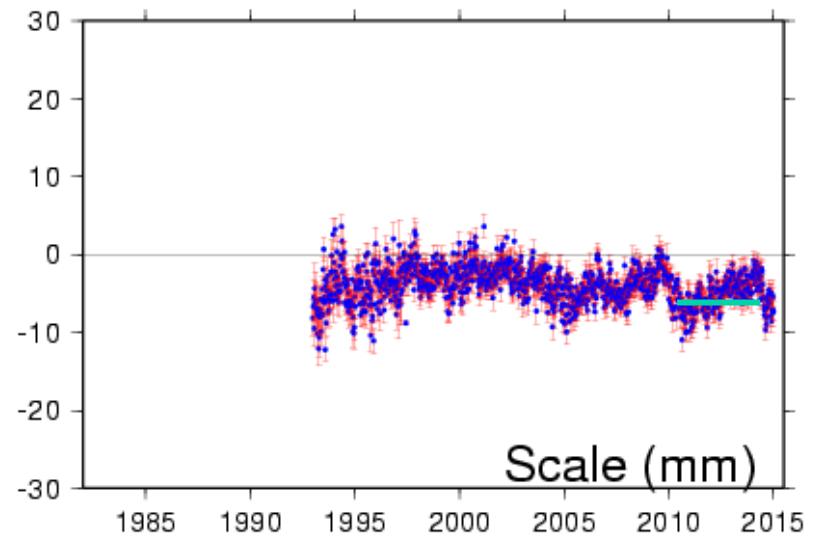
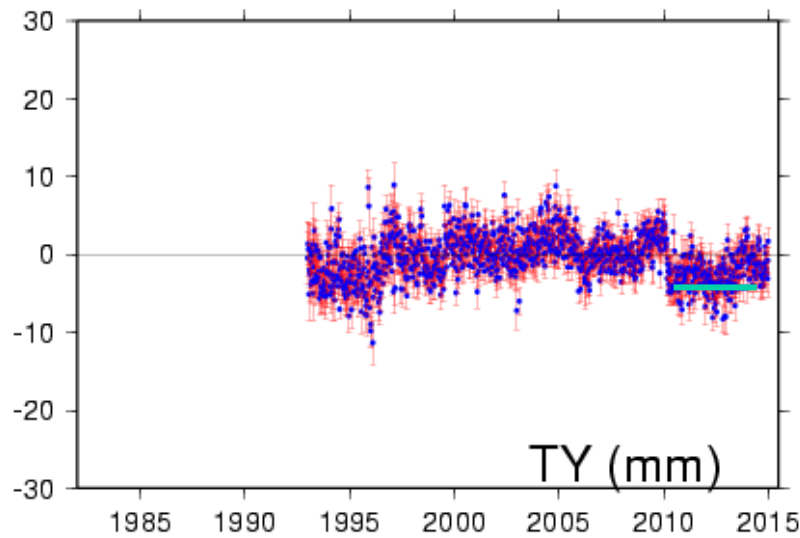
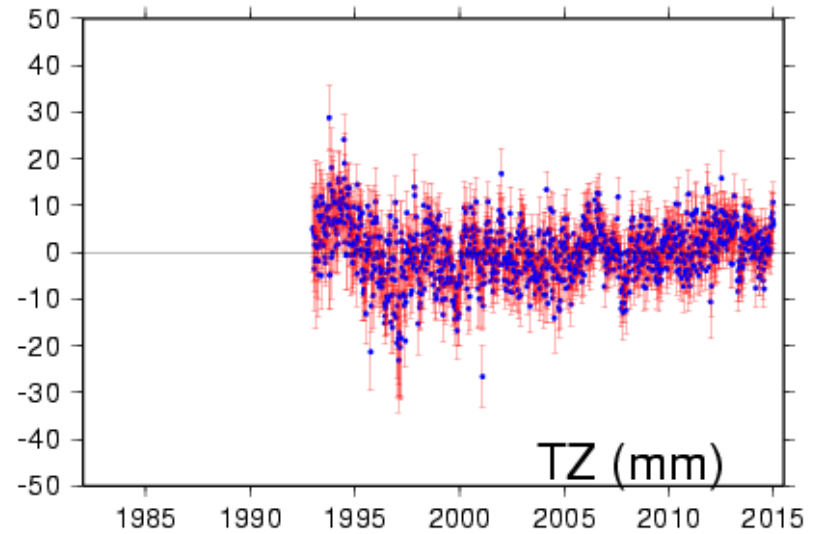
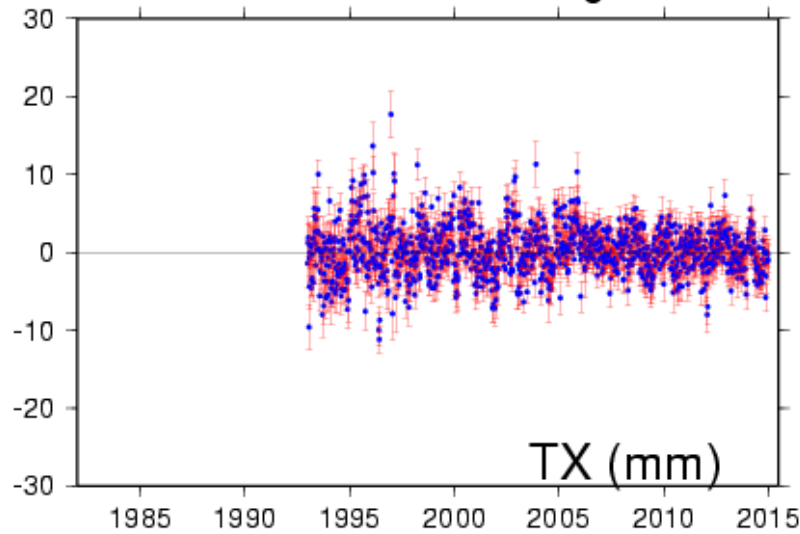
Residuals

7358_21749S001 Residuals



SLR Origin & Scale WRT ITRF2014P

ILRS origin and scale wrt ITRF2014P



Consistency of ILRS SLR and ITRF2014P

Origin and Scale at epoch 2010.0 , and rates
from ITRF2014P to ILRS Cumulative Solution

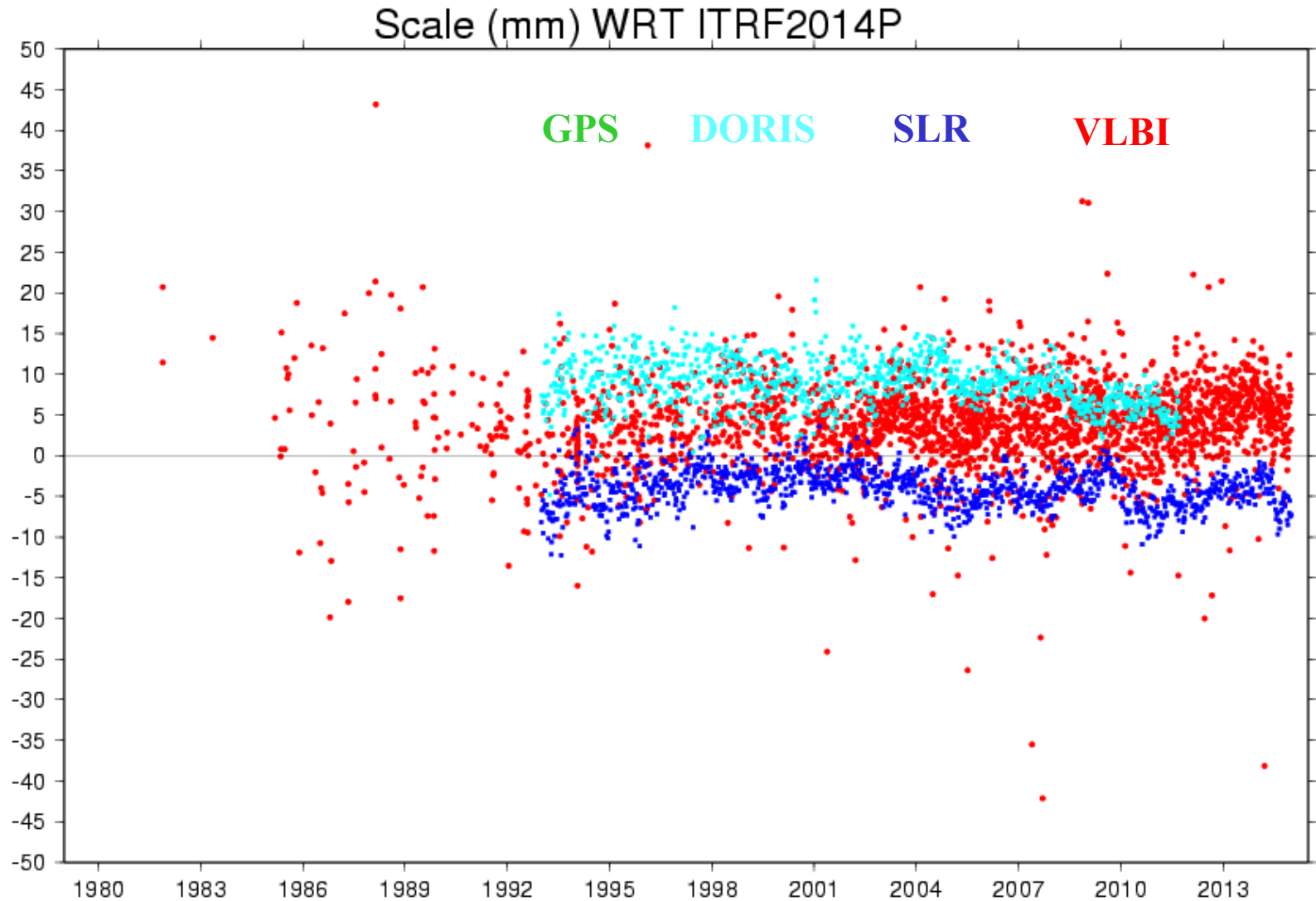
	Tx (mm)	Ty (mm)	Tz (mm)	Scale (ppb)
At 2010.0	0.1 (± 0.1)	0.2 (± 0.1)	0.0 (± 0.1)	-0.72 (± 0.02)
Rates (mm/yr)	0.0 (± 0.1)	0.0 (± 0.1)	0.0 (± 0.1)	-0.01 (± 0.01)

WRMS of fit

	East	North	Up
Positions (mm)	0.7	0.9	0.4
Velocities (mm/yr)	0.4	0.4	0.2

stations
133

VLBI, SLR, DORIS & GPS Scales wrt ITRF2014P



ASI AC&CC

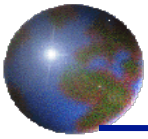
ITRF2014P evaluation



V. Luceri, B. Pace
eGEOS S.p.A., CGS – Matera

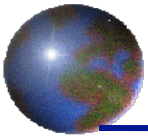


G. Bianco
Agenzia Spaziale Italiana, CGS - Matera



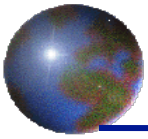
Outline

- Post-Seismic Deformation (PSD) Model
- Discontinuities
- 1983-2014 ILRSA v61 transformed into ITRF2014P (transformation into SLRF2008 already available)
- Analysis of SSC residuals
- Analysis of Helmert parameters (Translations&Scale)



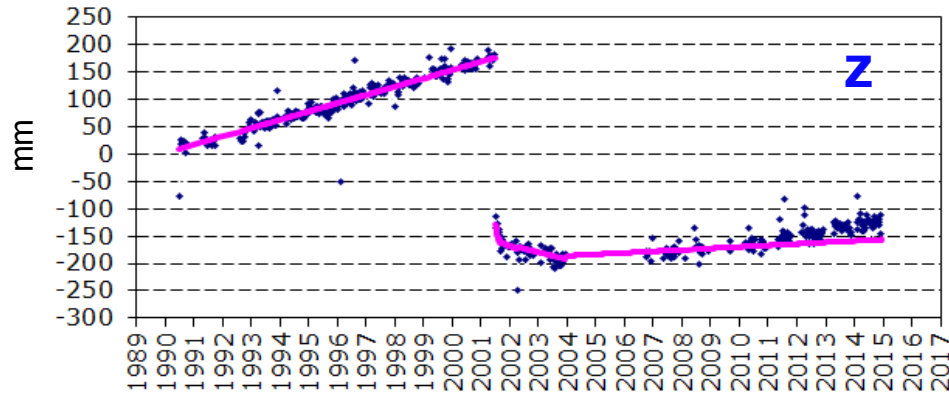
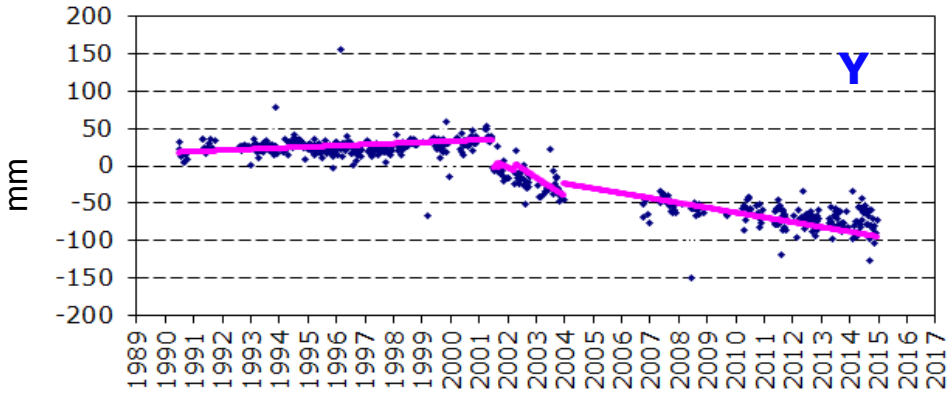
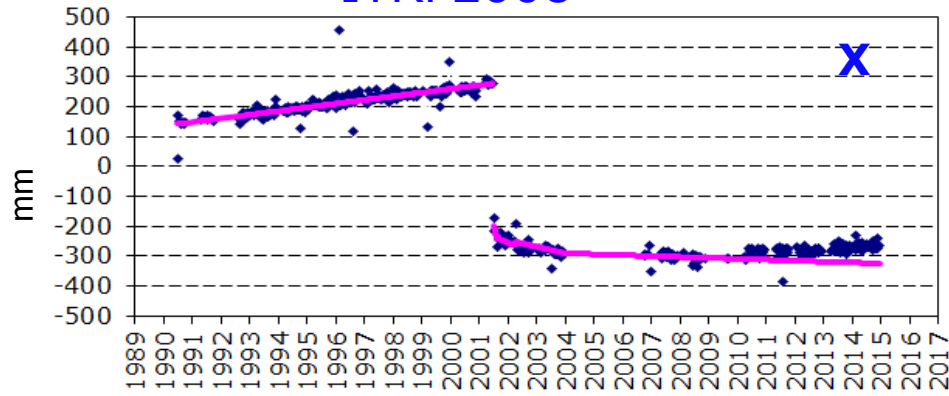
ITRF2014P

- The SINEX file with ITRF2014P and the discontinuity file are formally correct and usable
- The Post Seismic Deformation model source code and input file are easy to use and integrated into our processing chain.
- PSD is now implemented into the SW for the SLR data analysis, for the combination and for the solution comparison/checking.
- Discontinuities under discussion for some stations
- New ASI time series using ITRF2014P, analyzing the data from 2009 to 2014. No issue found.

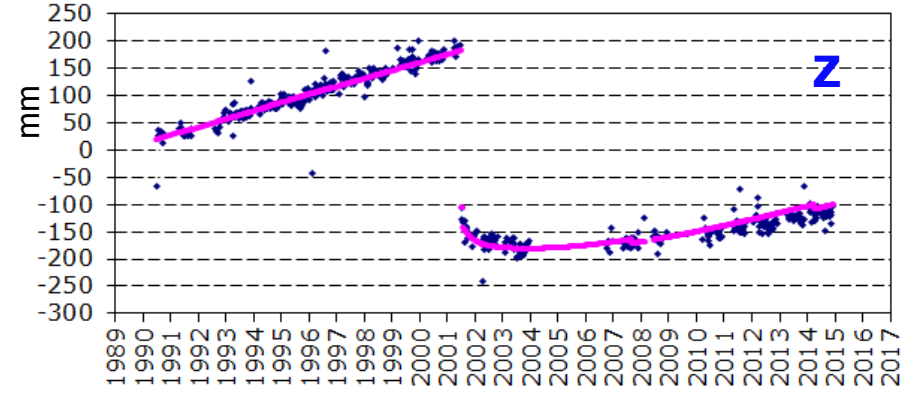
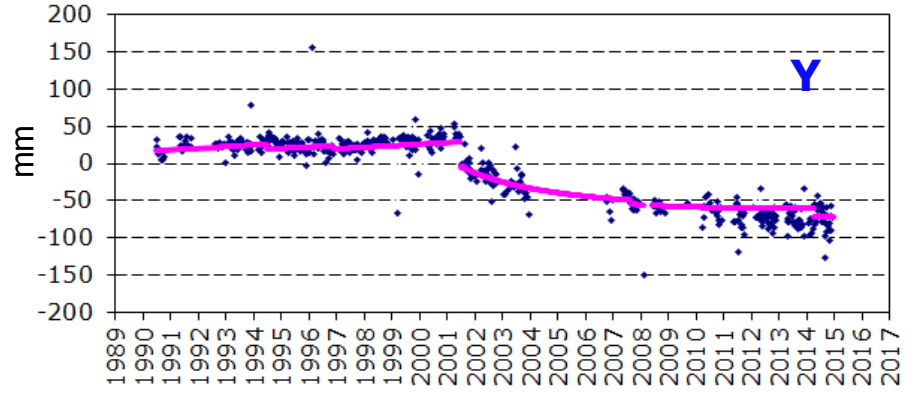
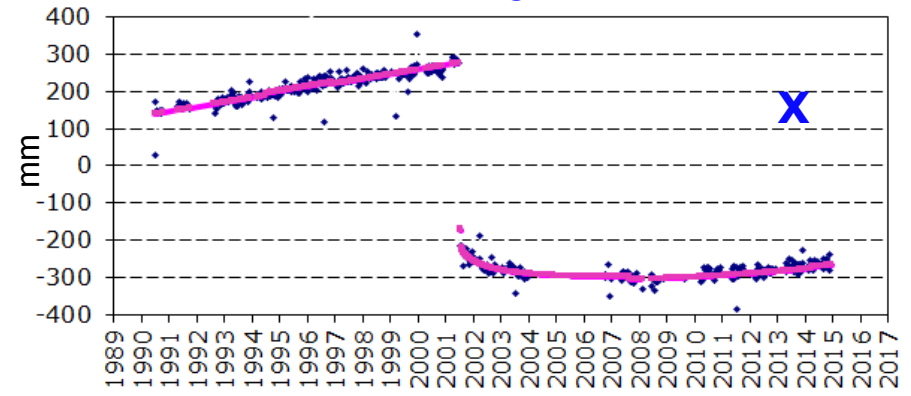


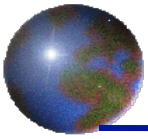
PSD Model: 7403 Arequipa, Peru

ITRF2008



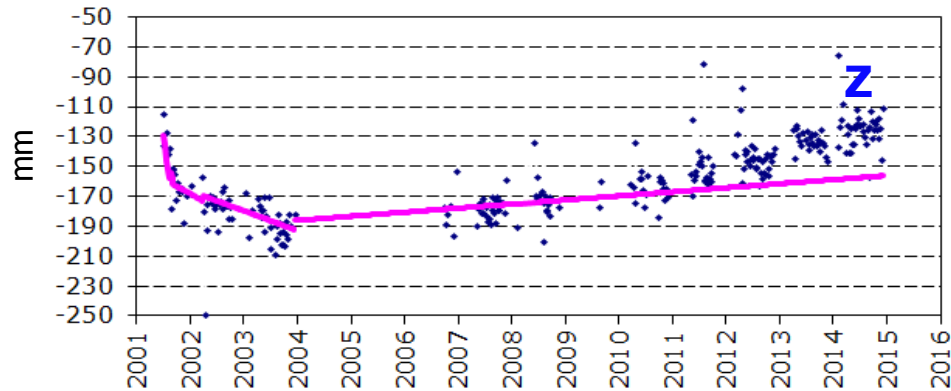
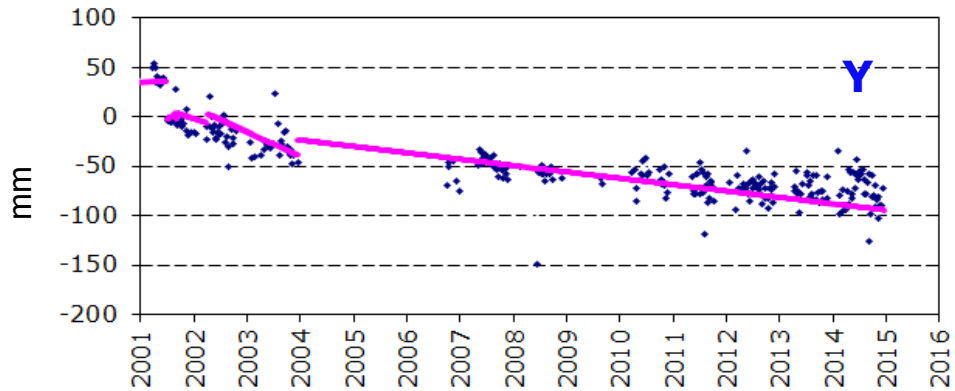
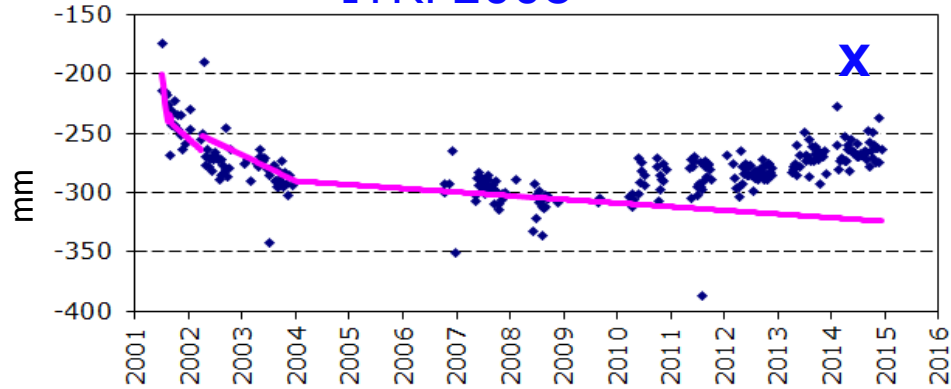
ITRF2014P



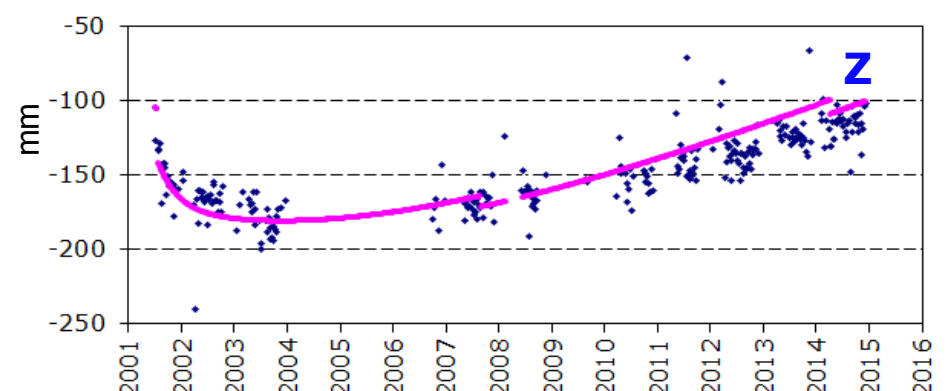
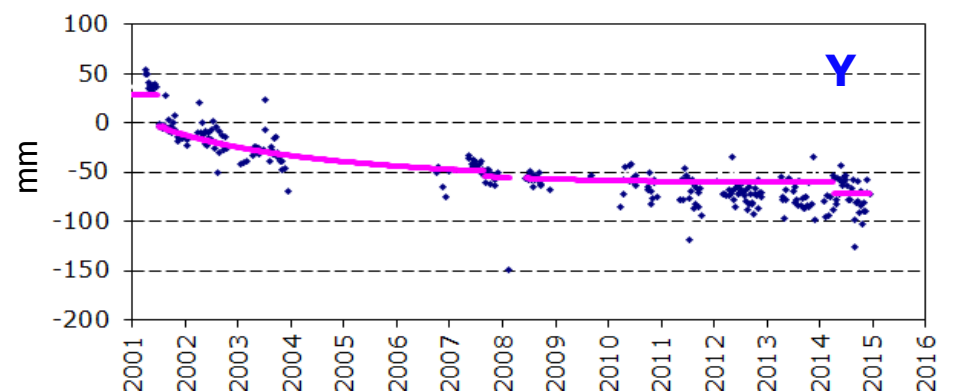
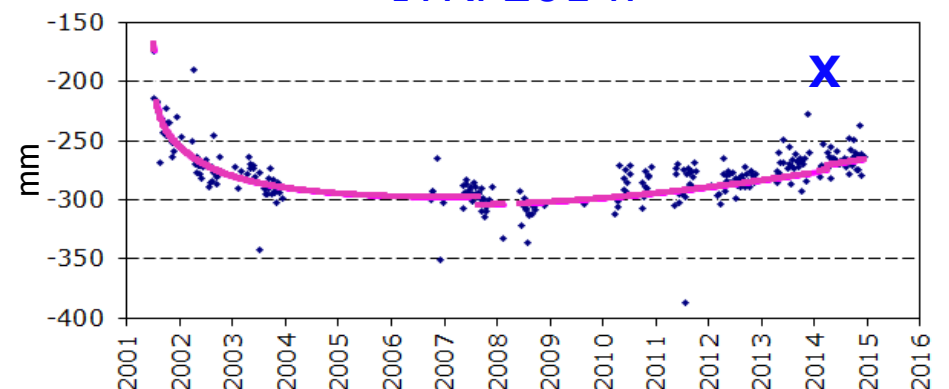


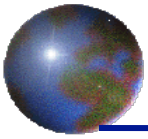
PSD Model: 7403 Arequipa, Peru

ITRF2008



ITRF2014P

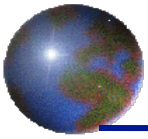




Discontinuities in ITRF2014P

	Discontinuities					
	yyyy:doj	yyyy:doj	yyyy:doj	yyyy:doj	yyyy:doj	yyyy:doj
1868	2003:157					
1893	2008:298					
7110	1999:289 E	2010:092 E				
7122	1985:266	1991:087				
7124	2001:138					
7210	1989:263	1994:020	1999:216			
7237	2011:069 E					
7249	2011:031 E					
7307	1997:307					
7308	2011:056 E					
7358	2011:064 E					
7403	1994:161	1996:321	2001:166 E	2001:186	2007:230	2014:093
7405	2010:058 E	2011:038				
7406	2010:051					
7501	2012:098					
7811	2002:208					
7820	2002:098					
7821	2009:135	2010:028	2011:068 E			
7835	1990:078					
7837	1995:229					
7838	2003:100	2011:049 E				
7839	1995:332	1999:316				
7843	1992:126					
7907	1988:104					
8834	2000:343	2009:045				

E=earthquake



Questionable discontinuities

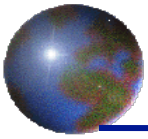
	Discontinuities					
	yyyy:doj	yyyy:doj	yyyy:doj	yyyy:doj	yyyy:doj	yyyy:doj
1868	2003:157					
1893	2008:298					
7110	1999:289 E	2010:092 E				
7122	1985:266	1991:087				
7124	2001:138					
7210	1989:263	1994:020	1999:216			
7237	2011:069 E					
7249	2011:031 E					
7307	1997:307					
7308	2011:056 E					
7358	2011:064 E					
7403	1994:161	1996:321	2001:166 E	2001:186	2007:230	2014:093
7405	2010:058 E	2011:038				
7406	2010:051					
7501	2012:098					
7811	2002:208					
7820	2002:098					
7821	2009:135	2010:028	2011:068 E			
7835	1990:078					
7837	1995:239					
7838	2003:100	2011:049 E				
7839	1995:332	1999:316				
7843	1992:126					
7907	1988:104					
8834	2000:343	2009:045				

+ 2010:058 E

2004:249 E instead of

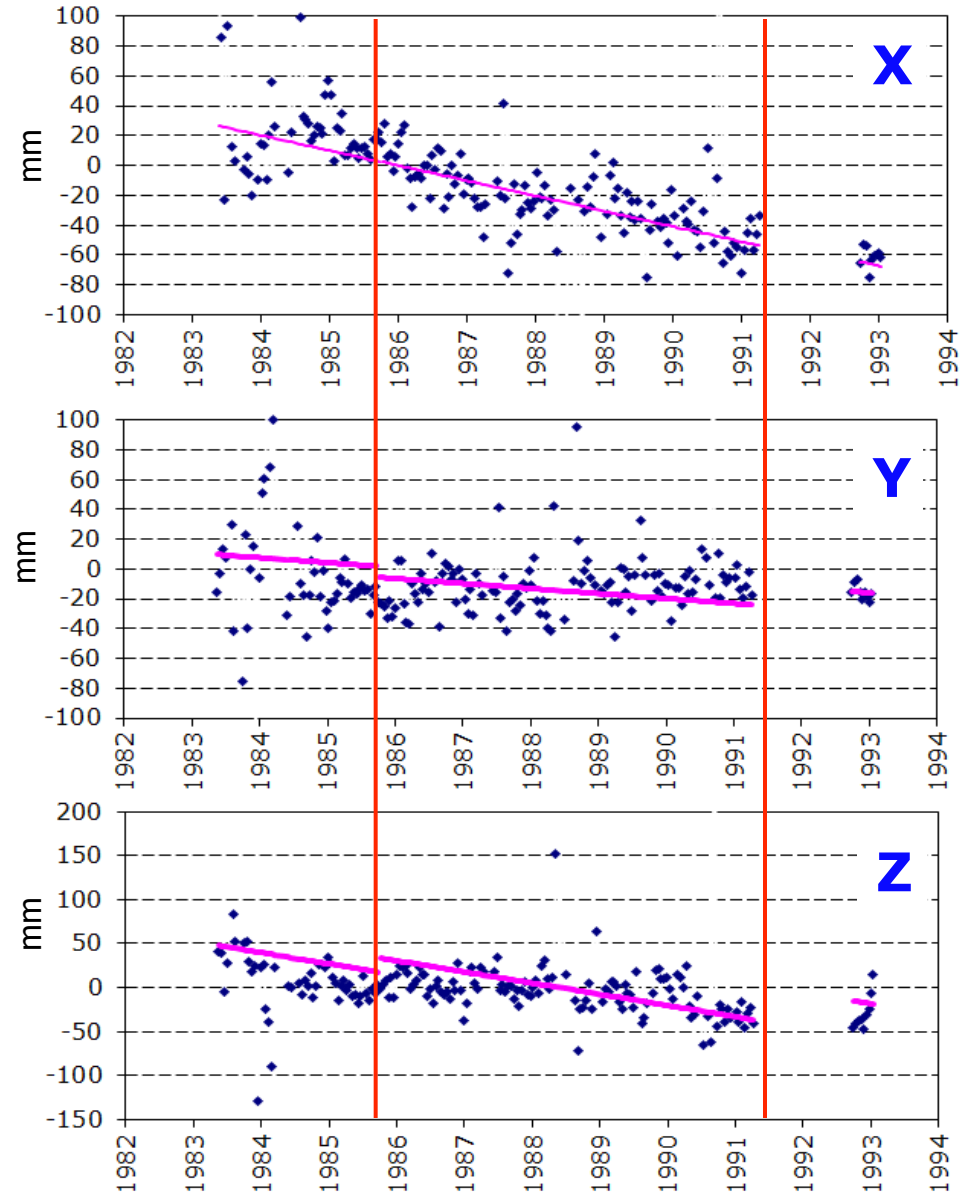
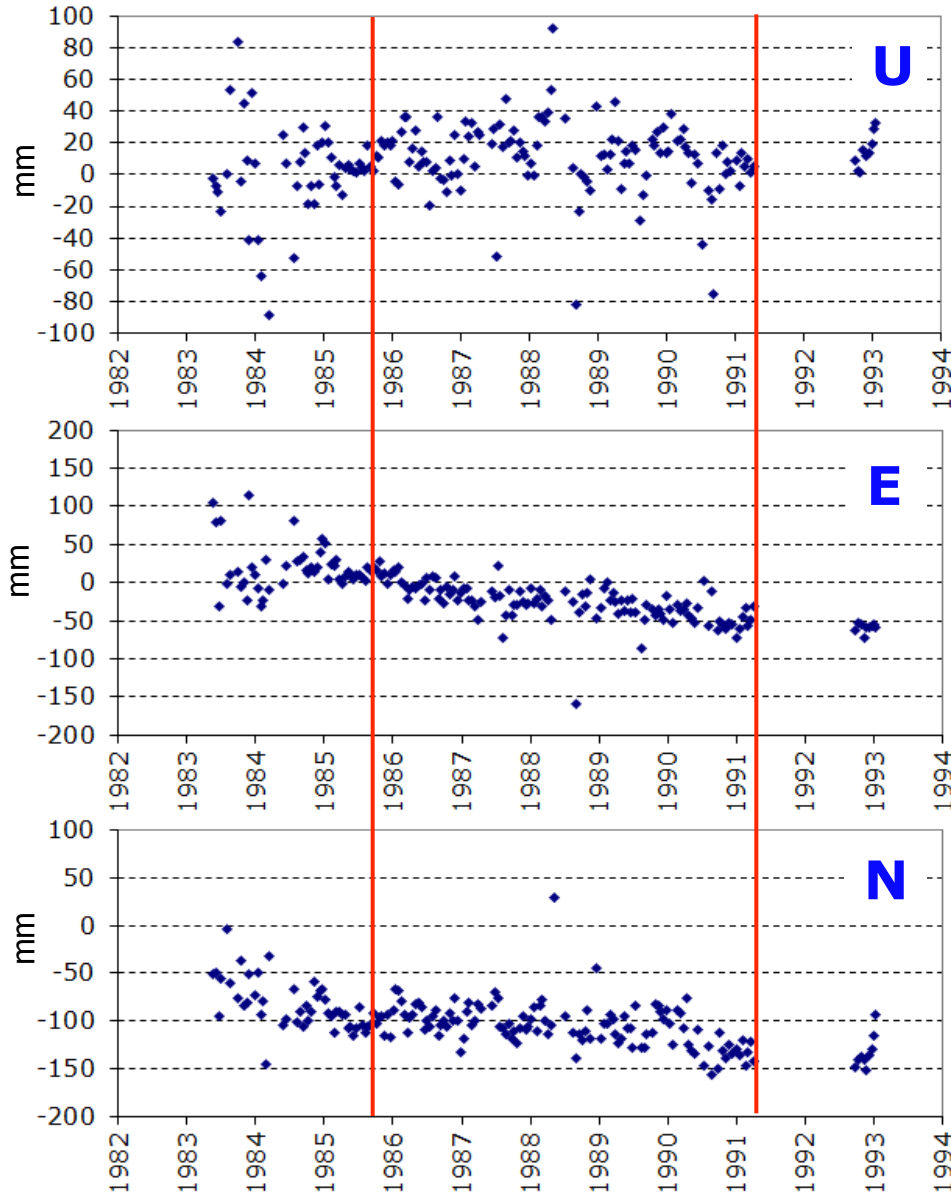
+ 1988

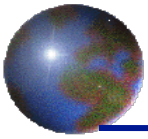
We see also a discontinuity for **1864** at 1997



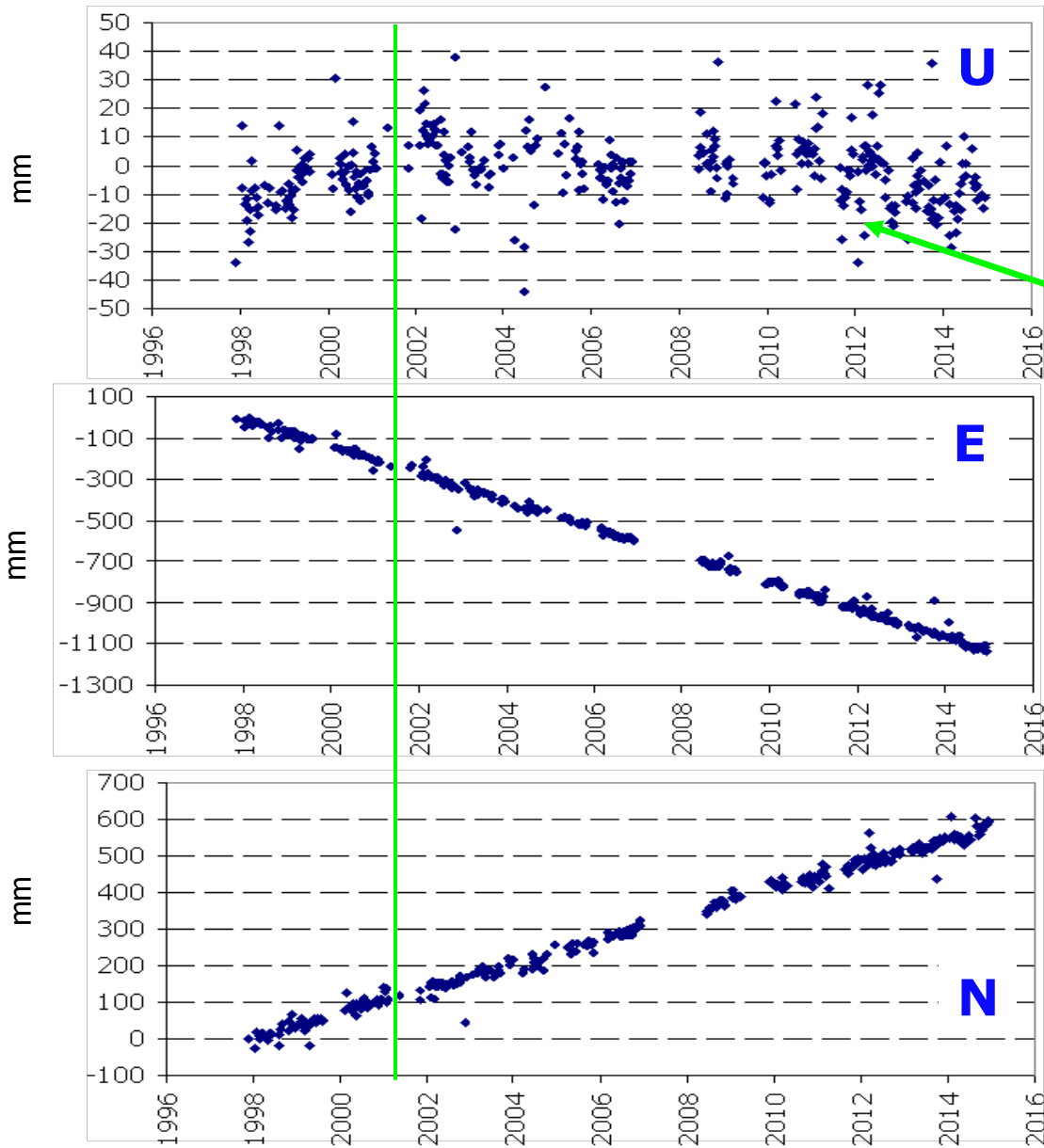
7122 Mazatlan

The scatter is large and the discontinuities are not so evident

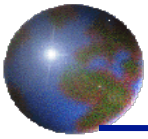




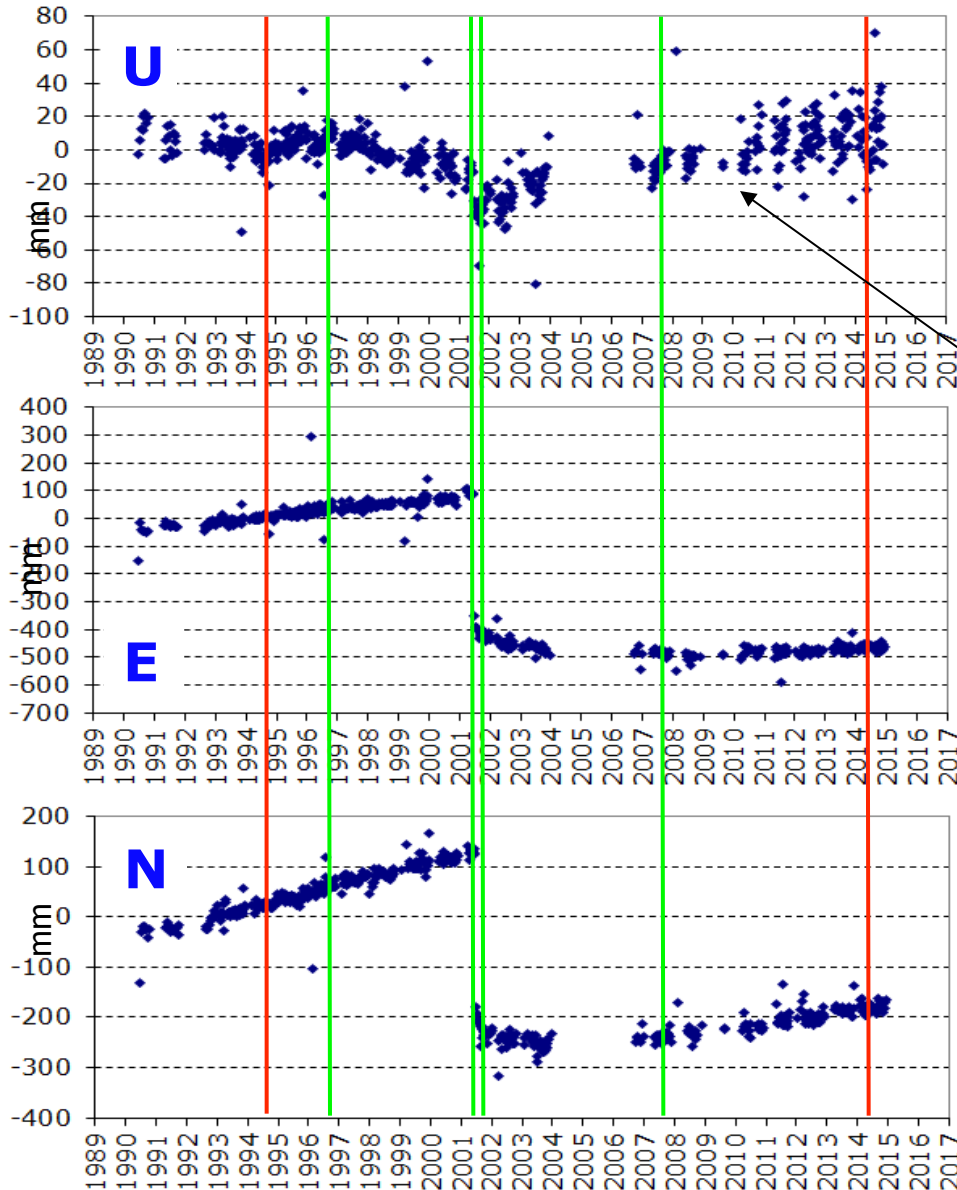
7124 Tahiti, French Polynesia



A discontinuity in 2012?



7403 Arequipa, Peru

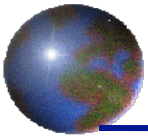


- Discontinuities 1994:161 and 2014:093 are not obvious
- 1996 and 2007 Earthquakes are not considered in PSD model file

Chile Earthquake **2010:058?**

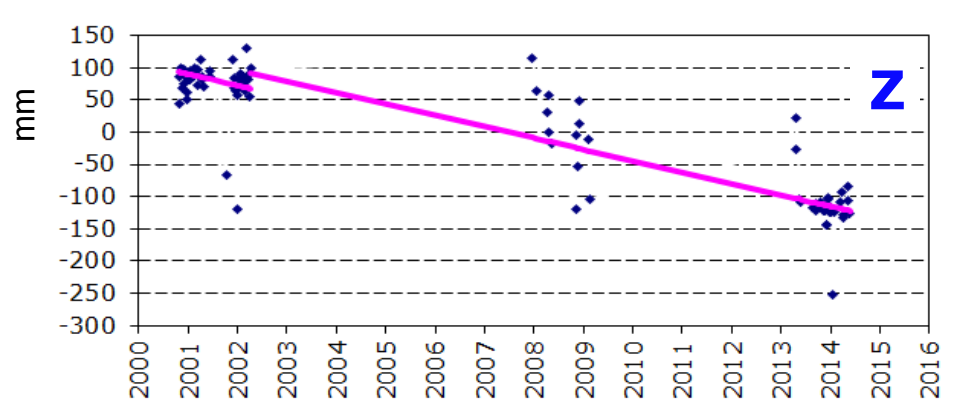
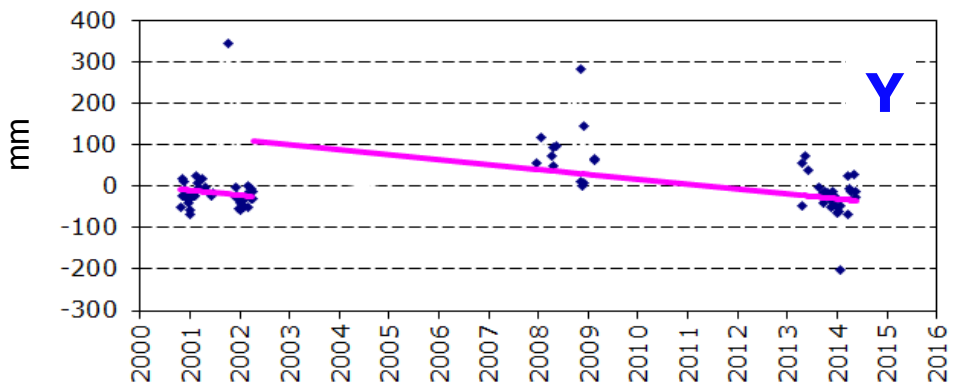
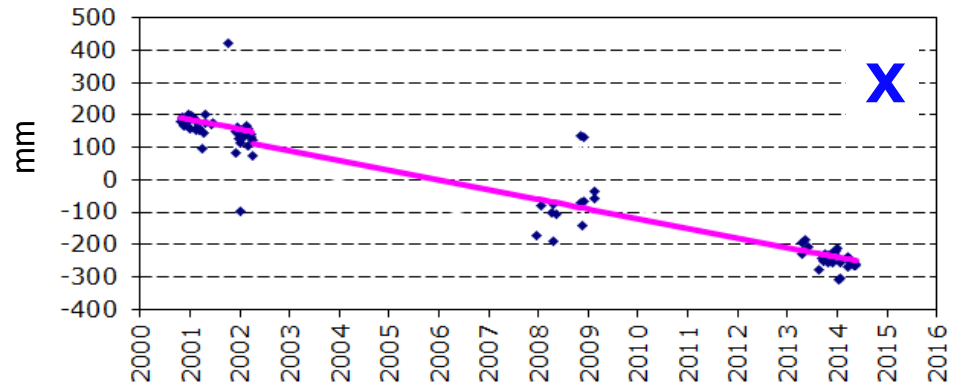
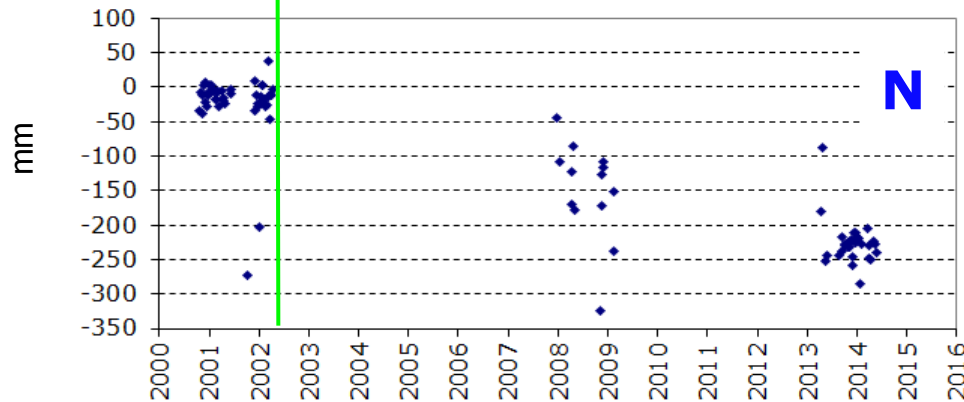
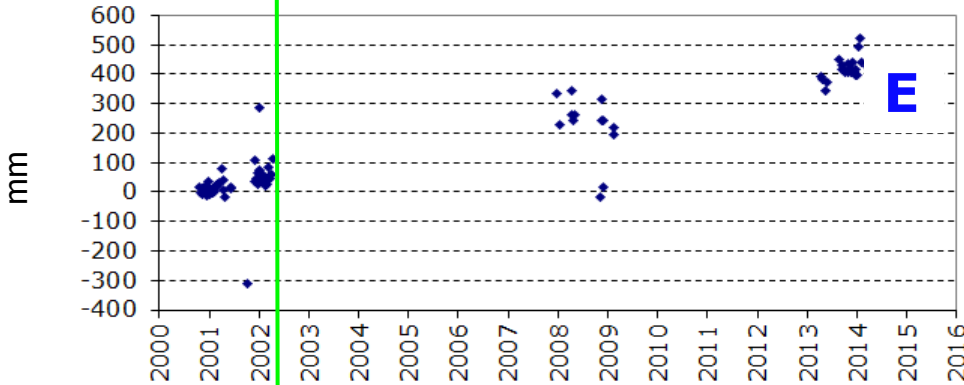
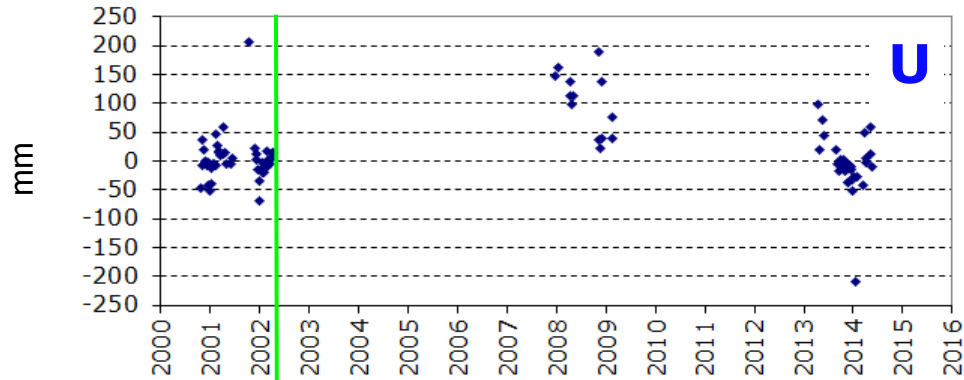
Registered Earthquake with $M > 7$

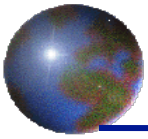
12 November 1996	7.7
23 June 2001	8.4
15 August 2007	8.0
25 September 2013	7.0



7820 Kunming, China

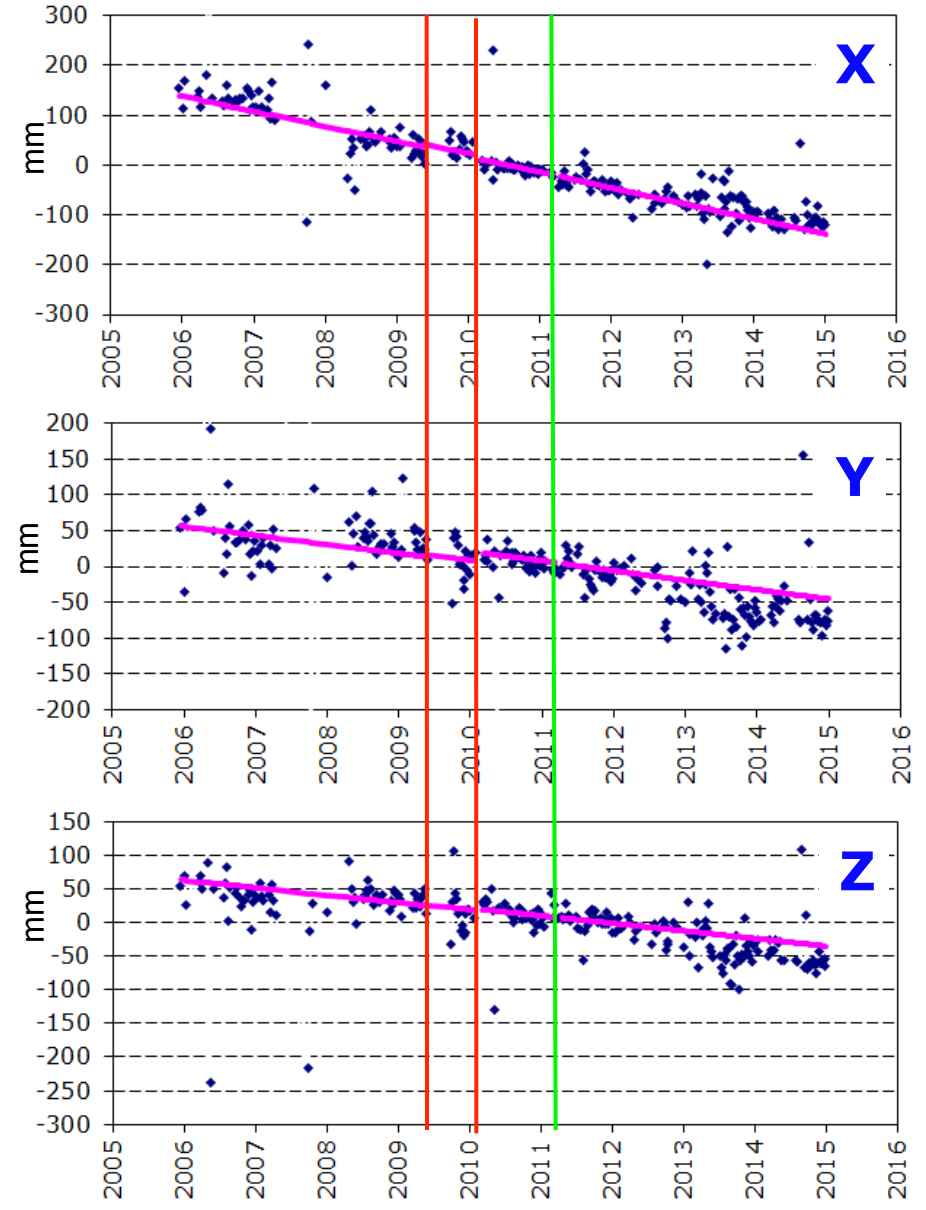
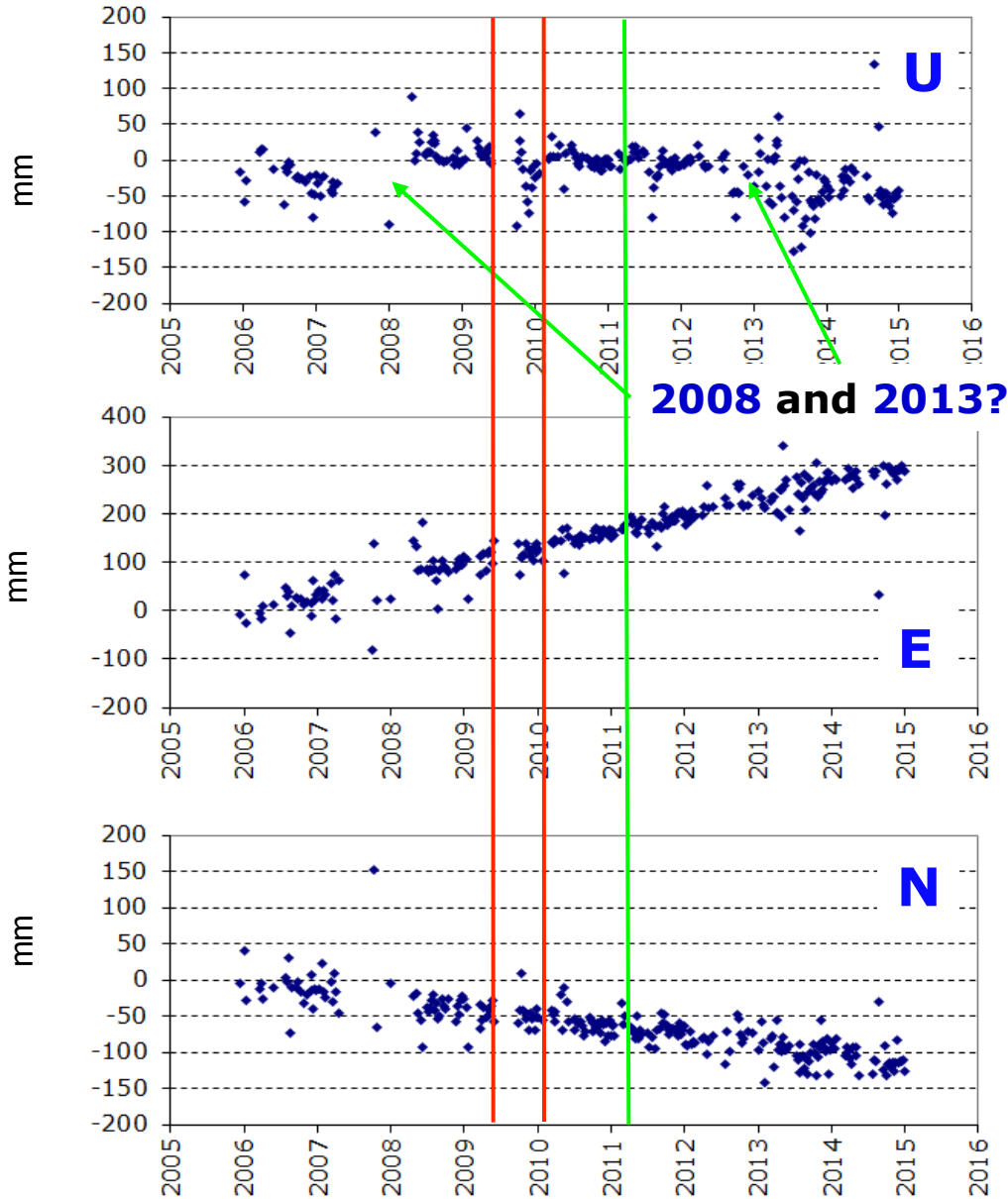
Noisy station with large gaps

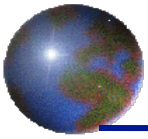




7821 Shanghai, China

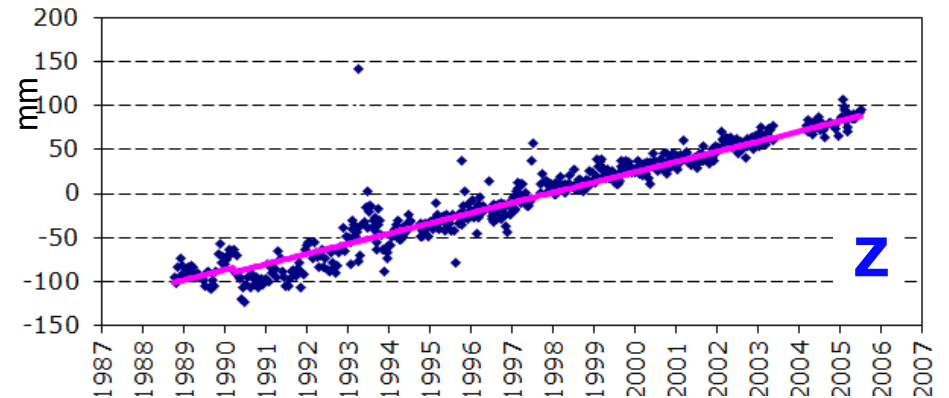
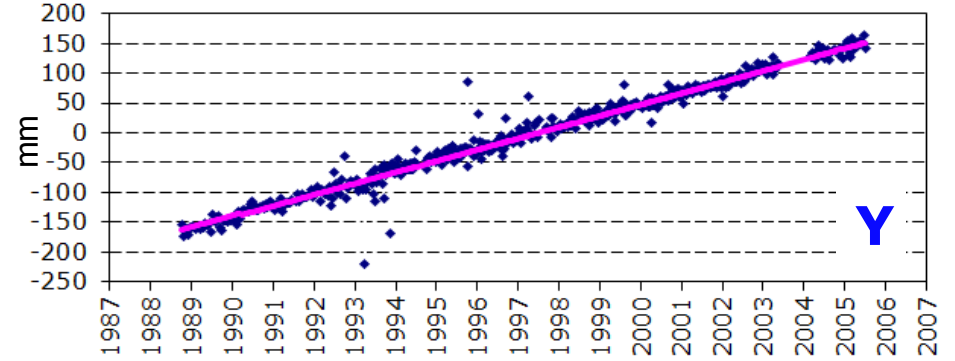
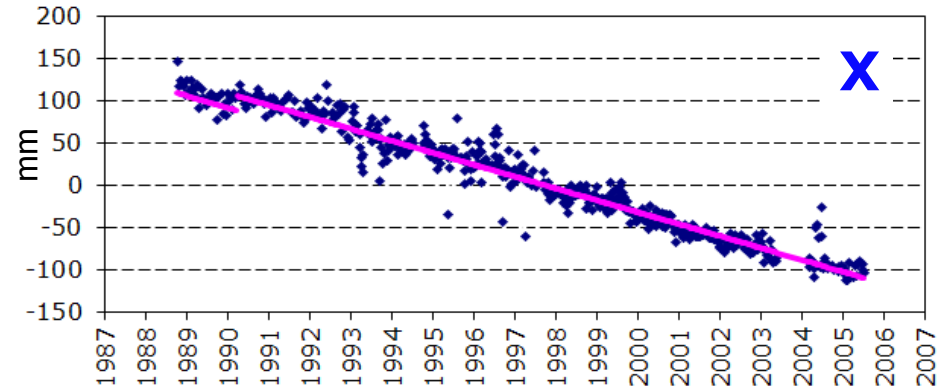
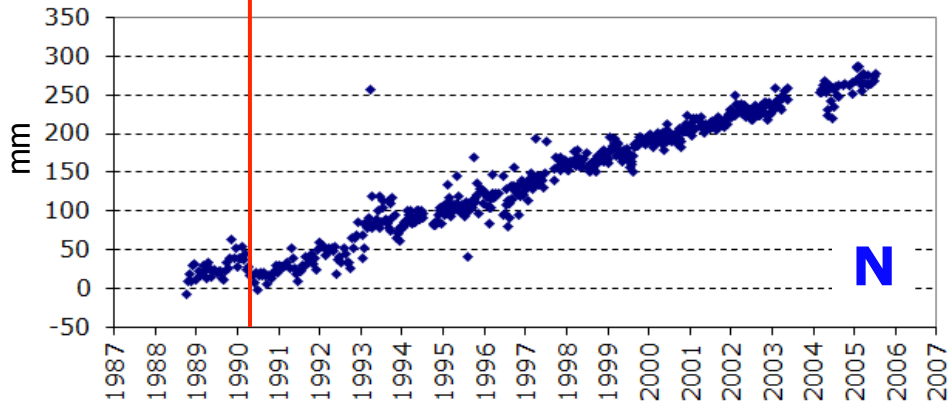
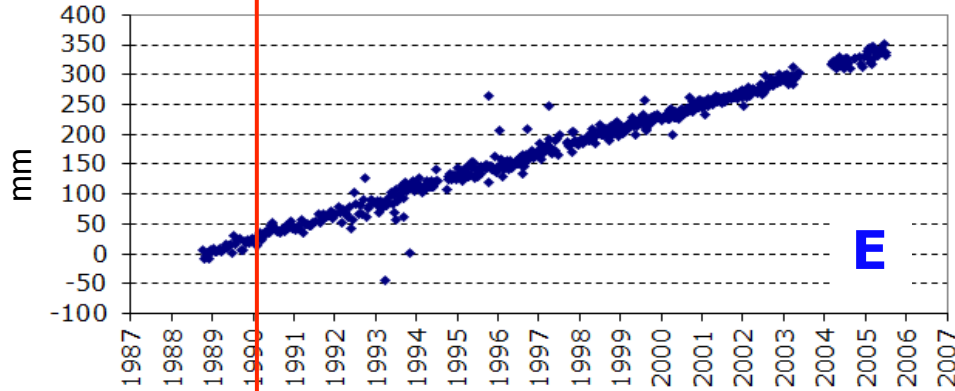
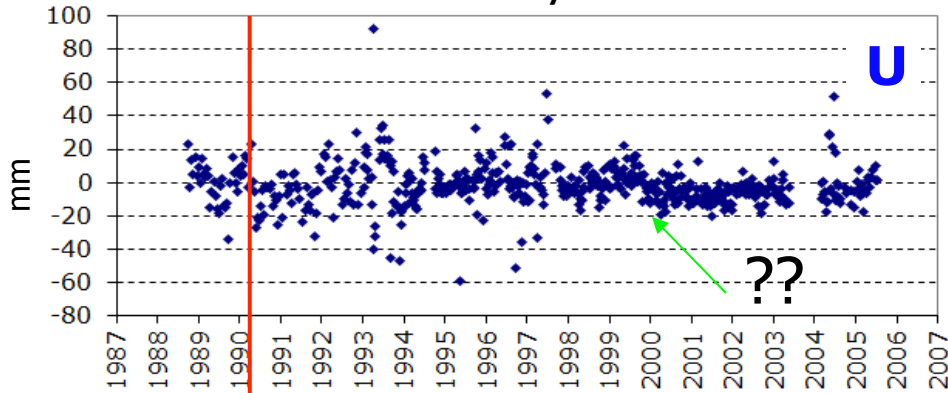
Discontinuities 2009:135 and 2010:028 are not obvious

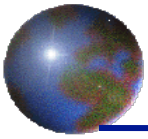




7835 Grasse, France

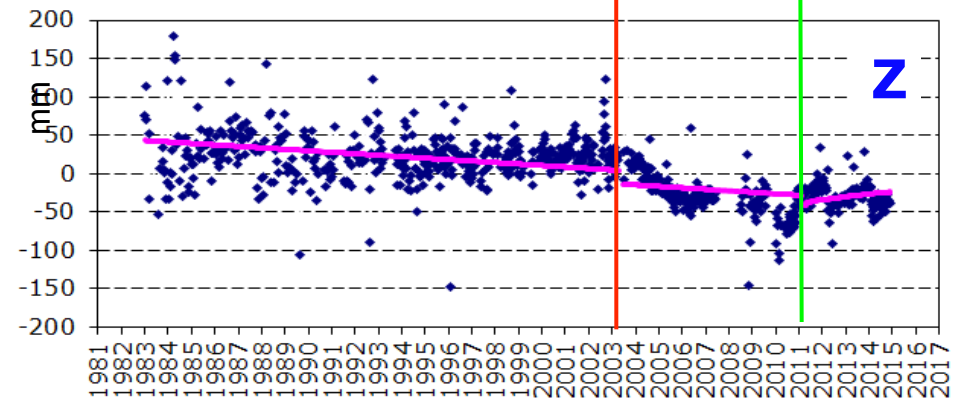
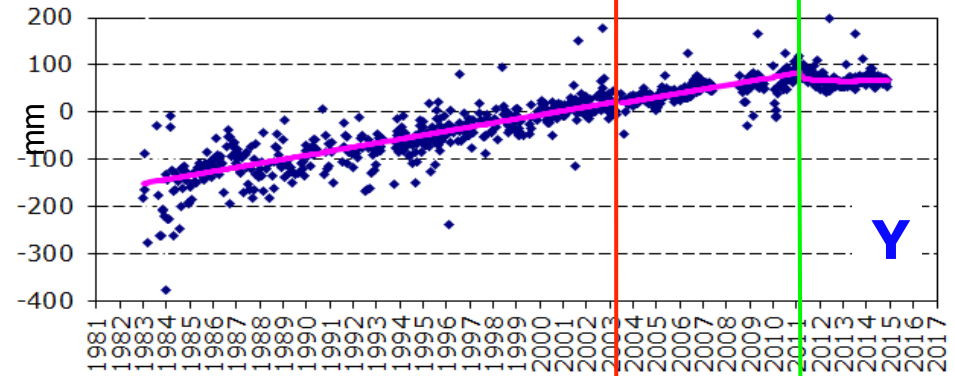
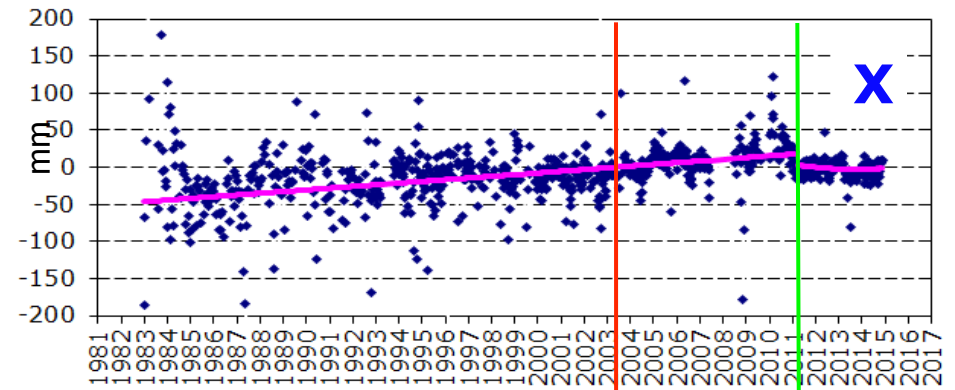
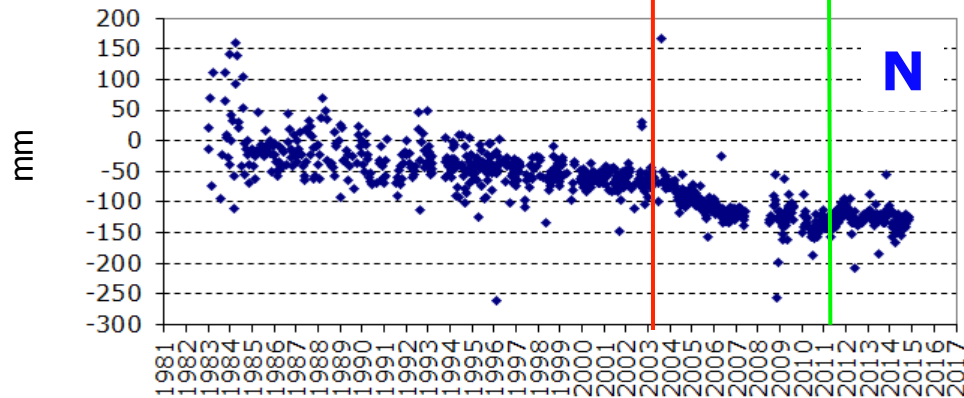
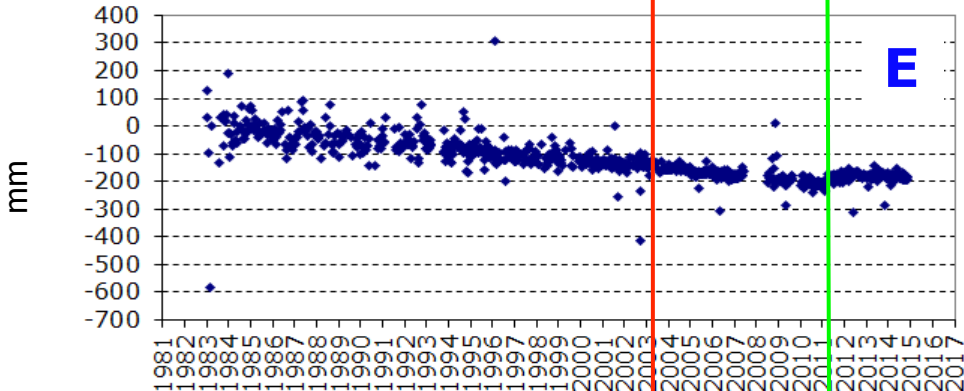
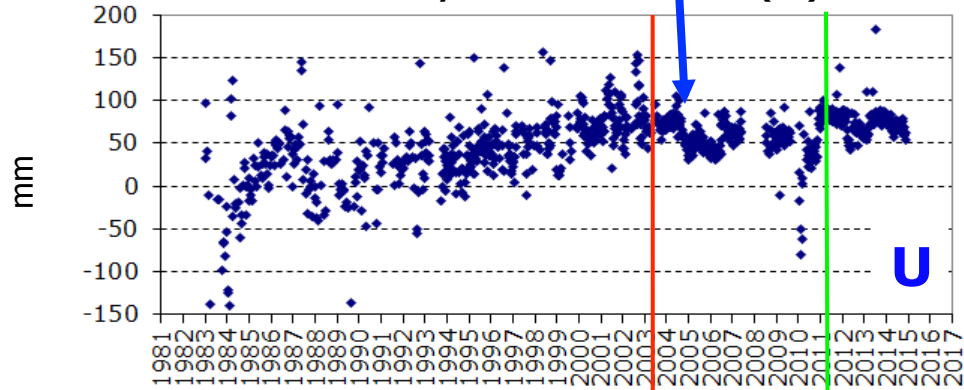
Real discontinuity in 1990?

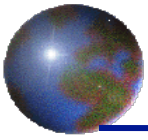




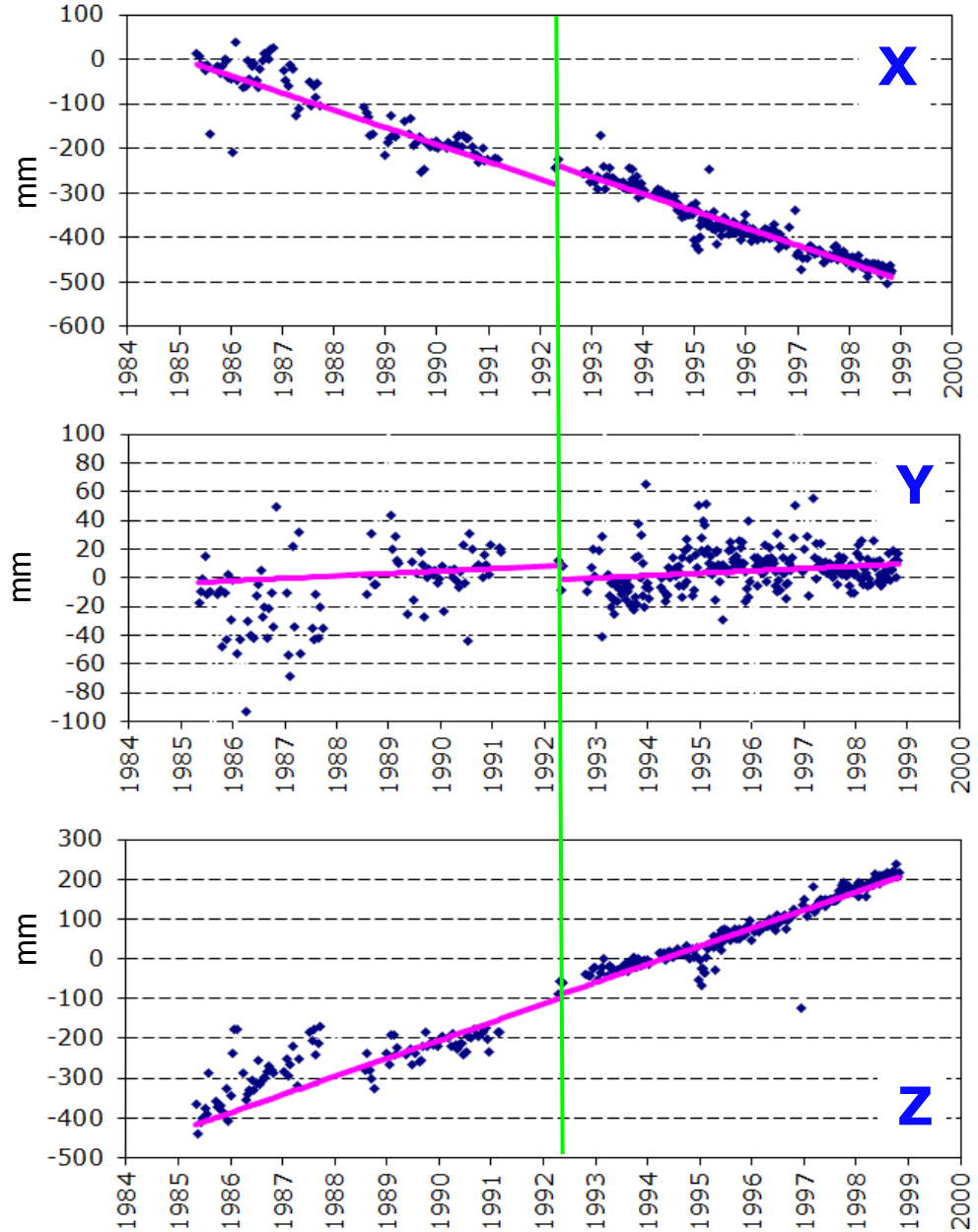
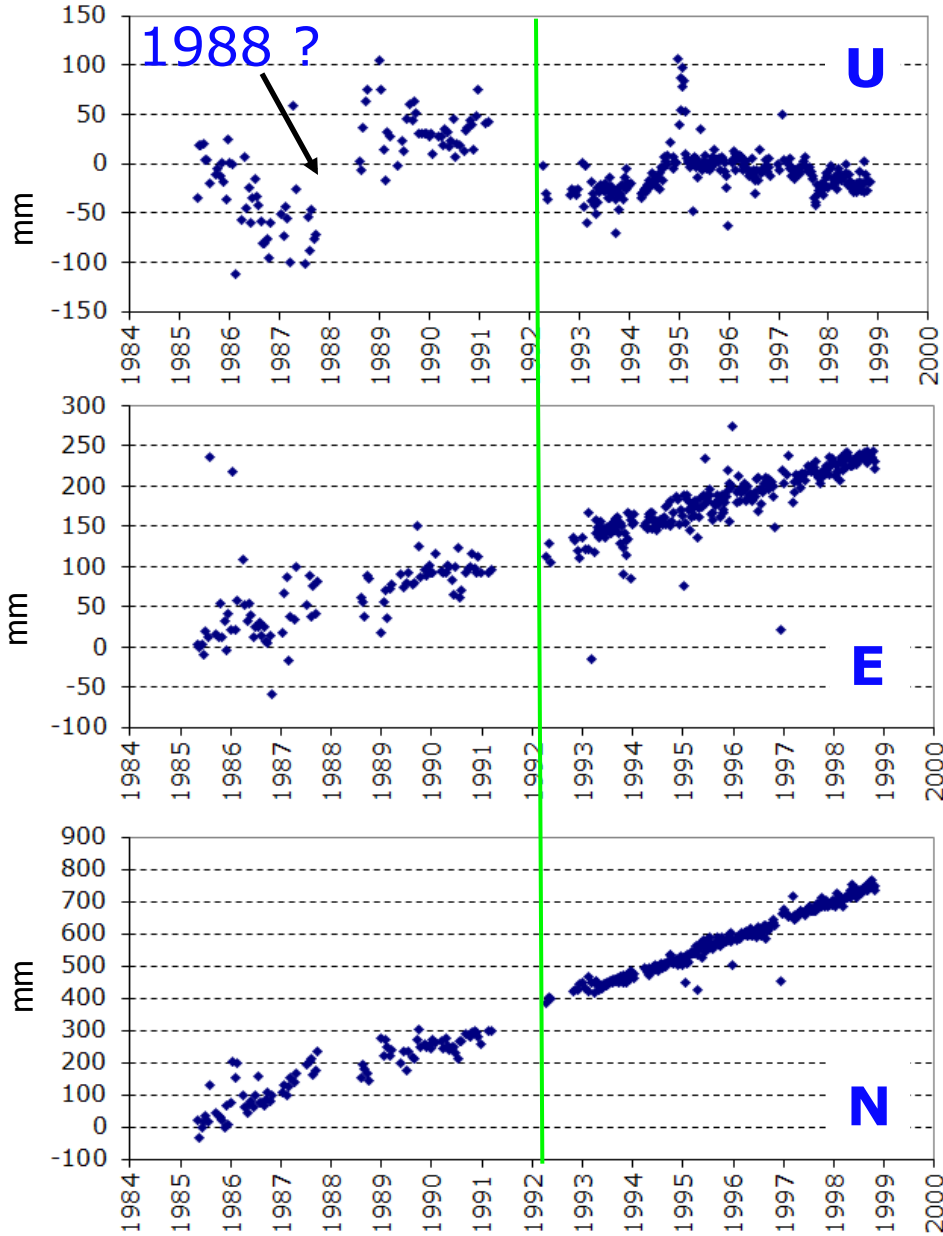
7838 Simosato, Japan

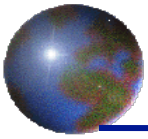
Discontinuity: 2004:249 (E) instead of 2003:100





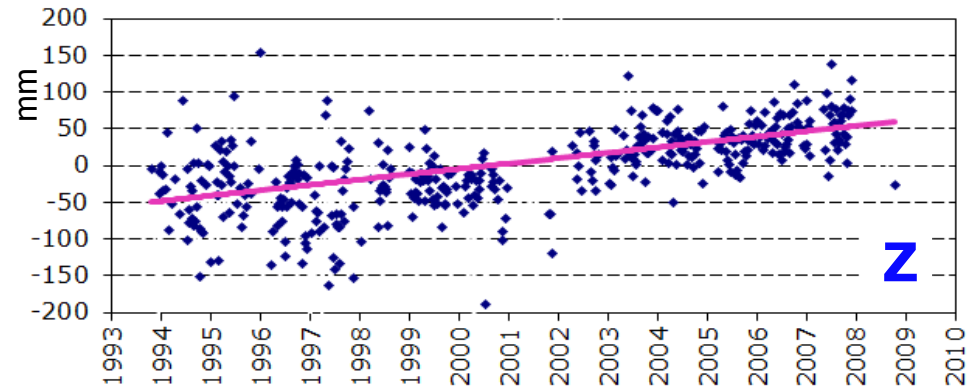
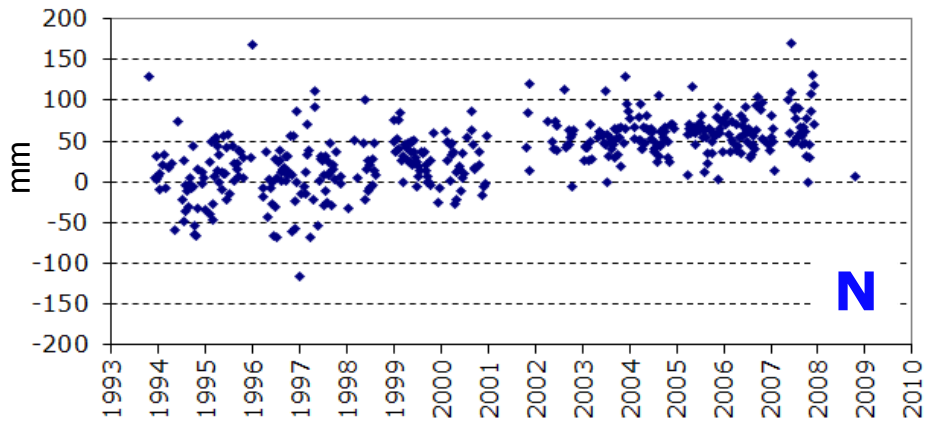
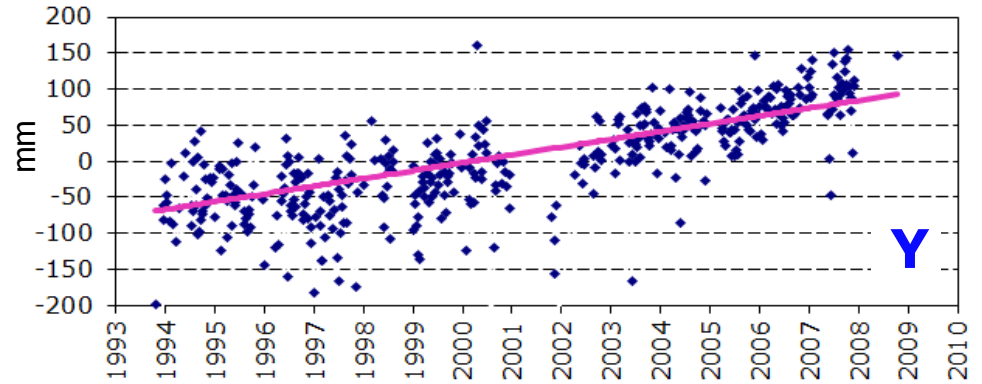
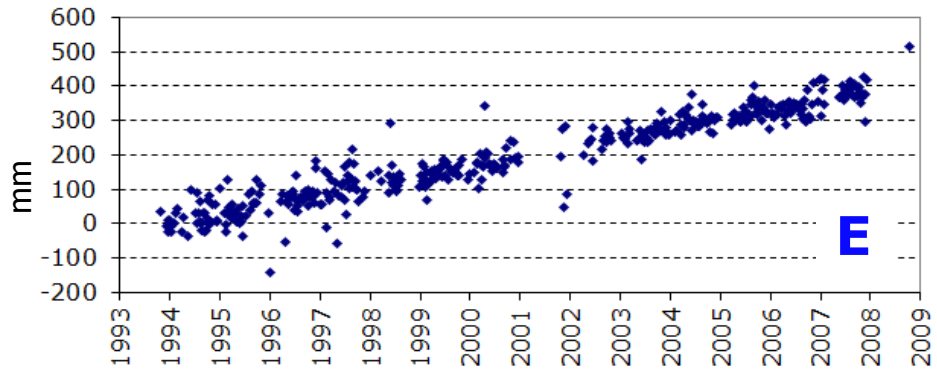
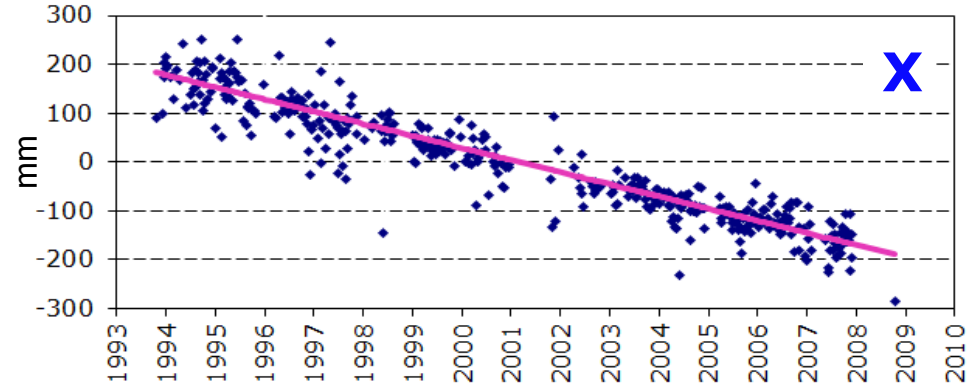
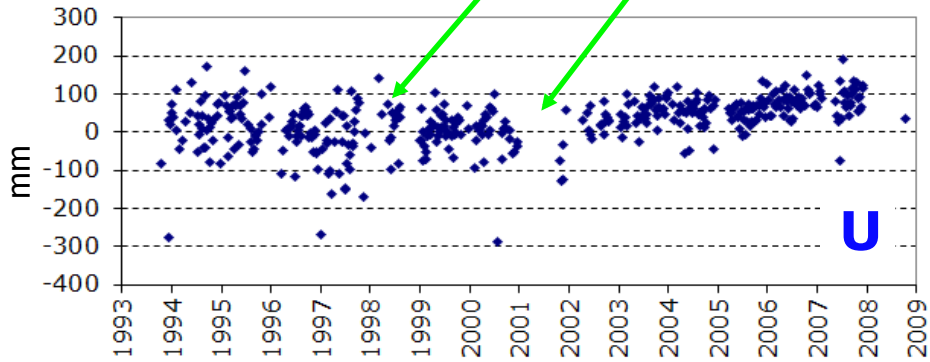
7843 Orroral, Australia

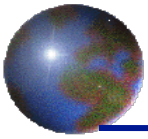




1864 Maidanak 1, Uzbekistan

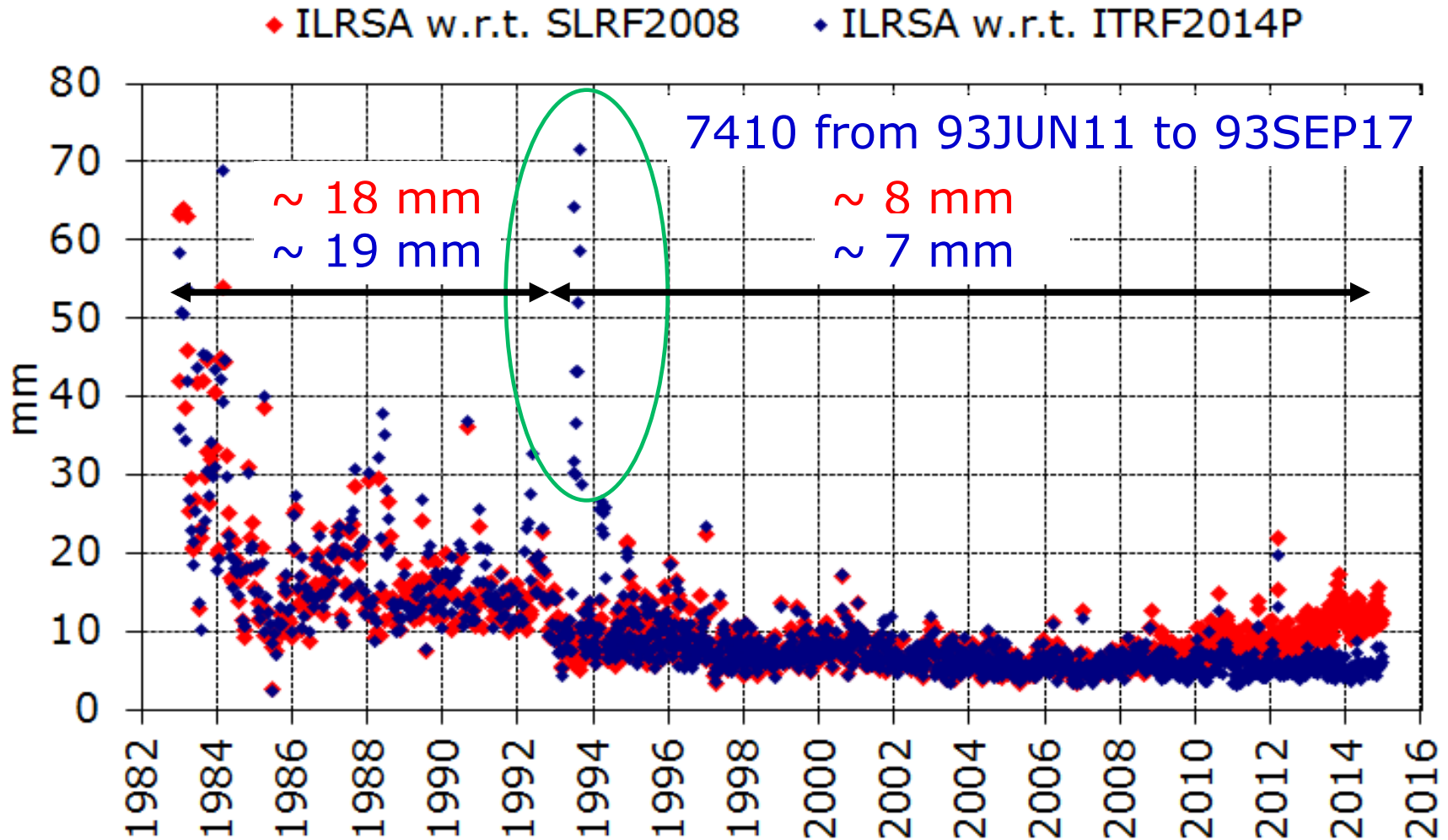
1998 or 2001?

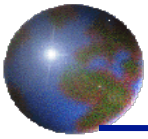




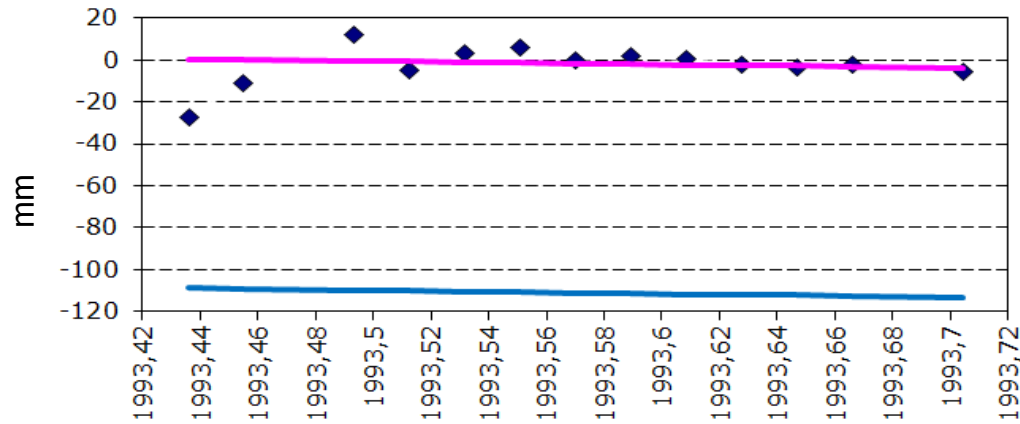
Site Coordinate Residuals

All Sites – 3D Residuals WRMS wrt ITRF

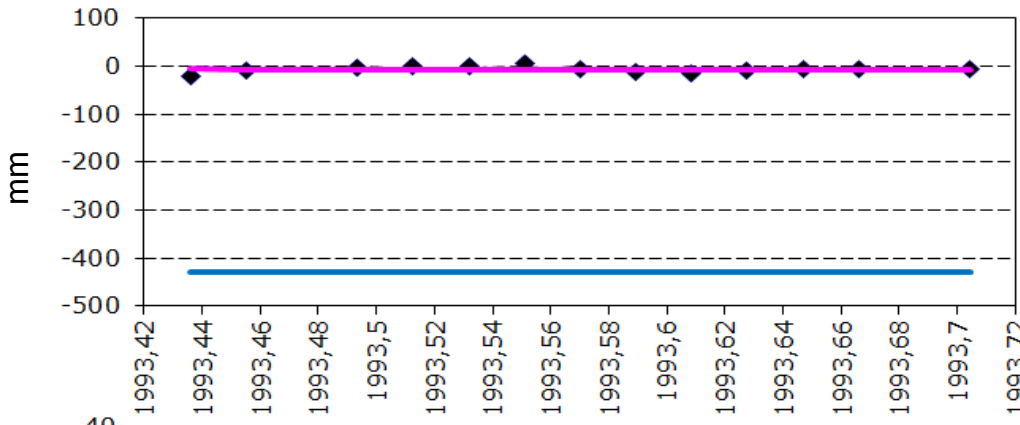




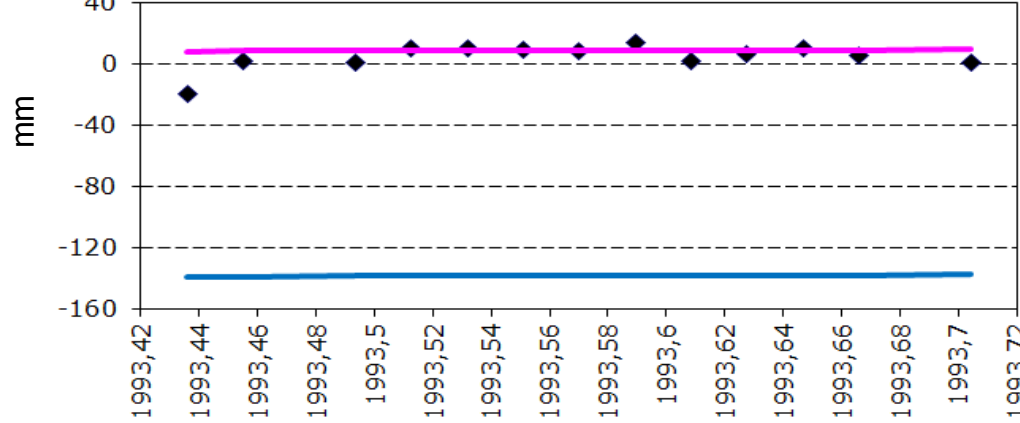
7410 Algonquin (93JUN11-93SEP17)



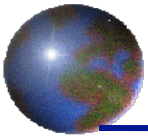
X SLRF2008
ITRF2014P



Y

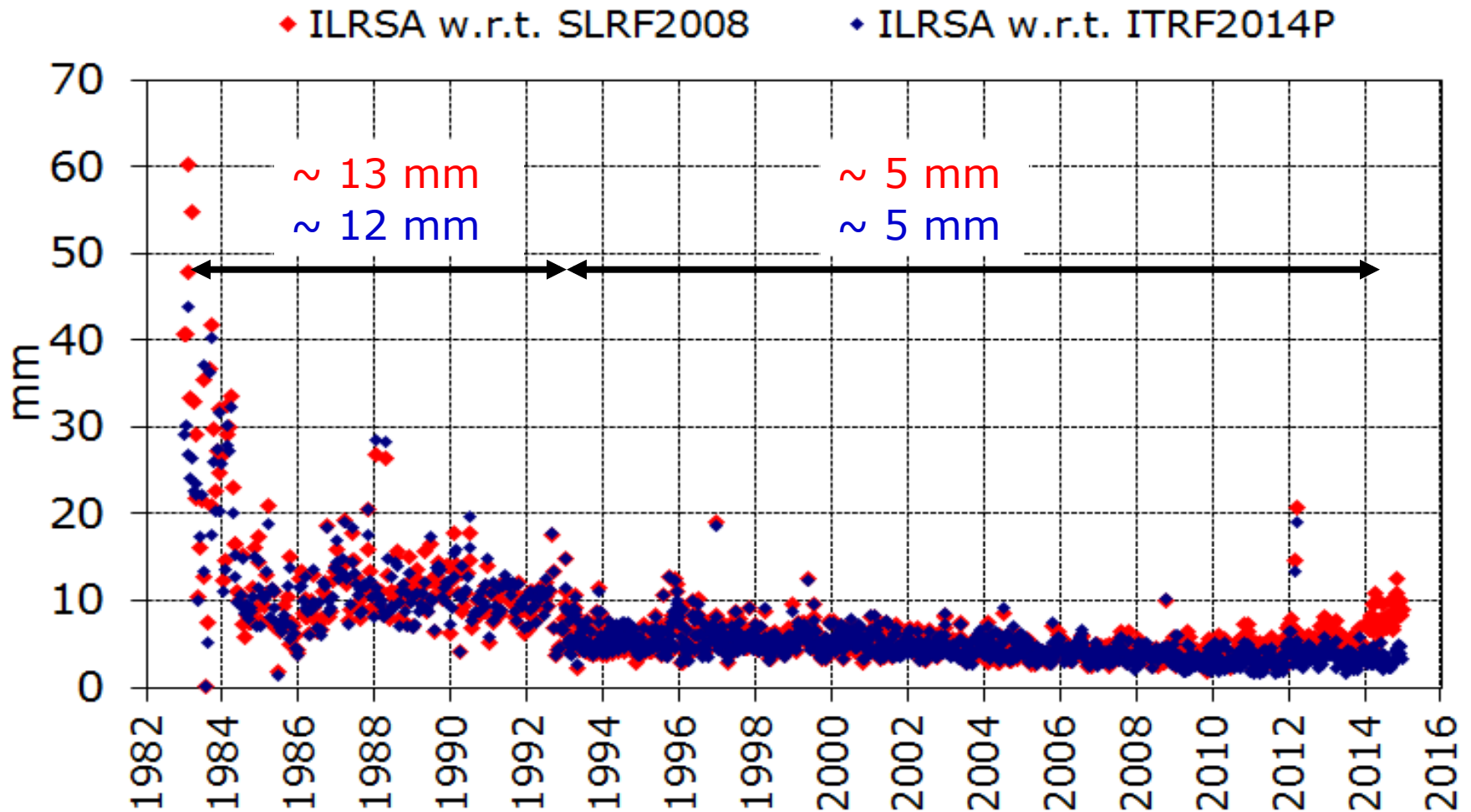


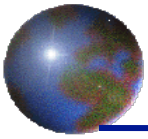
Z



Site Coordinate Residuals

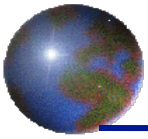
Core Sites – 3D Residuals WRMS wrt ITRF Frame





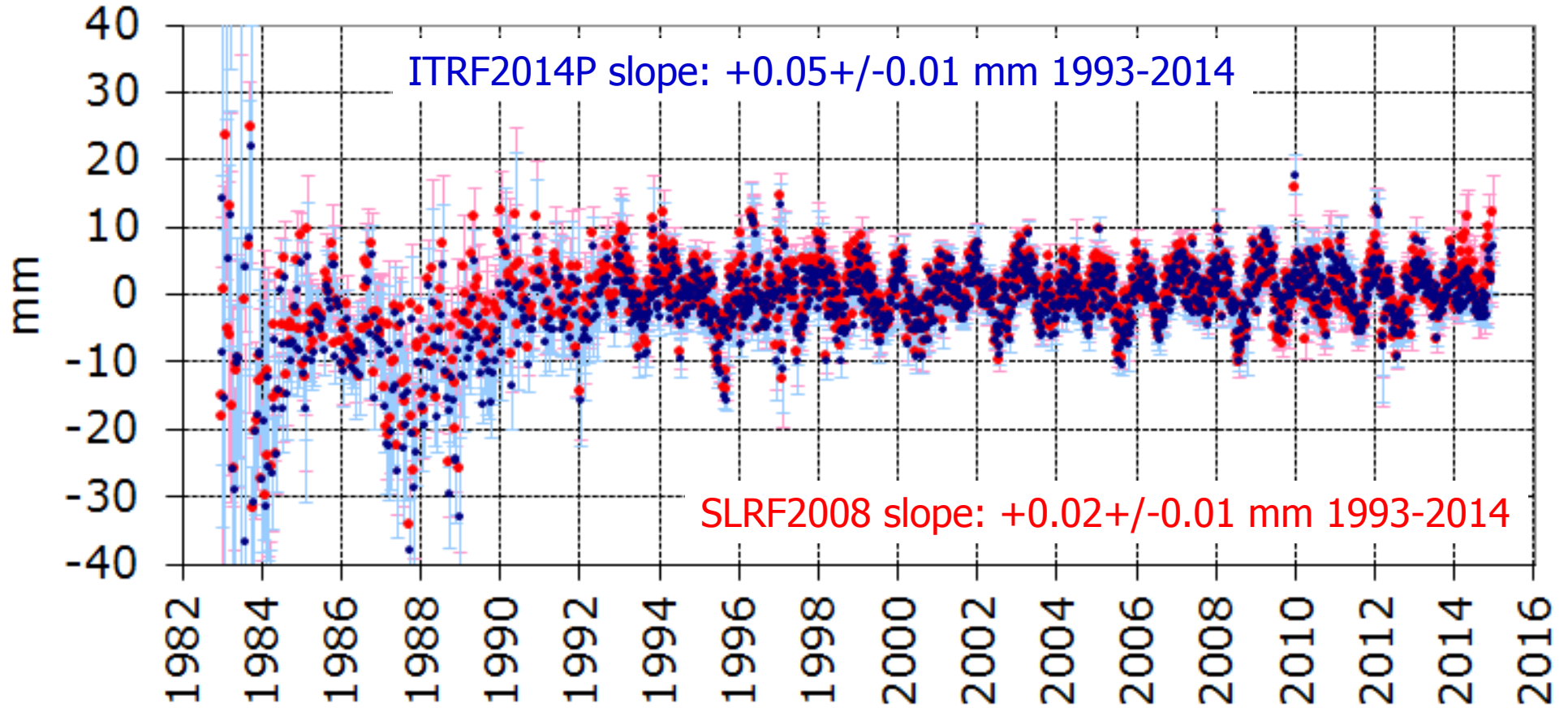
Site Coordinate Residuals - Statistics

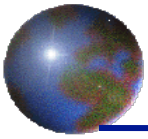
	vs SLRF2008		vs ITRF2014P	
	Mean WRMS [mm]	STD WRMS [mm]	Mean WRMS [mm]	STD WRMS [mm]
All Sites	9.7	6.2	9.0	6.5
Core Sites	6.5	4.9	6.0	4.3



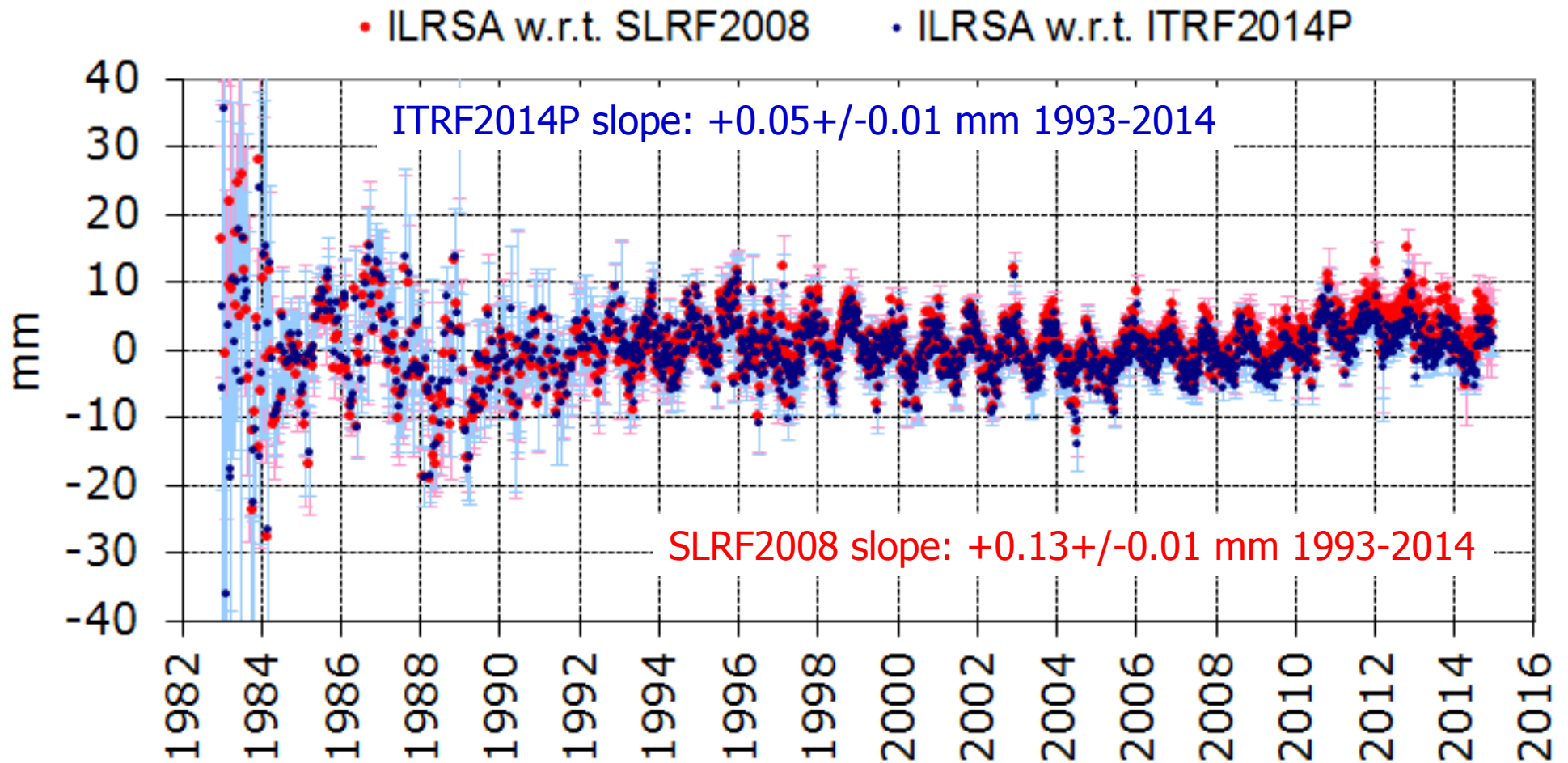
Helmert Translations: Tx

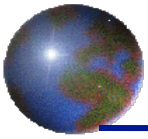
• ILRSA w.r.t. SLRF2008 • ILRSA w.r.t. ITRF2014P





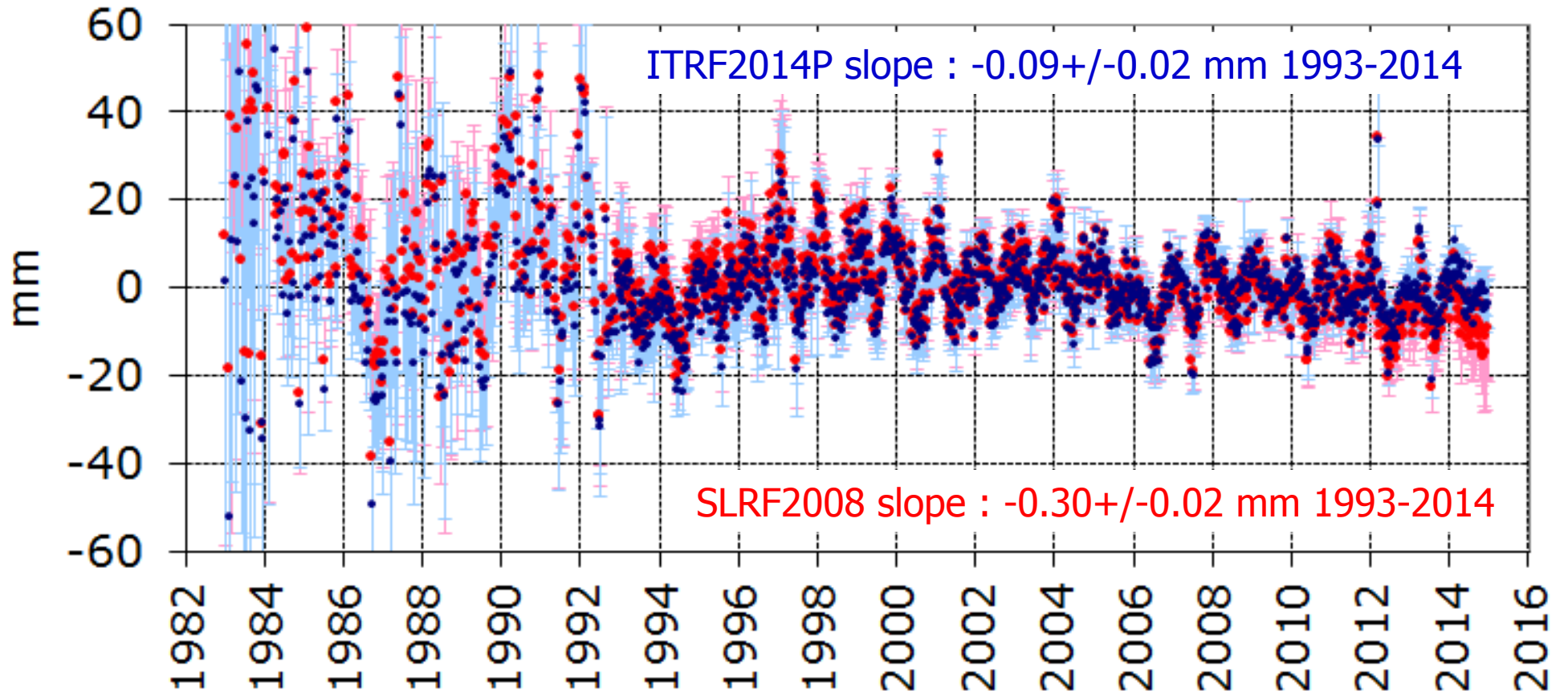
Helmert Translations: Ty

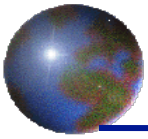




Helmert Translations: Tz

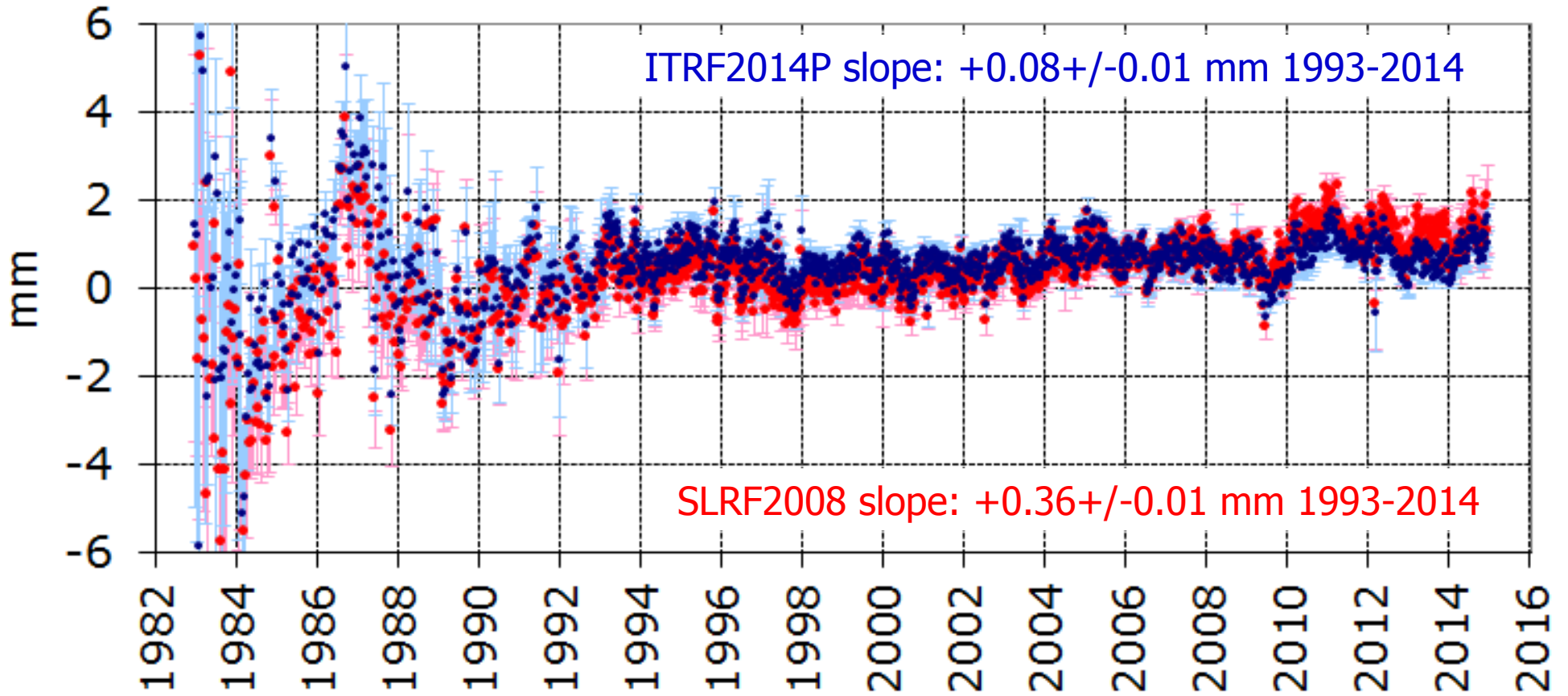
• ILRSA w.r.t. SLRF2008 • ILRSA w.r.t. ITRF2014P

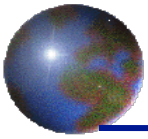




Helmert Scale

• ILRSA w.r.t. SLRF2008 • ILRSA w.r.t. ITRF2014P

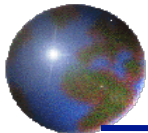




Helmert Parameters comparison

	vs SLRF2008 1983-2014			vs ITRF2014P 1983-2014		
	WRMS [mm]	Slope [mm/yr]	σ slope [mm/yr]	WRMS [mm]	Slope [mm/yr]	σ slope [mm/yr]
Tx	3.89	+0.06	0.01	3.85	+0.10	0.01
Ty	3.72	+0.11	0.01	3.39	+0.03	0.01
Tz	7.47	-0.37	0.02	6.84	-0.15	0.02
Sc	4.98	+0.34	0.01	4.98	+0.07	0.01

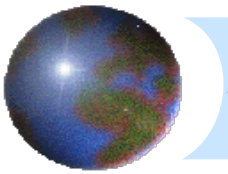
	vs SLRF2008 1993-2014			vs ITRF2014P 1993-2014		
	WRMS [mm]	Slope [mm/yr]	σ slope [mm/yr]	WRMS [mm]	Slope [mm/yr]	σ slope [mm/yr]
Tx	3.73	+0.02	0.01	3.62	+0.05	0.01
Ty	3.55	+0.13	0.01	3.26	+0.05	0.01
Tz	6.76	-0.30	0.02	6.31	-0.09	0.02
Sc	4.91	+0.36	0.01	4.85	+0.08	0.01



AWG plan for ITRF2014P evaluation

- The AWG plan is the generation of a combined ILRS solution for the period 2009-2014.

Agency	Time series	Submission date	Note
ASI	2009-2014	21 Oct 2015	
BKG	-		
DGFI	2009-2014	09 Oct 2015	
ESA	1993-2014	22 Oct 2015	
GRGS	2009-2014	23 Oct 2015	Without PSD model
GFZ	2009-2014	08 Oct 2015	
JCET	-		
NSGF	-		



ILRSA CC

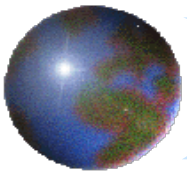
Status of the SP3 files combination



B.Pace, V. Luceri
eGEOS S.p.A., CGS – Matera

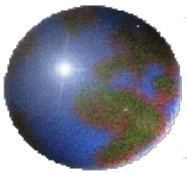


G. Bianco
Agenzia Spaziale Italiana, CGS - Matera



Contents

- SP3 data evaluation
- Preliminary combination
- Next steps

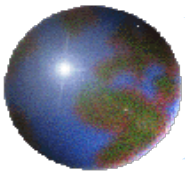


SP3 data evaluation

- L51/L52/L53/L54 SP3 files from 150620 to 150926 available at CDDIS
- cross-evaluate their consistency (RAC)
- preliminary combination

Assumptions

- EF frame as in the ACs weekly solution
- UTC
- SP3c format
- 2' POS/VEL L51/L52
- 15' POS/VEL L53/L54



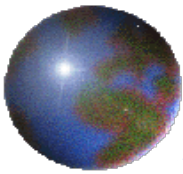
SP3 availability and assumptions adherence

AC	L51	L52	L53	L54
ASI	yes	yes	yes	yes
BKG	yes	yes	yes	yes
DGFI	yes	yes	-	-
ESA	yes	yes	yes	yes
GFZ	yes	yes	-	-
GRGS	NO	NO	NO	NO
JCET	yes	yes	yes	yes
NSGF	yes	yes	yes	yes

← Uploaded just 2 weeks ago

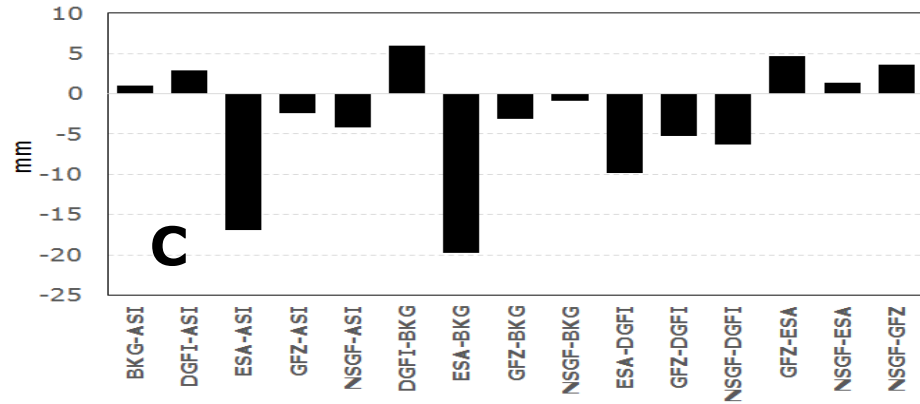
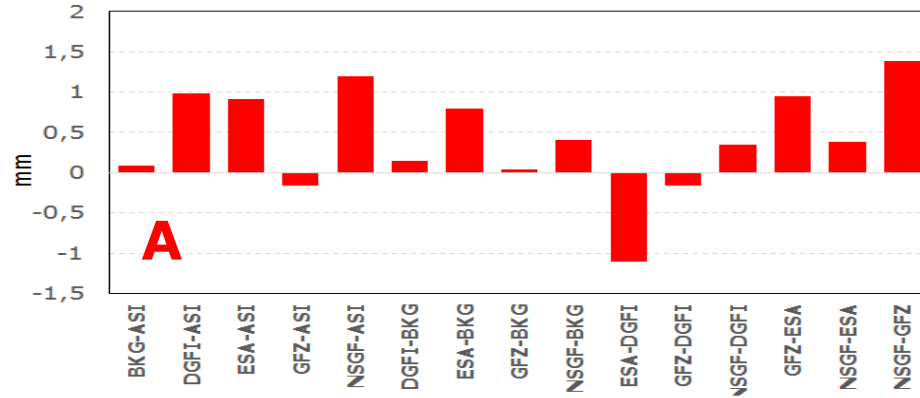
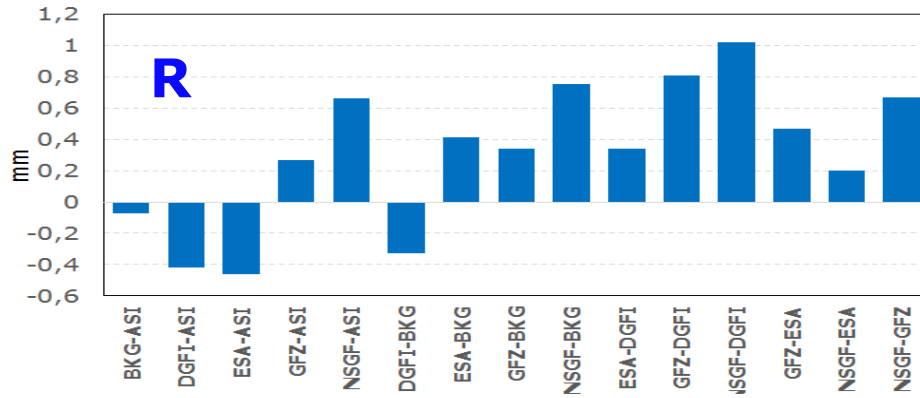
AC	Comments
DGFI	In LAGEOS1/2 sp3 files the “Number of Epochs” in the first line is 0.
BKG	In LAGEOS1/2 and ETALON1/2 sp3 files the name of Agency in the first line is CODE rather than BKG. Epoch incorrect from 150711 (second = 0.00000020)
ESA	- In LAGEOS1/2 and ETALON1/2 sp3 files the name of Agency in the first line is ESOC rather than ESA. - Format check NOK for L53/L54: the estimates are given every 5 min instead of 15 min.
NSGF	In LAGEOS1/2 and ETALON1/2 sp3 files the name of Agency in the first line is SGF rather than NSGF.

← OK

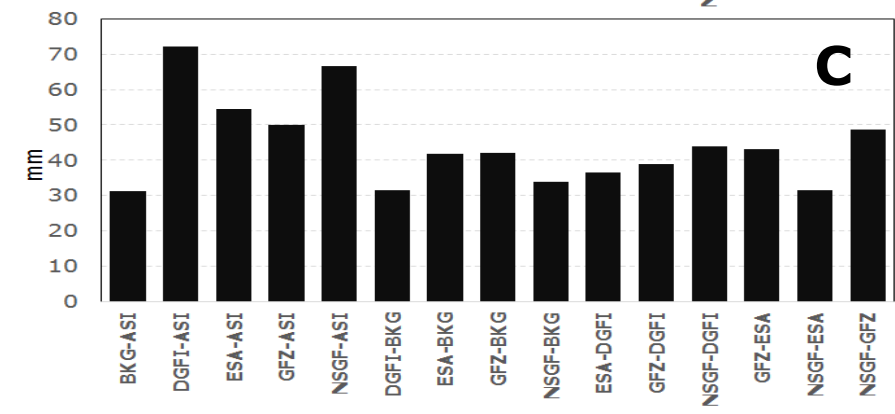
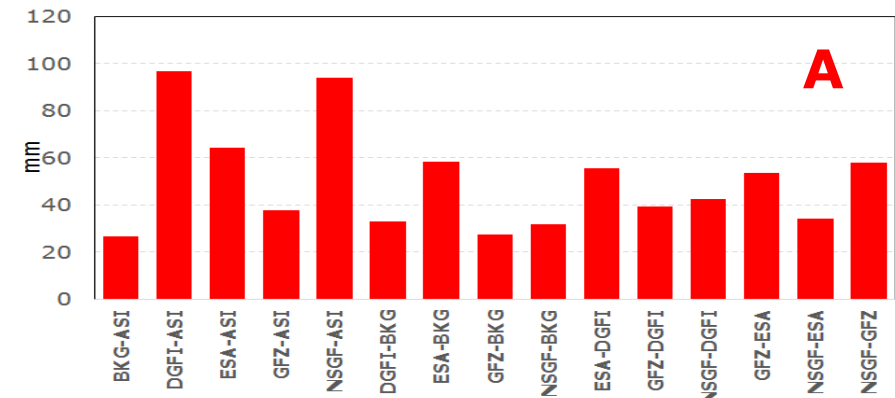
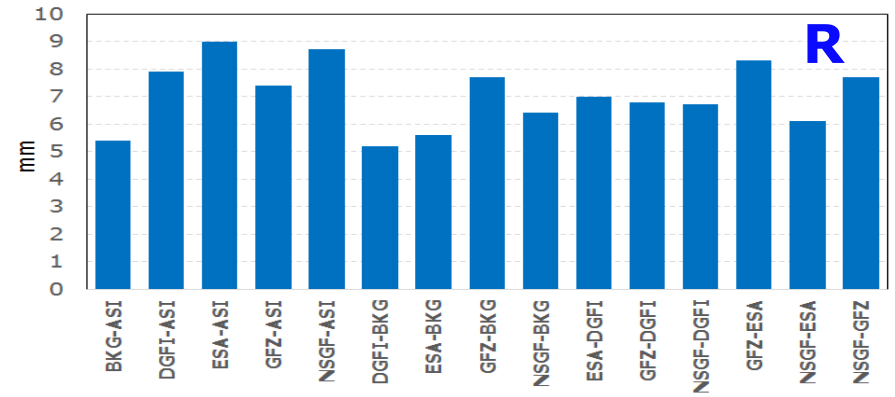


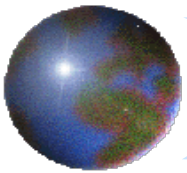
L51 – summary (150620-150926)

Mean



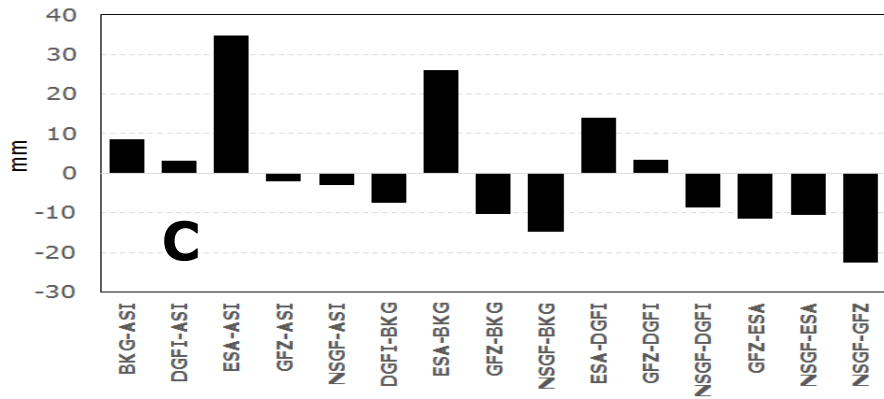
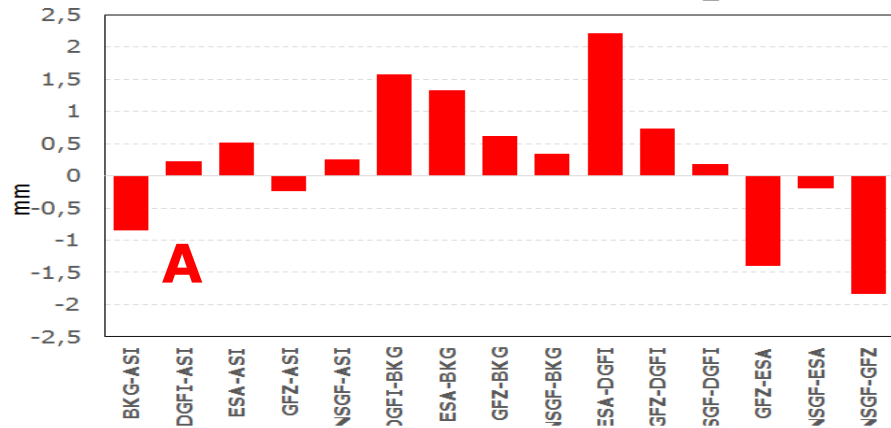
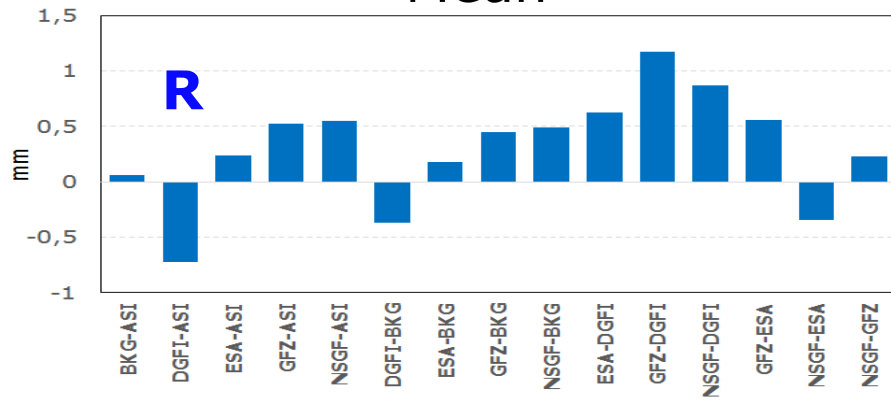
STD



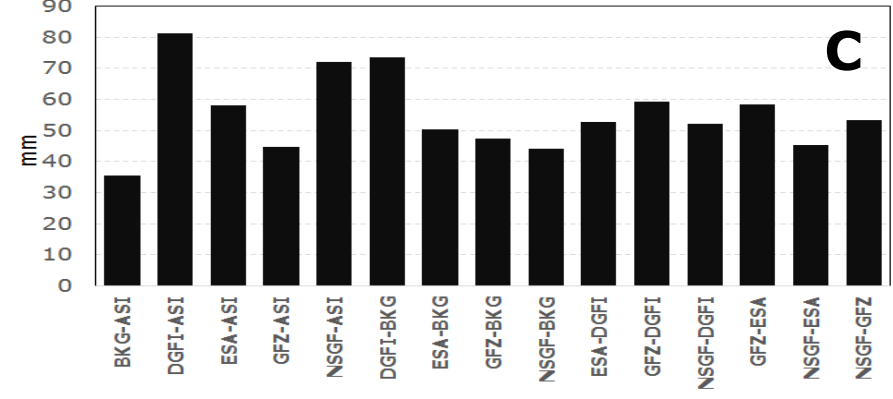
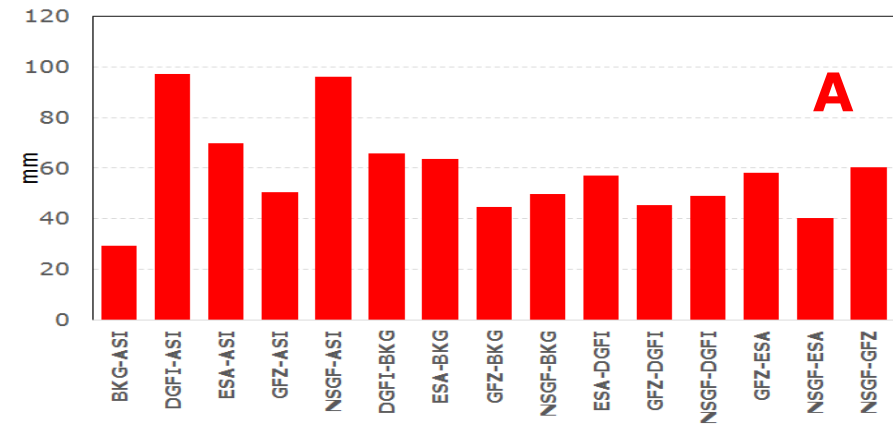
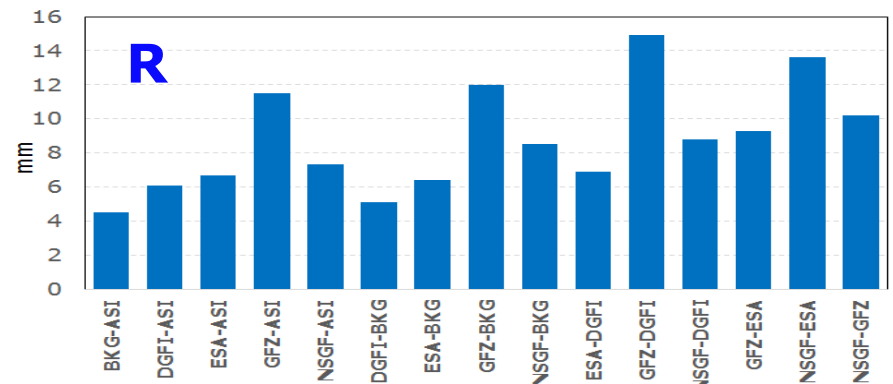


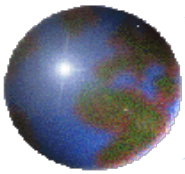
L52 – summary (150620-150926)

Mean



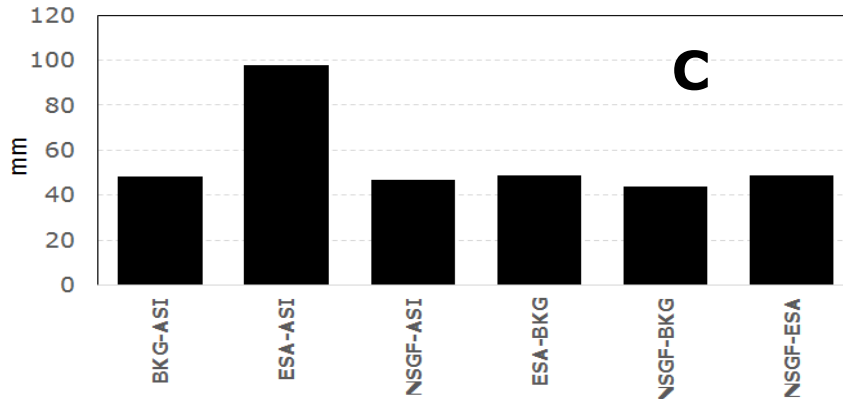
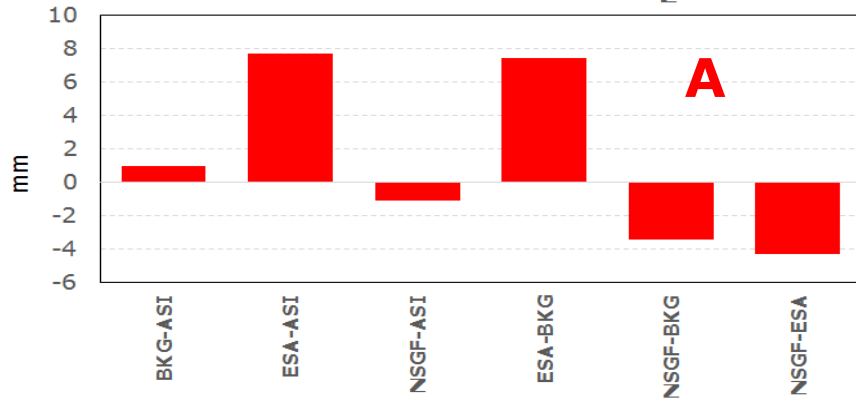
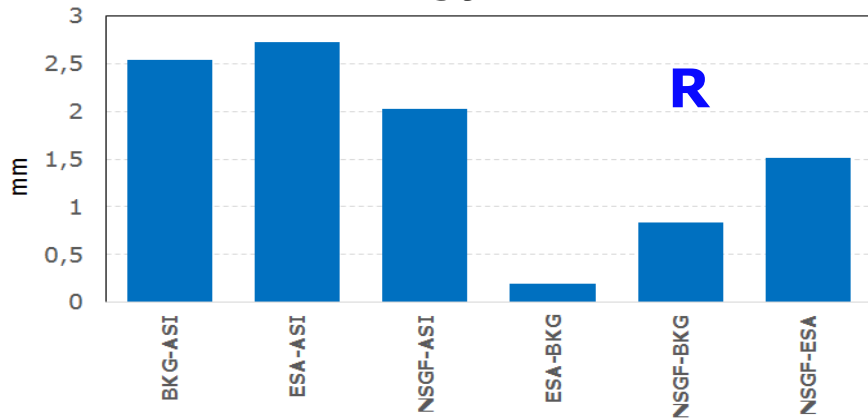
STD



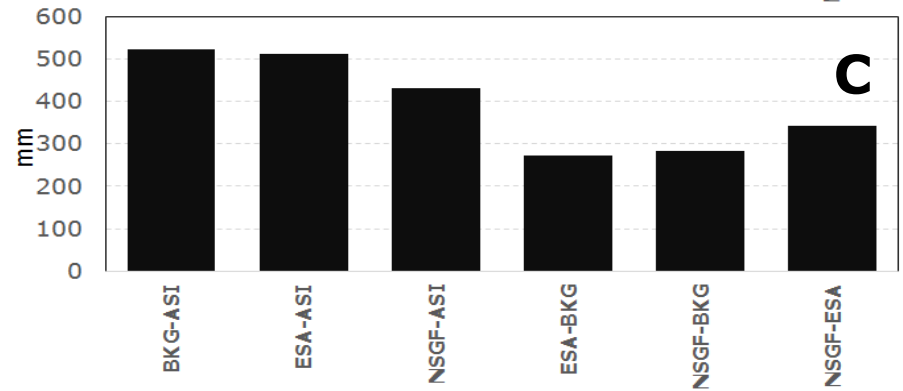
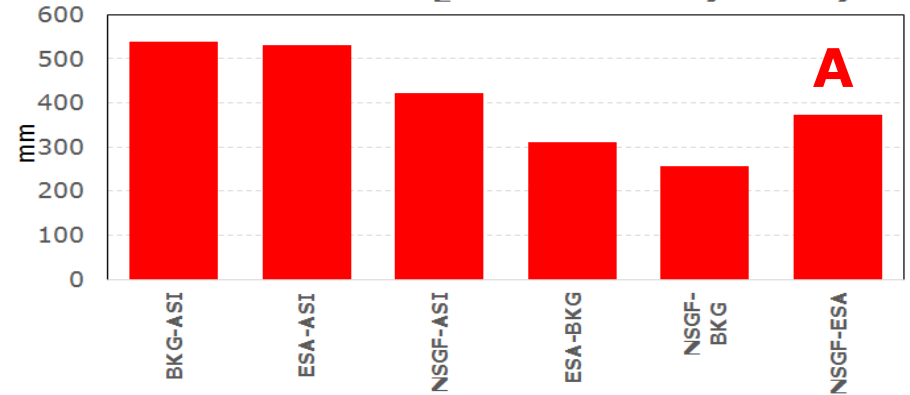
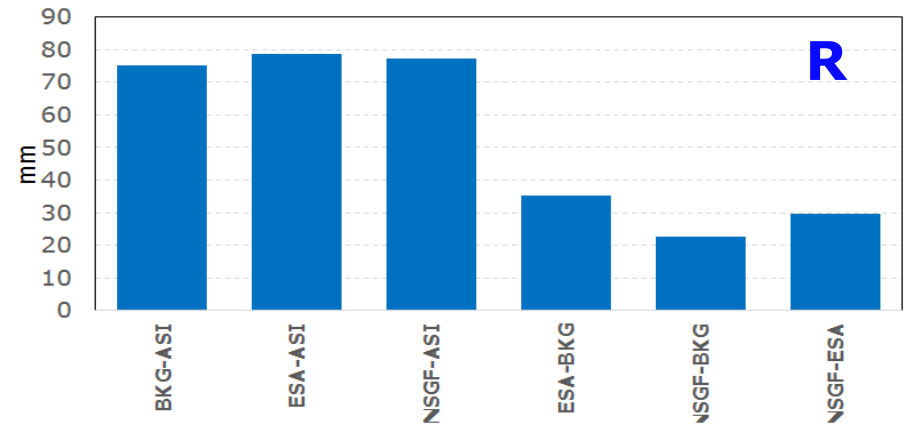


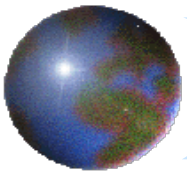
L53 – summary (150620-150926)

Mean



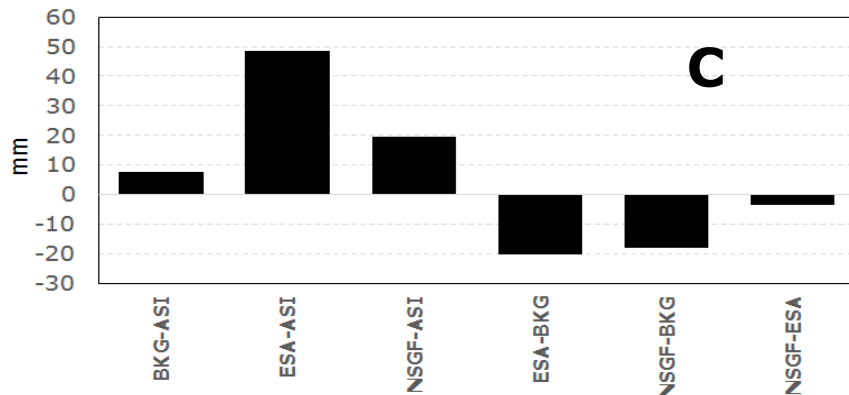
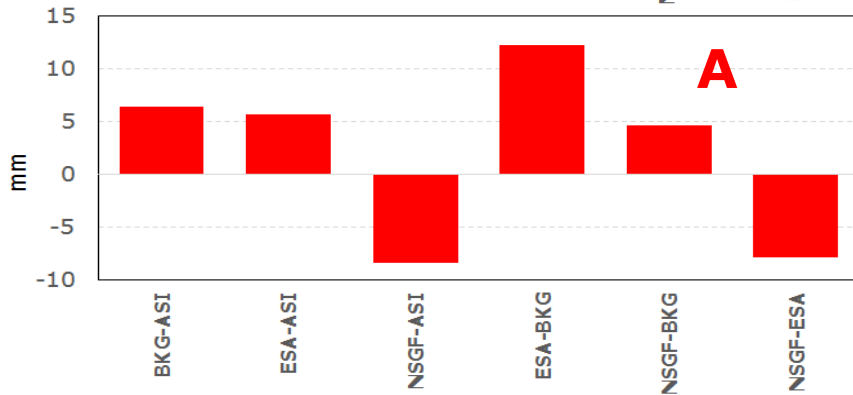
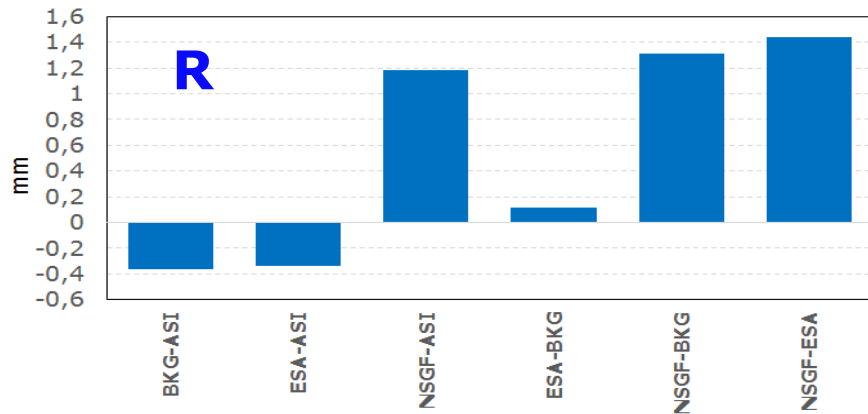
STD



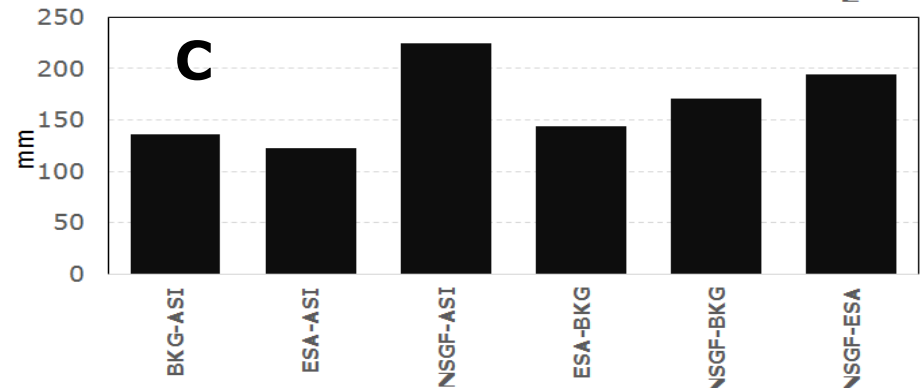
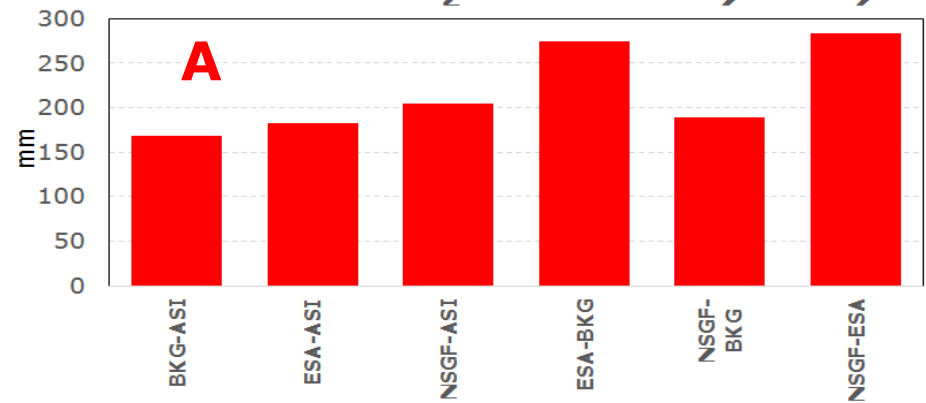
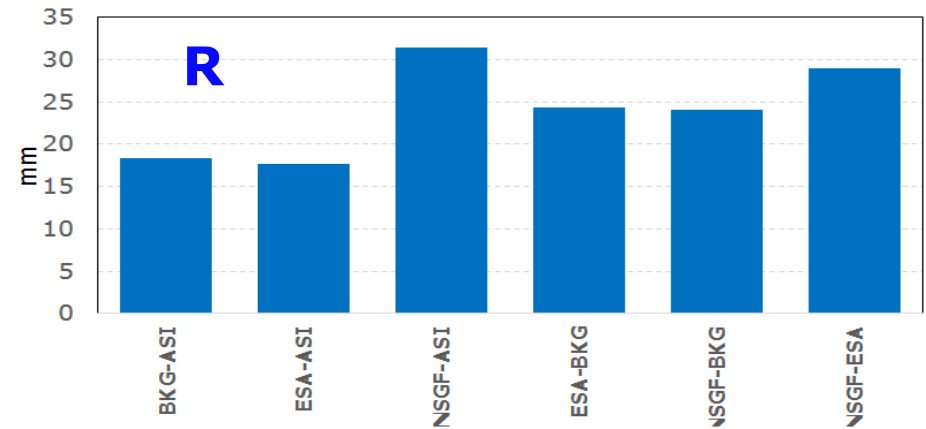


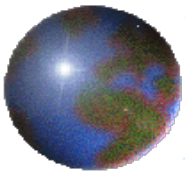
L54 – summary (150620-150926)

Mean



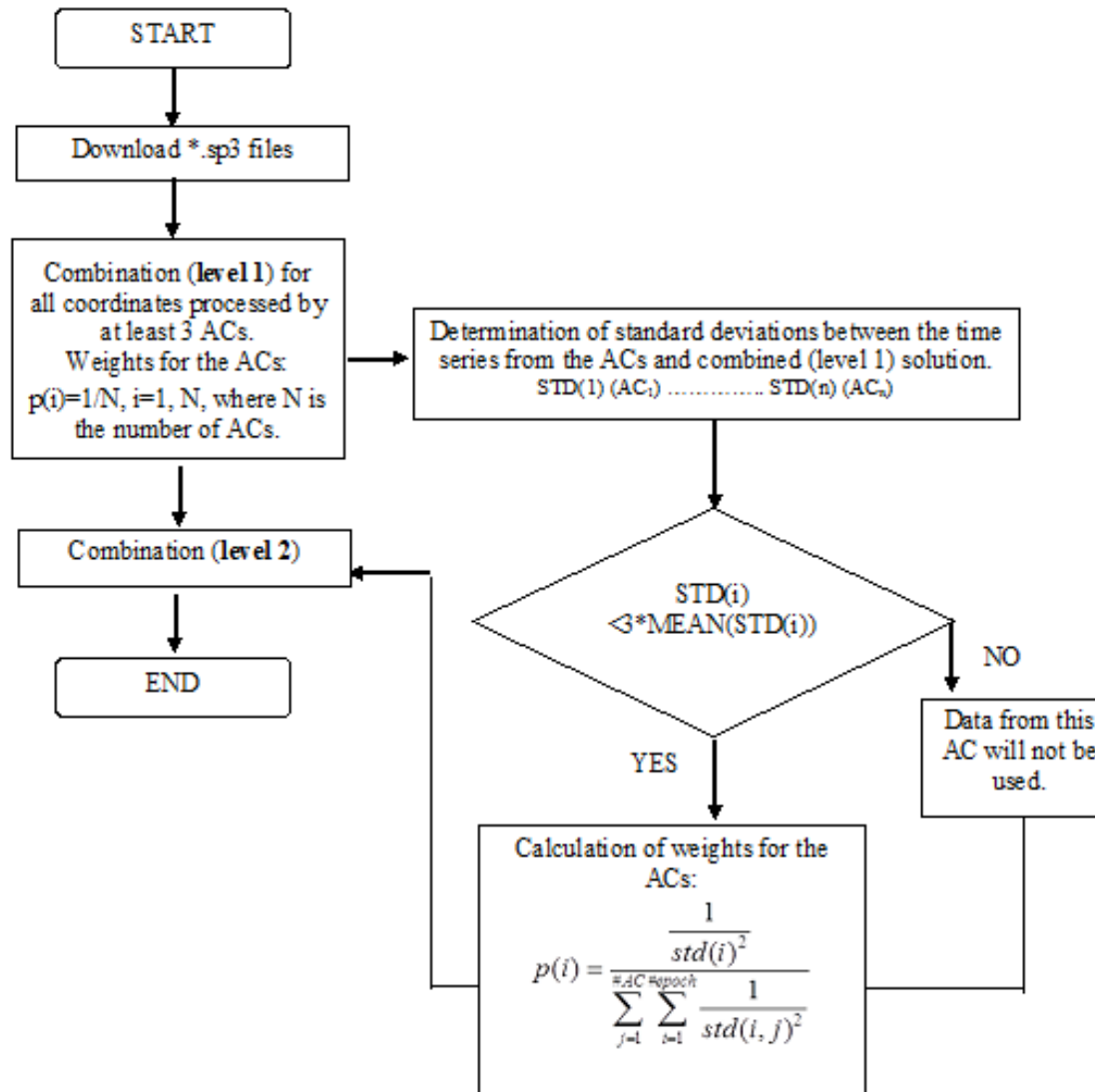
STD

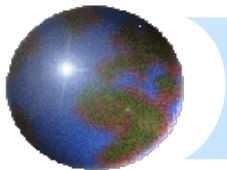




Combination strategy outline

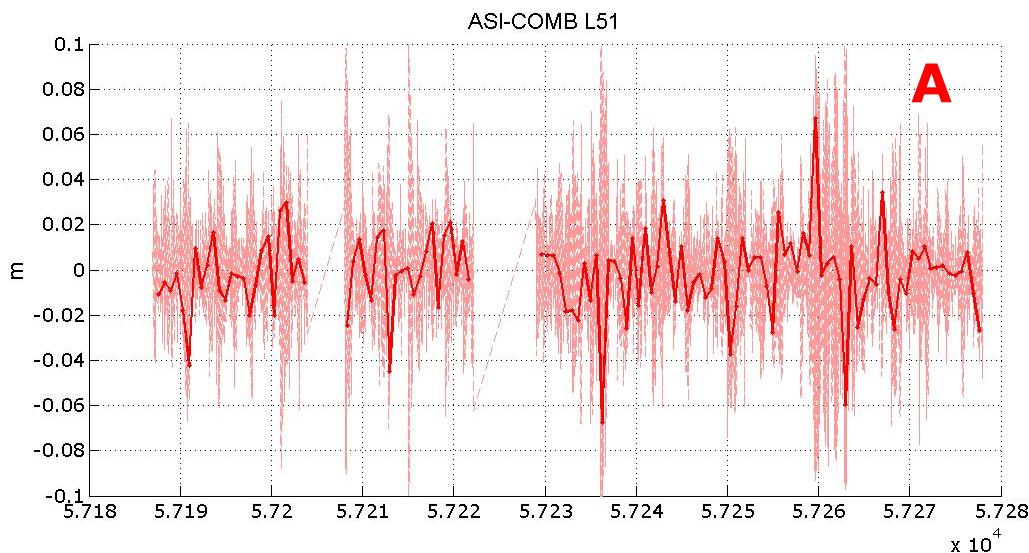
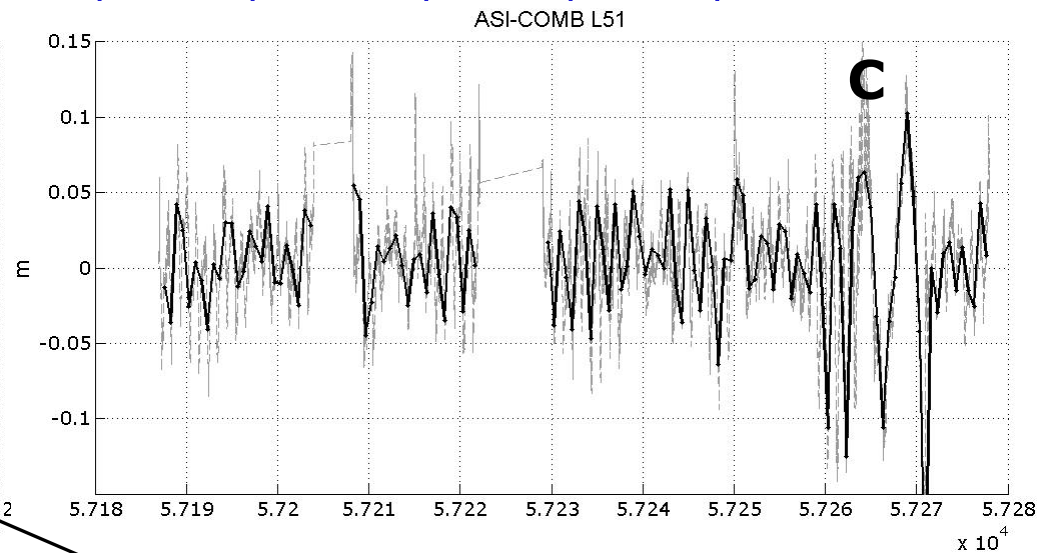
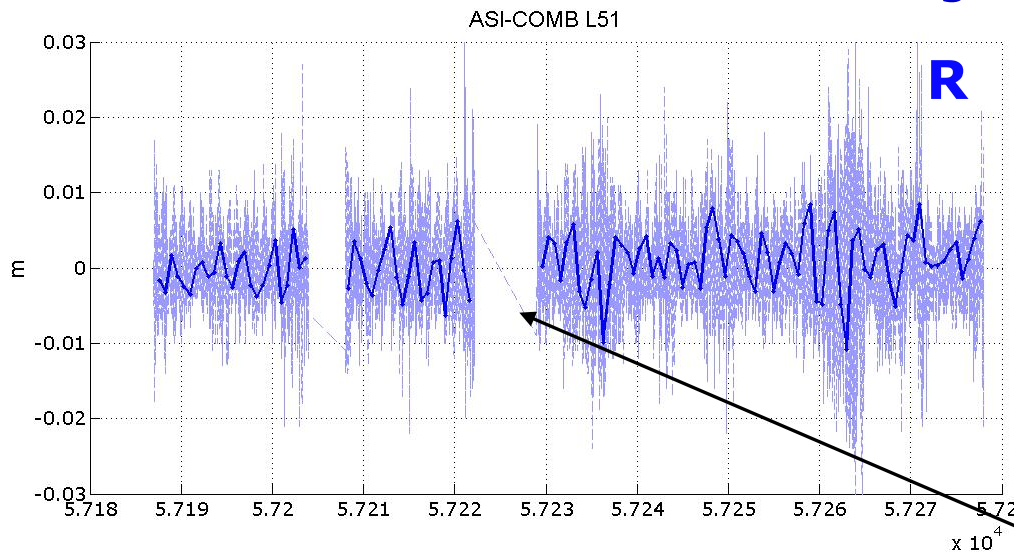
Assumption: each ILRS AC SP3 in AC weekly EF reference frame





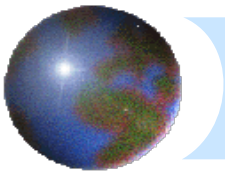
L51 ACs vs Combination

Test combination for L51 using **ASI**, BKG, DGFI, ESA, GFZ, NSGF



Gap to investigate

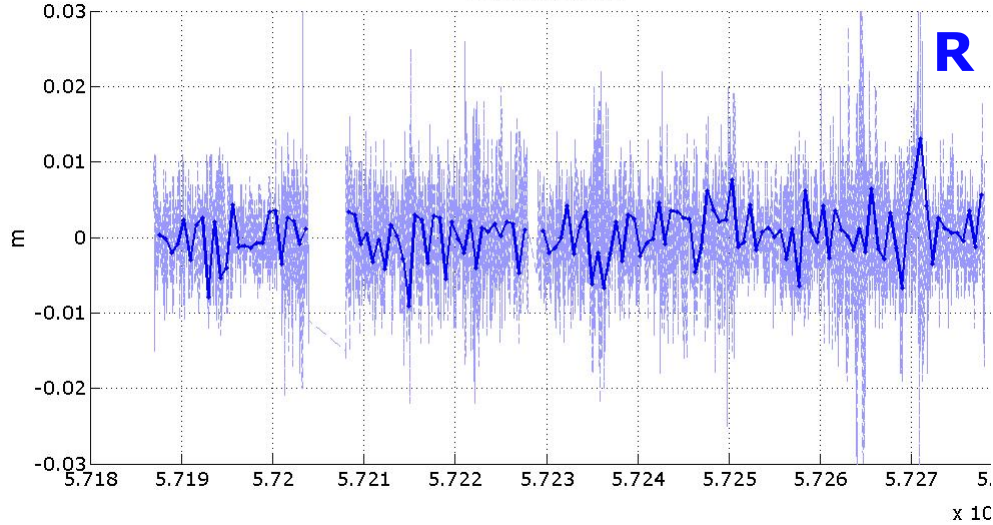
	MEAN [mm]	STD [mm]
R	0.2	5.8
A	-0.4	24.9
C	3.4	37.7



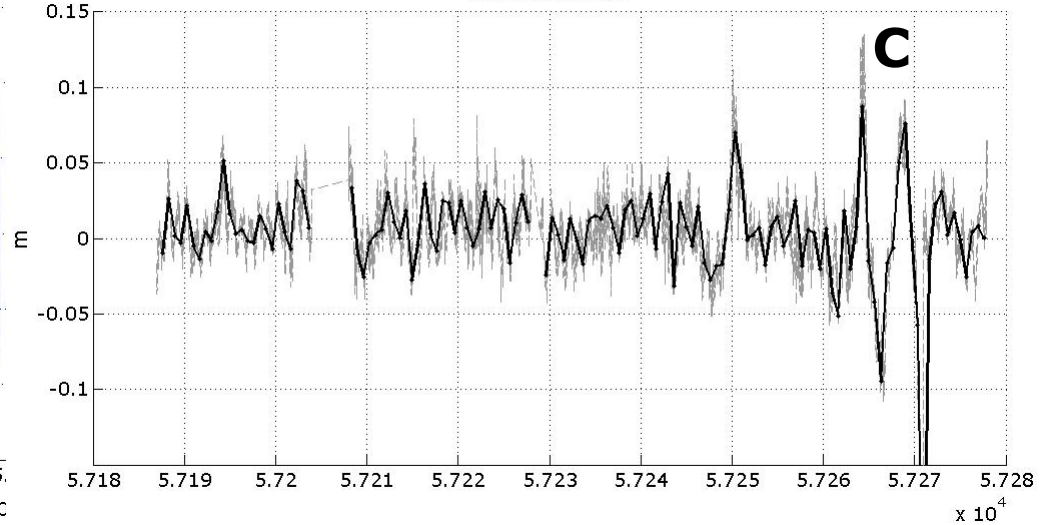
L51 ACs vs Combination

Test combination for L51 using ASI, **BKG**, DGFI, ESA, GFZ, NSGF

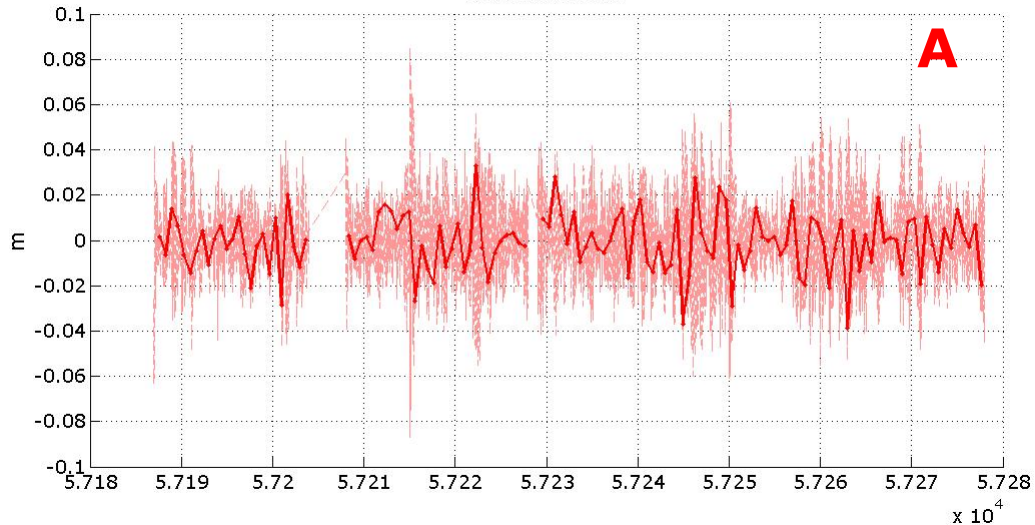
BKG-COMB L51



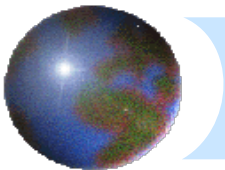
BKG-COMB L51



BKG-COMB L51

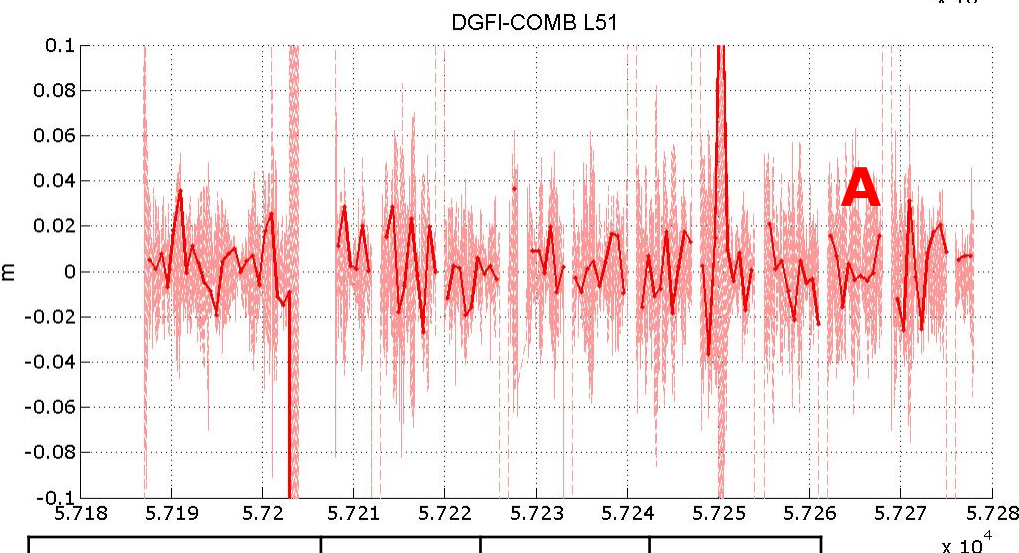
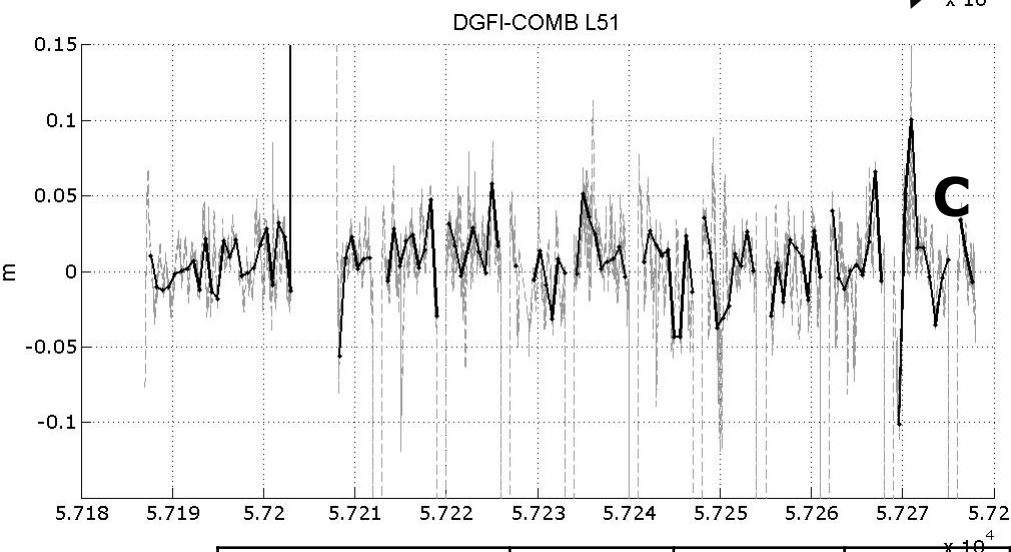
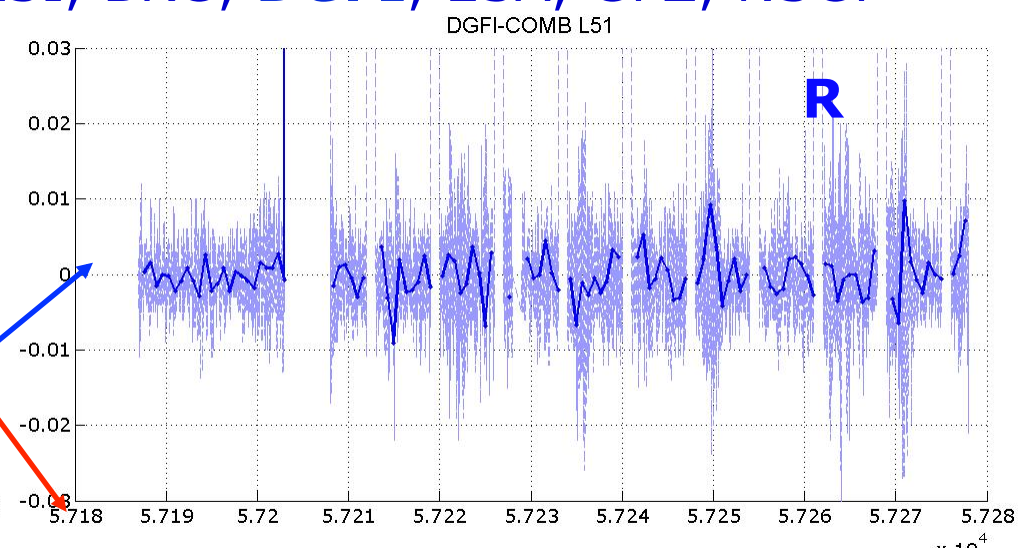
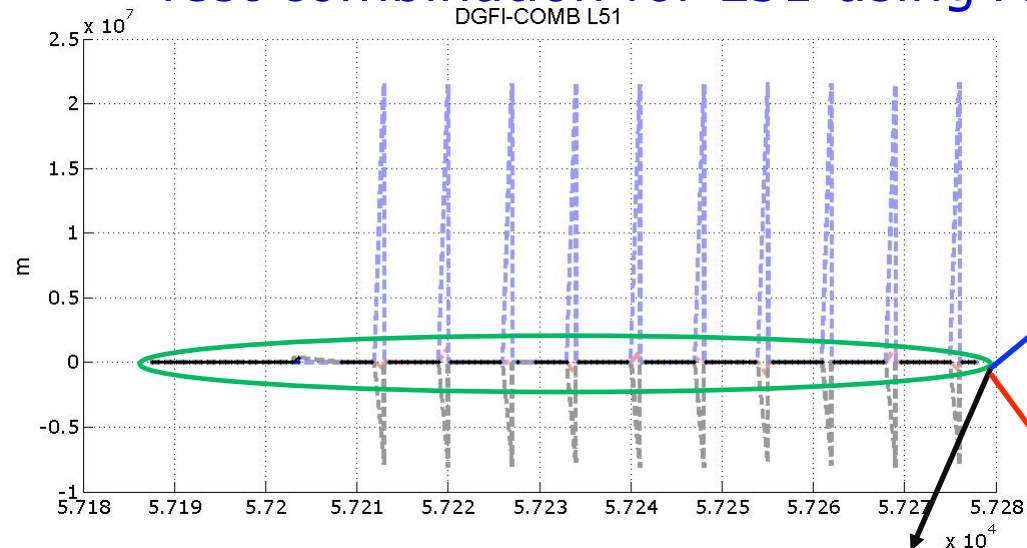


	MEAN [mm]	STD [mm]
R	0.2	5.4
A	-0.2	16.7
C	3.9	29.4



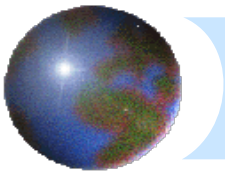
L51 ACs vs Combination

Test combination for L51 using ASI, BKG, **DGFI**, ESA, GFZ, NSGF



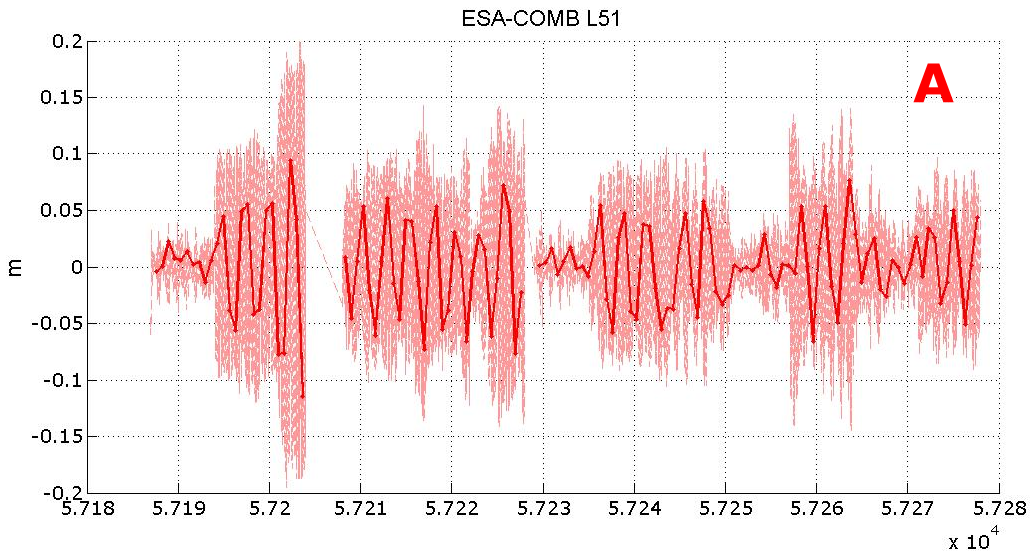
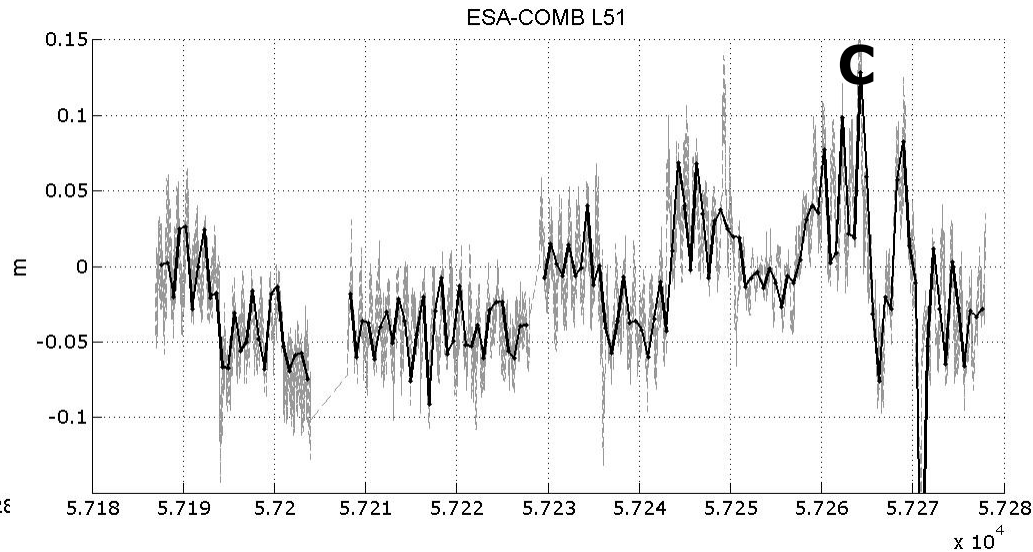
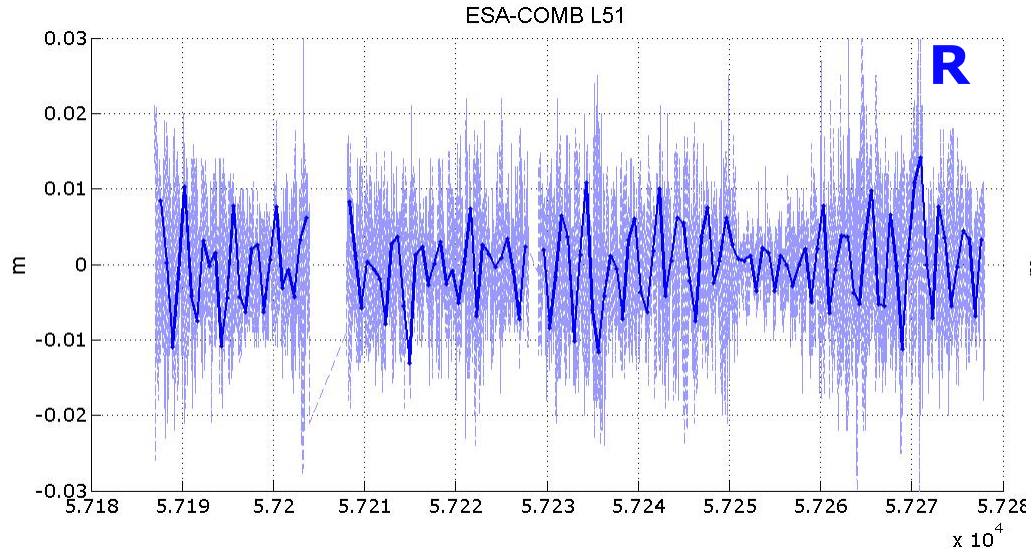
	R	A	C
MEAN [mm]	2.1	-0.9	3.3

	R	A	C
STD [mm]	6.6	14.5	20.2

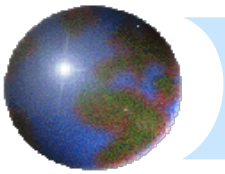


L51 ACs vs Combination

Test combination for L51 using ASI, BKG, DGFI, **ESA**, GFZ, NSGF



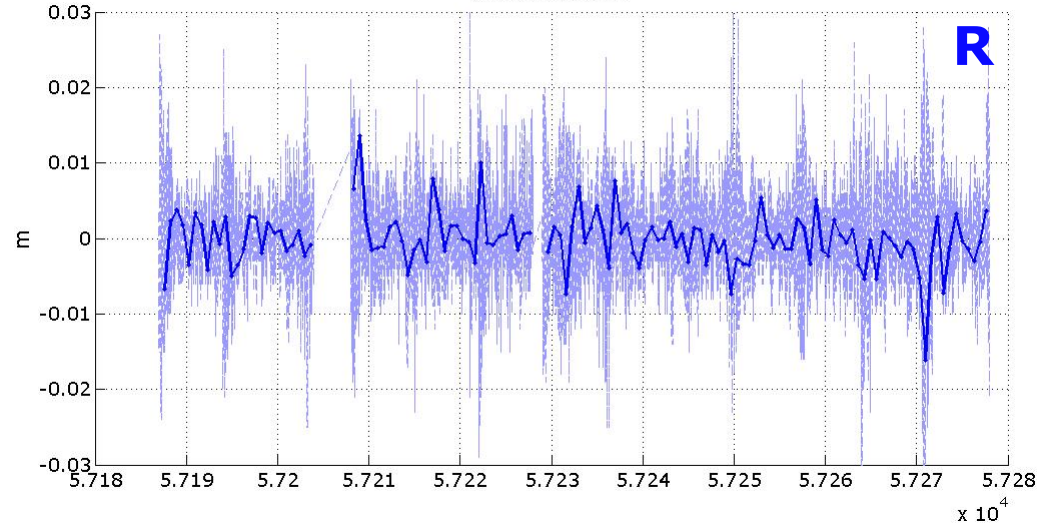
	MEAN [mm]	STD [mm]
R	-0.3	7.5
A	0.5	54.2
C	-15.8	42.7



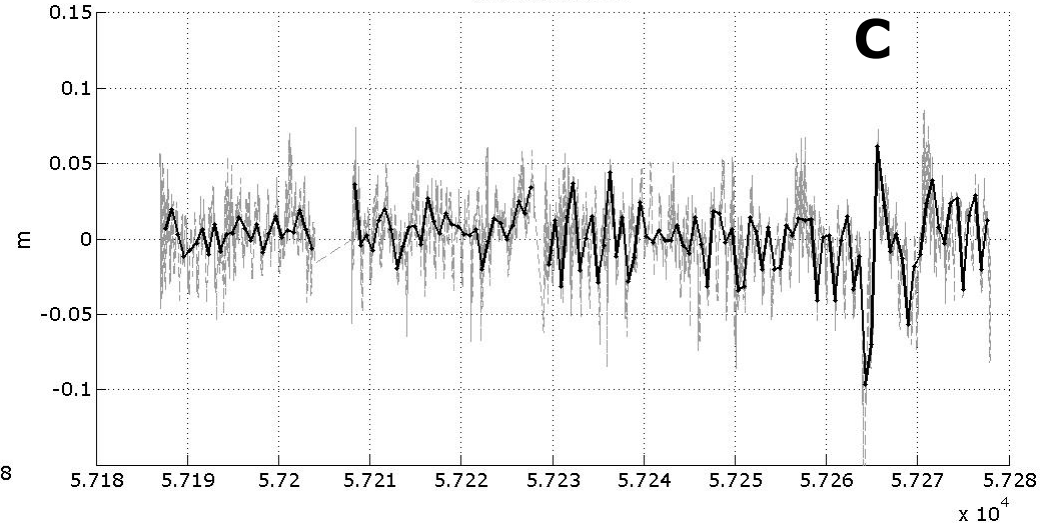
L51 ACs vs Combination

Test combination for L51 using ASI, BKG, DGFI, ESA, **GFZ**, NSGF

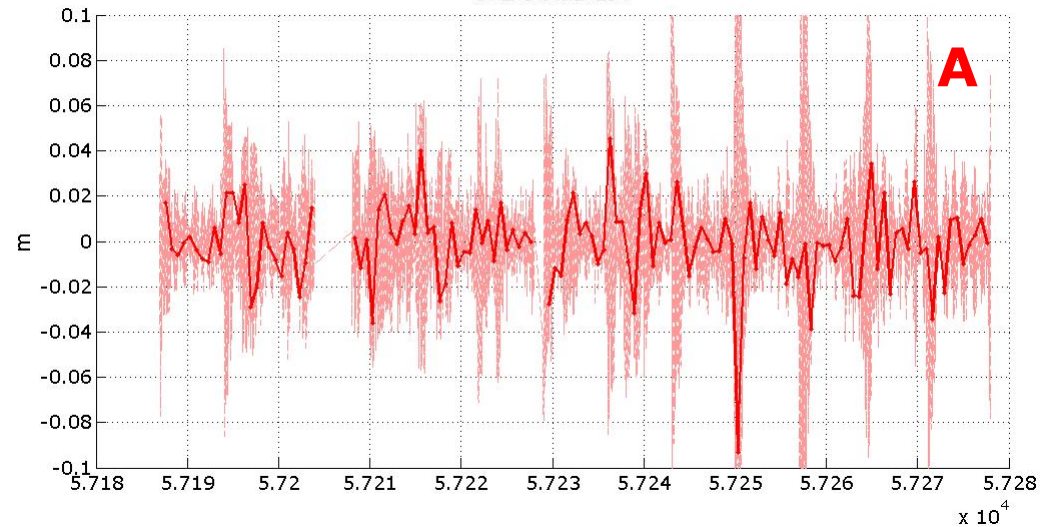
GFZ-COMB L51



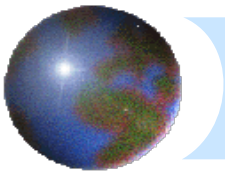
GFZ-COMB L51



GFZ-COMB L51



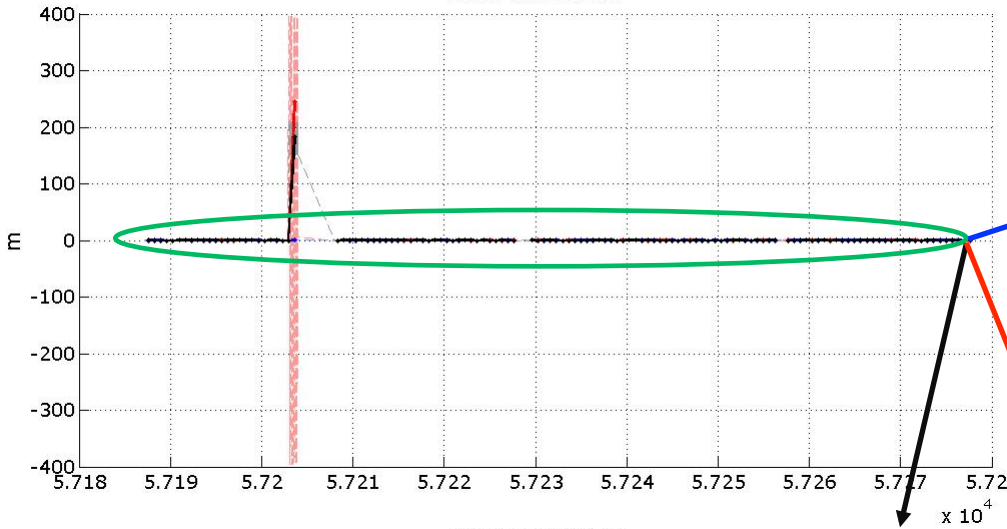
	MEAN [mm]	STD [mm]
R	0.4	5.8
A	-0.1	25.3
C	0.8	25.3



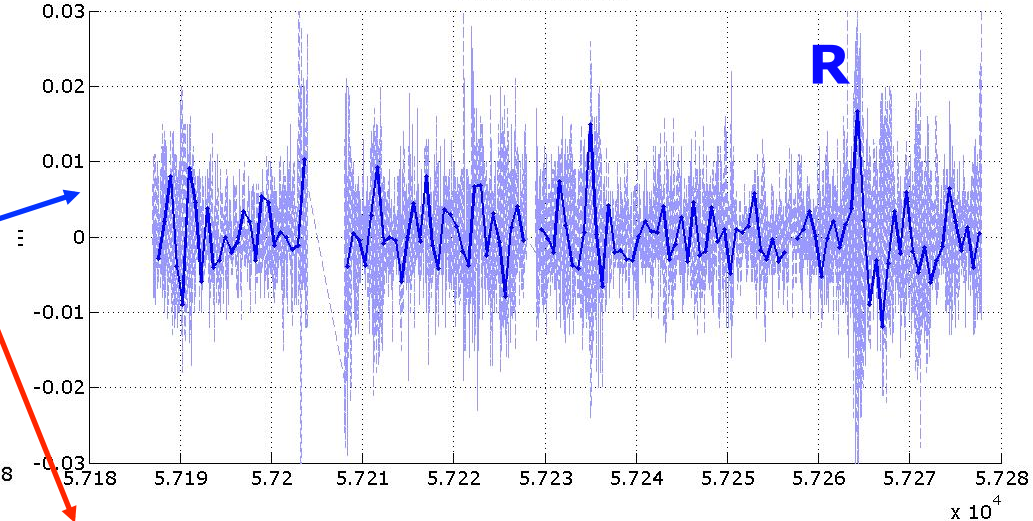
L51 ACs vs Combination

Test combination for L51 using ASI, BKG, DGFI, ESA, GFZ, **NSGF**

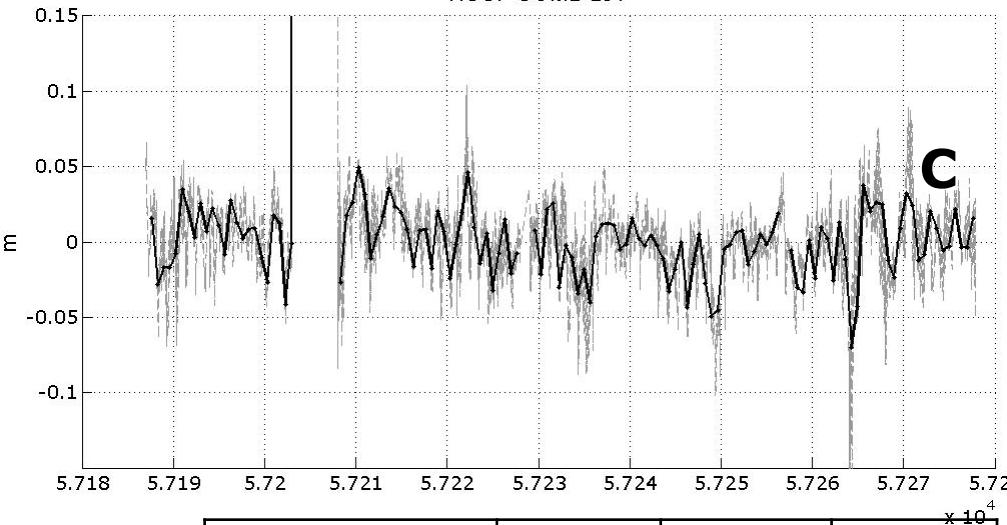
NSGF-COMB L51



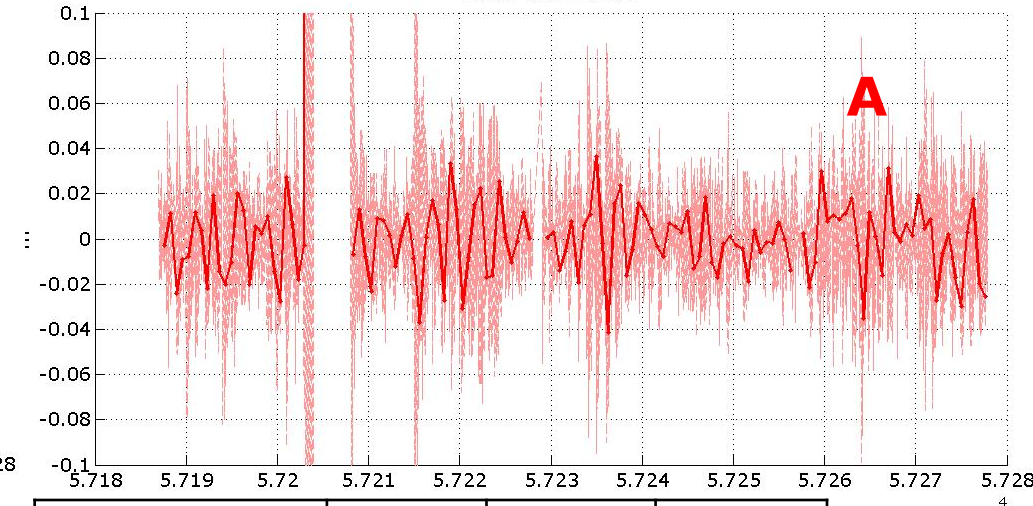
NSGF-COMB L51



NSGF-COMB L51

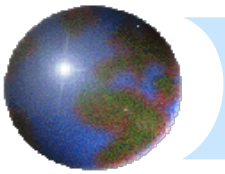


NSGF-COMB L51



	R	A	C
MEAN [mm]	0.4	1.0	-3.3

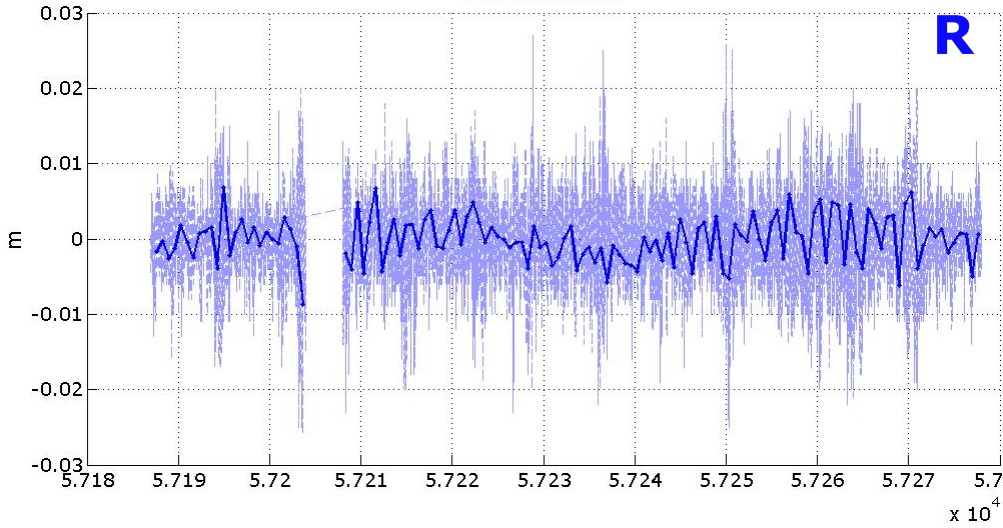
	R	A	C
STD [mm]	6.3	18.3	21.7



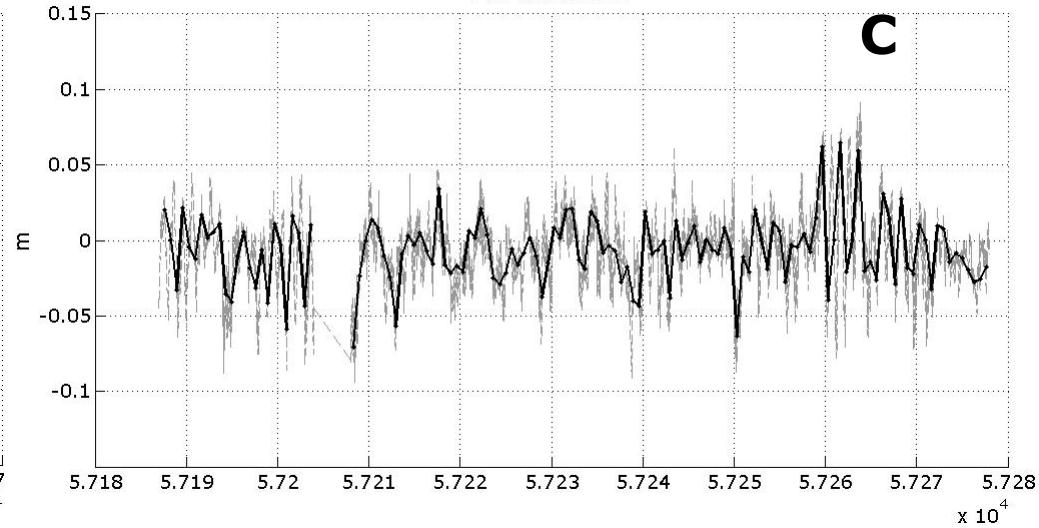
L52 ACs vs Combination

Test combination for L52 using **ASI**, BKG, DGFI, ESA, GFZ, NSGF

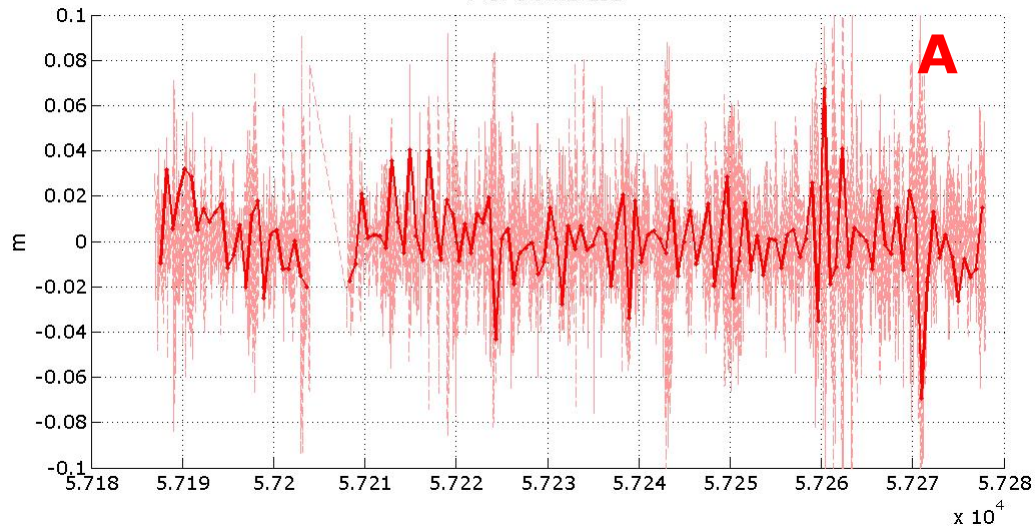
ASI-COMB L52



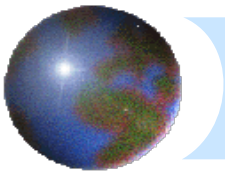
ASI-COMB L52



ASI-COMB L52



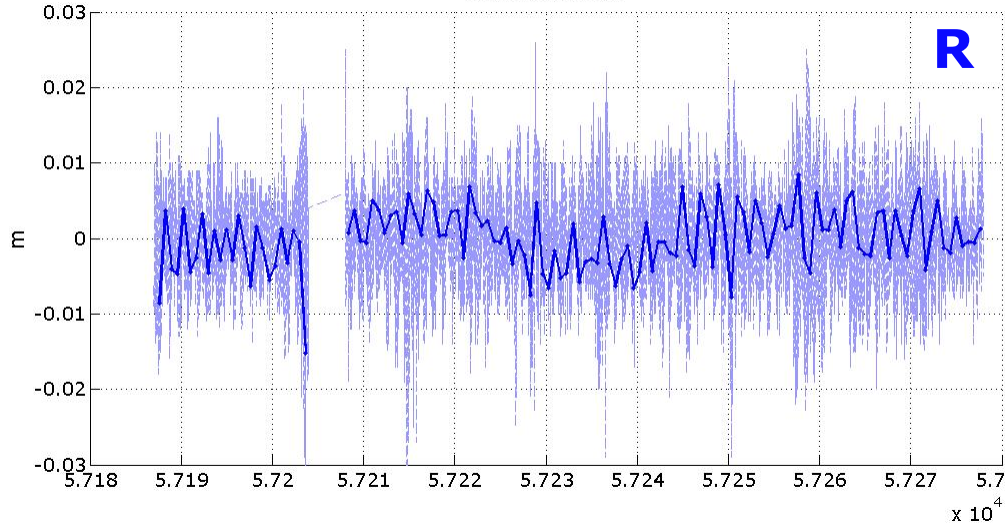
	MEAN [mm]	STD [mm]
R	-2.3	5.1
A	0.1	42.9
C	-7.2	23.7



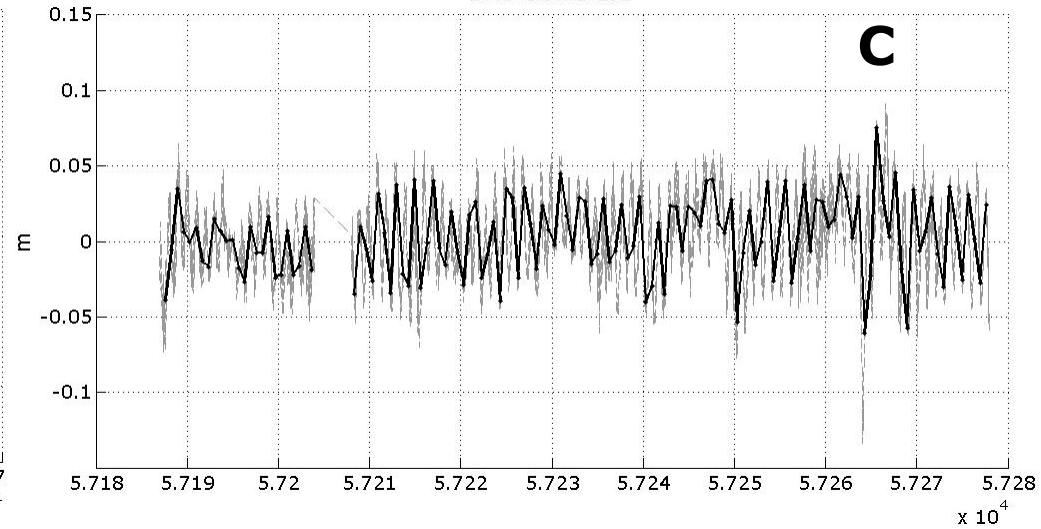
L52 ACs vs Combination

Test combination for L52 using ASI, **BKG**, DGFI, ESA, GFZ, NSGF

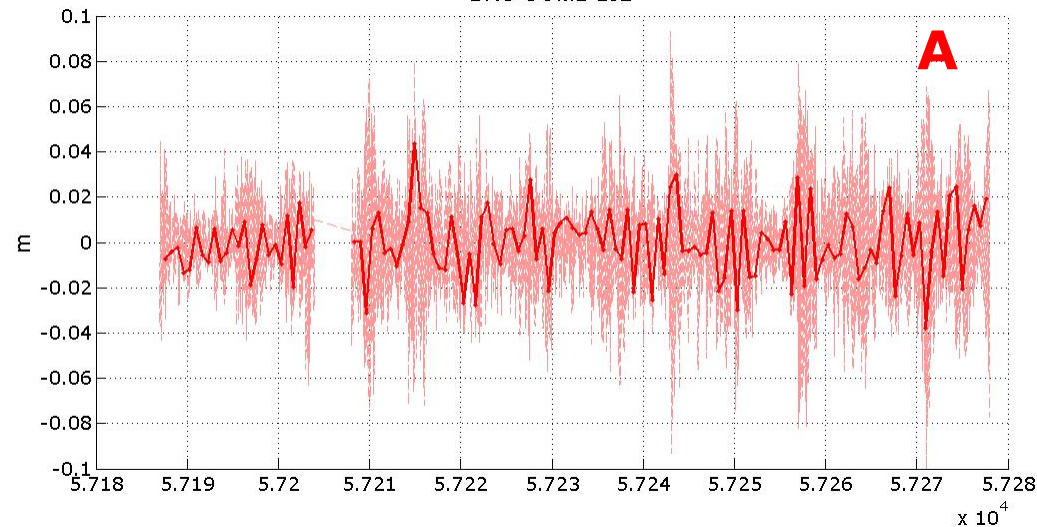
BKG-COMB L52



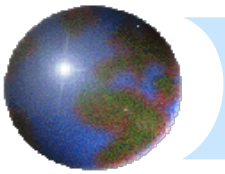
BKG-COMB L52



BKG-COMB L52

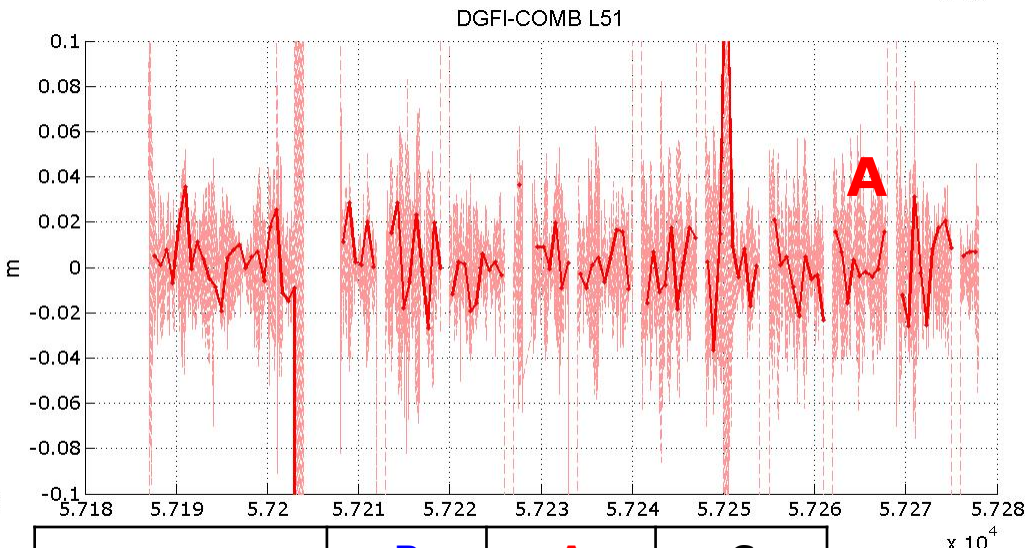
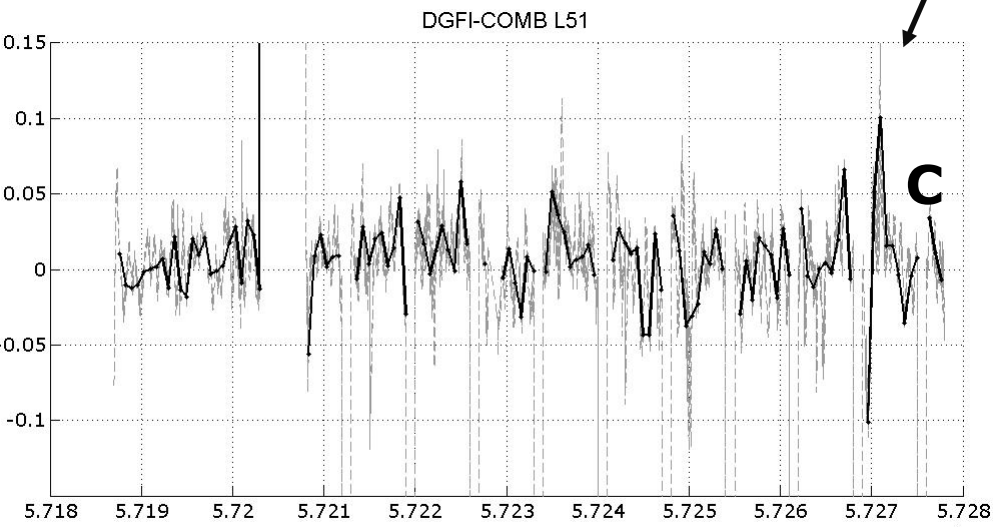
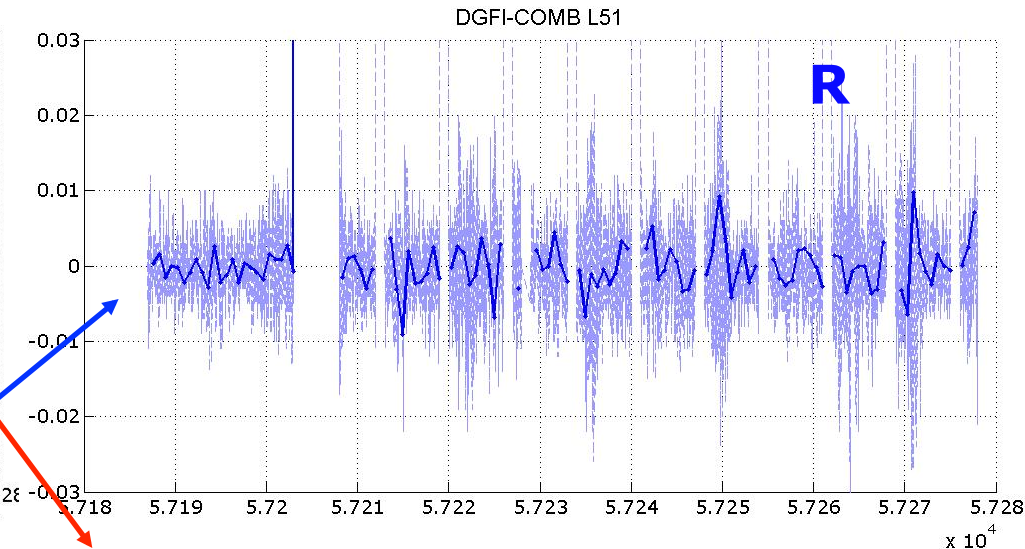
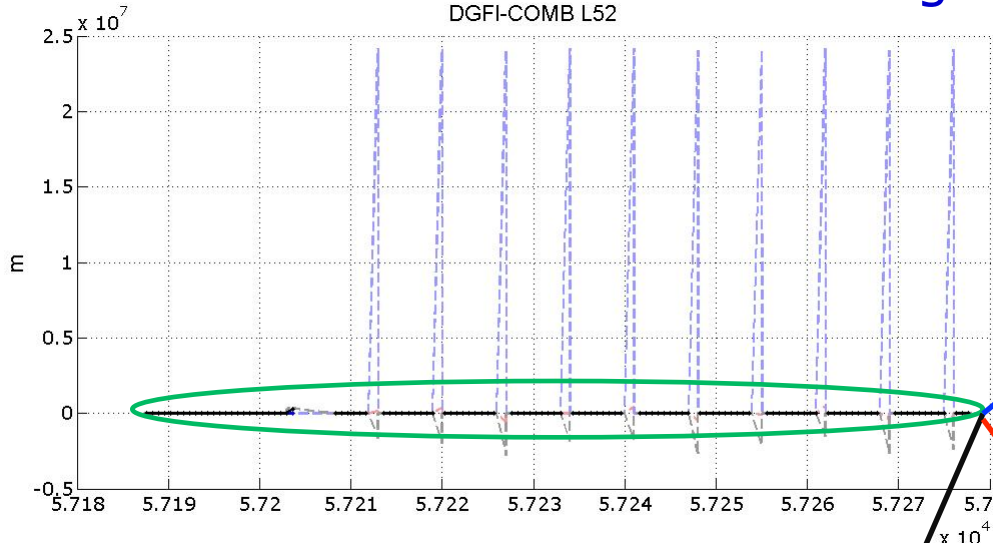


	MEAN [mm]	STD [mm]
R	-0.1	5.9
A	-0.8	21.1
C	1.8	25.6



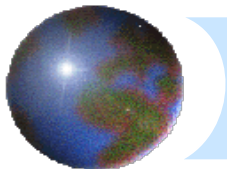
L52 ACs vs Combination

Test combination for L52 using ASI, BKG, **DGFI**, ESA, GFZ, NSGF



	R	A	C
MEAN [mm]	0.4	0.9	-3.0

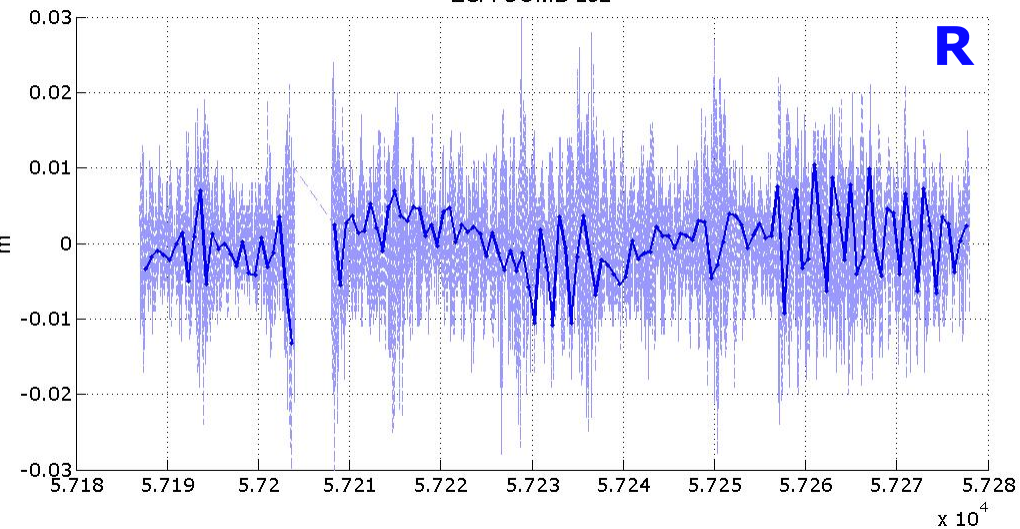
	R	A	C
STD [mm]	5.2	20.1	23.5



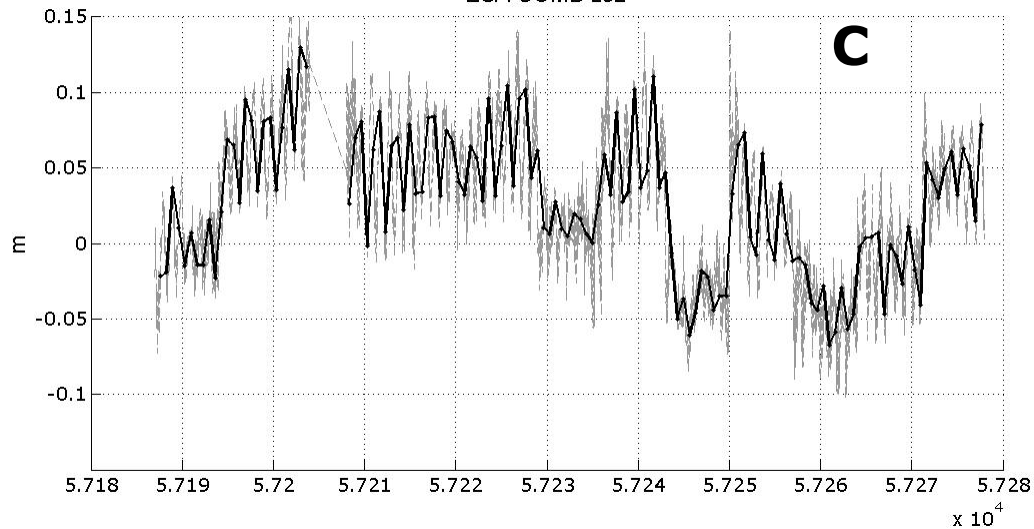
L52 ACs vs Combination

Test combination for L52 using ASI, BKG, DGFI, **ESA**, GFZ, NSGF

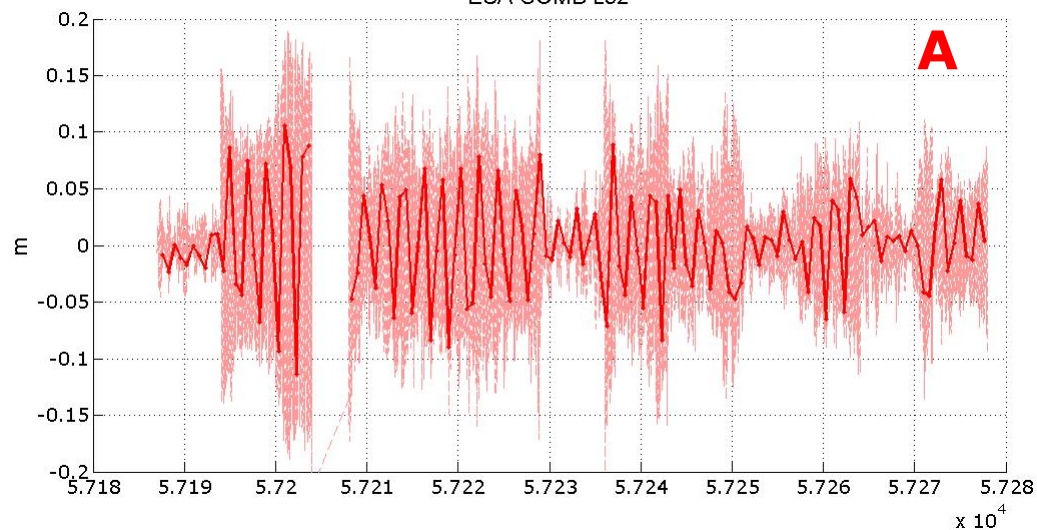
ESA-COMB L52



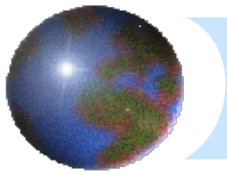
ESA-COMB L52



ESA-COMB L52



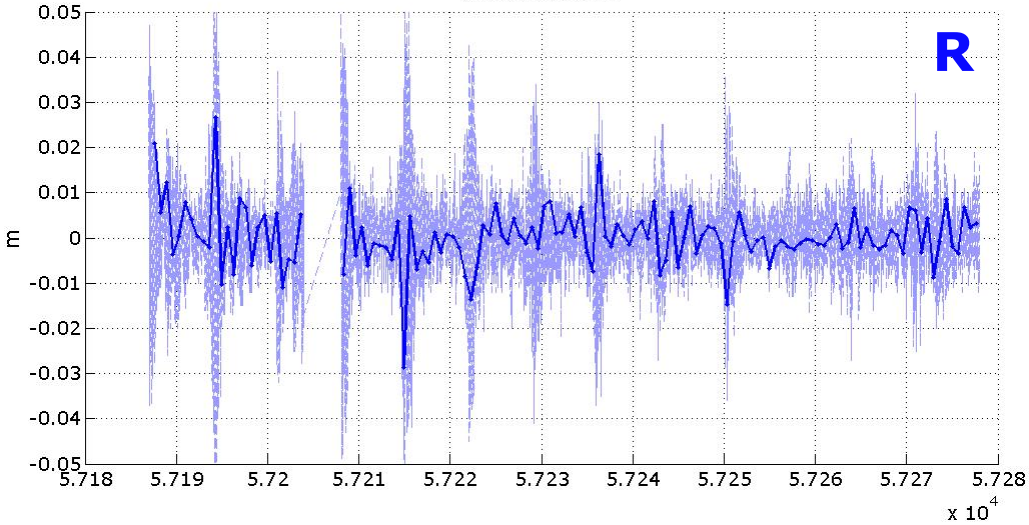
	MEAN [mm]	STD [mm]
R	-0.3	6.4
A	0.5	58.8
C	26.3	47.1



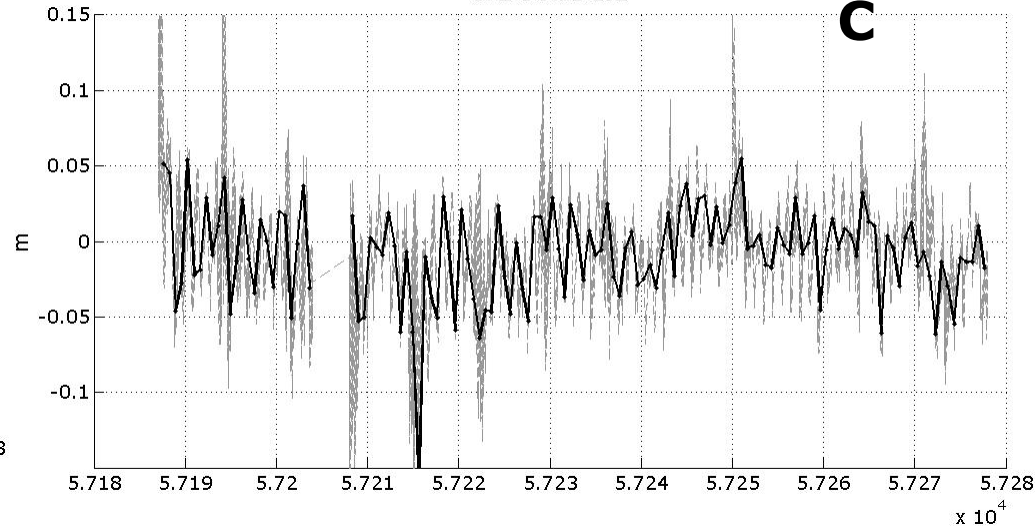
L52 ACs vs Combination

Test combination for L52 using ASI, BKG, DGFI, ESA, **GFZ**, NSGF

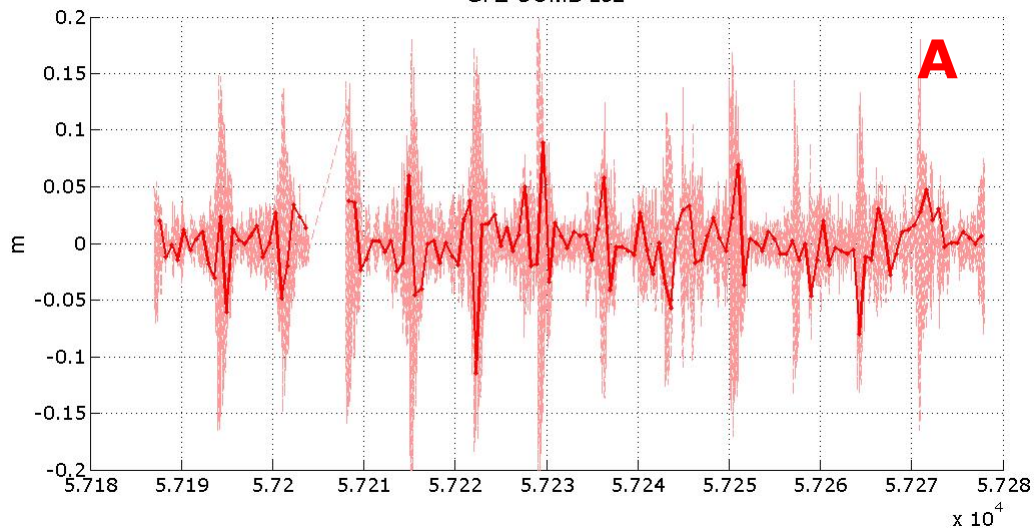
GFZ-COMB L52



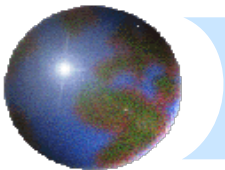
GFZ-COMB L52



GFZ-COMB L52



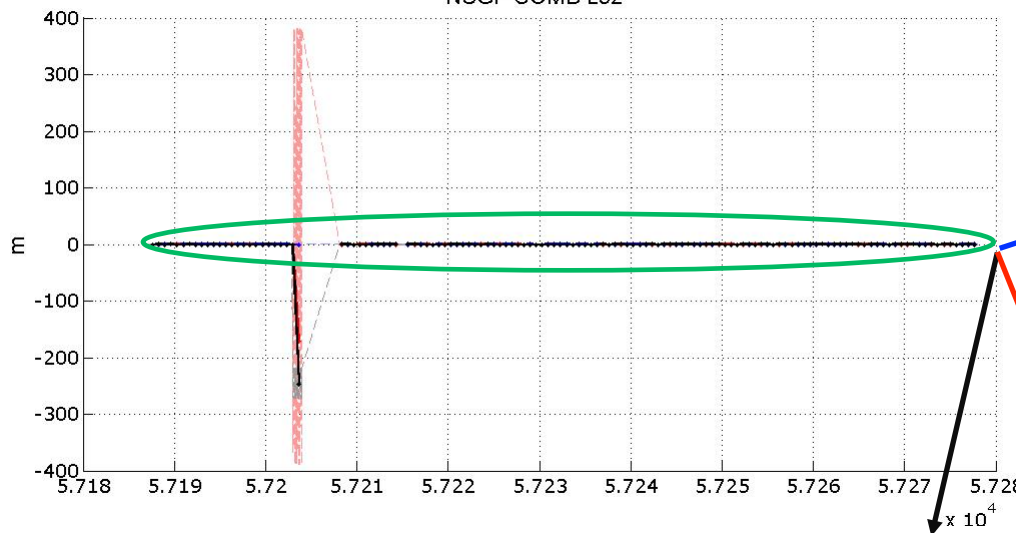
	MEAN [mm]	STD [mm]
R	0.2	9.6
A	-0.4	40.7
C	-7.9	33.9



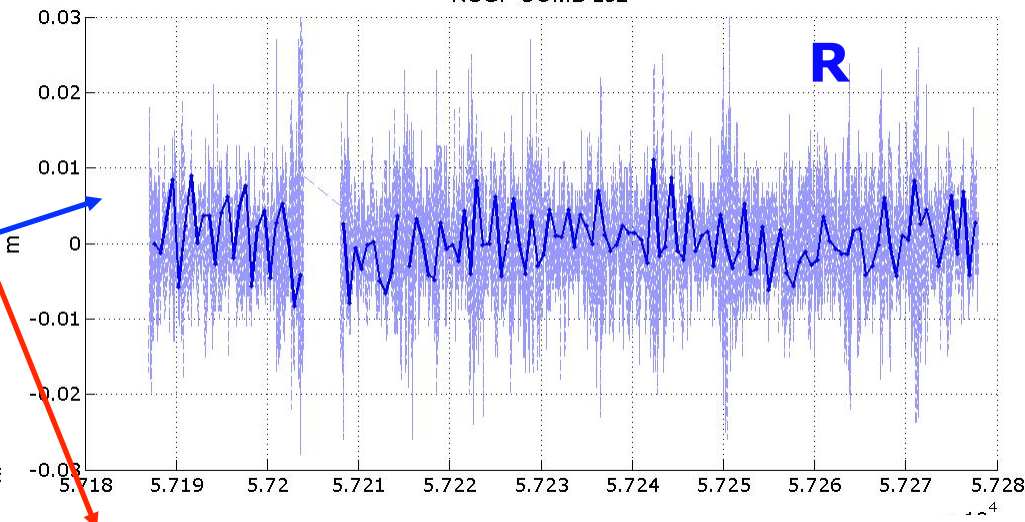
L52 ACs vs Combination

Test combination for L52 using ASI, BKG, DGFI, ESA, GFZ, **NSGF**

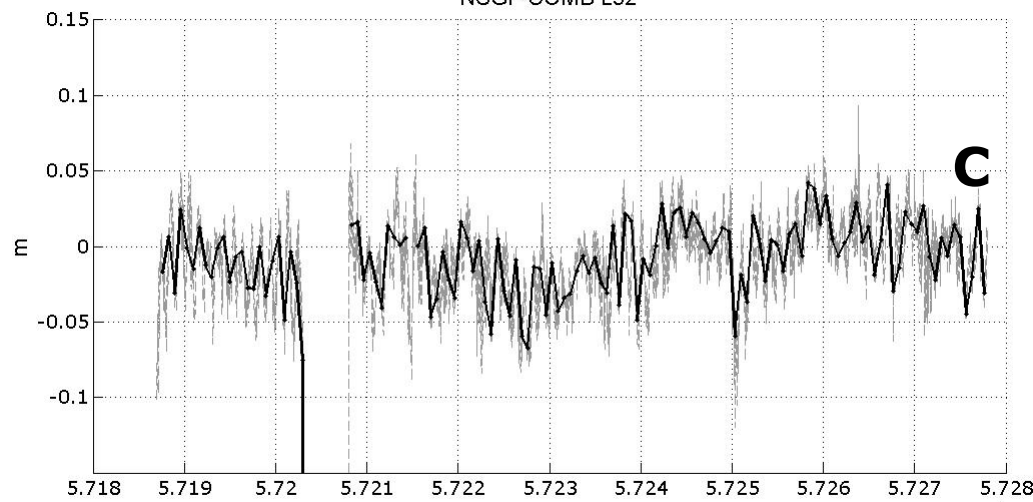
NSGF-COMB L52



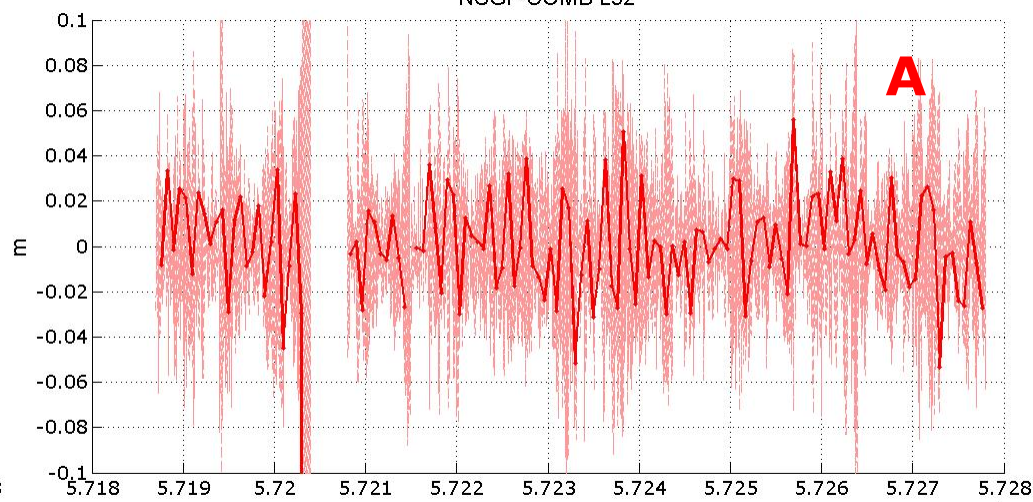
NSGF-COMB L52



NSGF-COMB L52

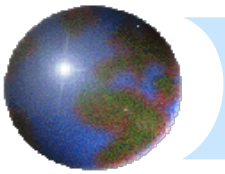


NSGF-COMB L52



	R	A	C
MEAN [mm]	0.2	-0.4	0.3

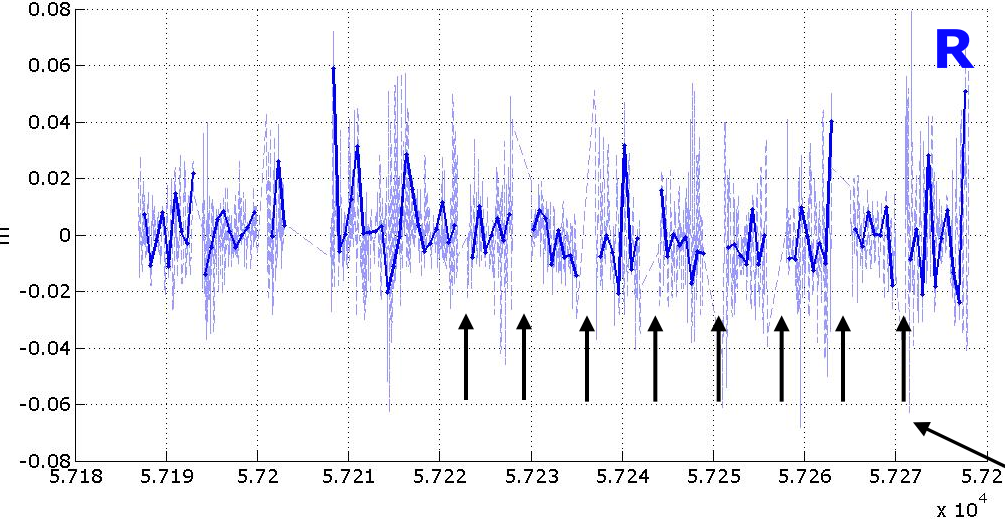
	R	A	C
STD [mm]	6.1	22.3	19.2



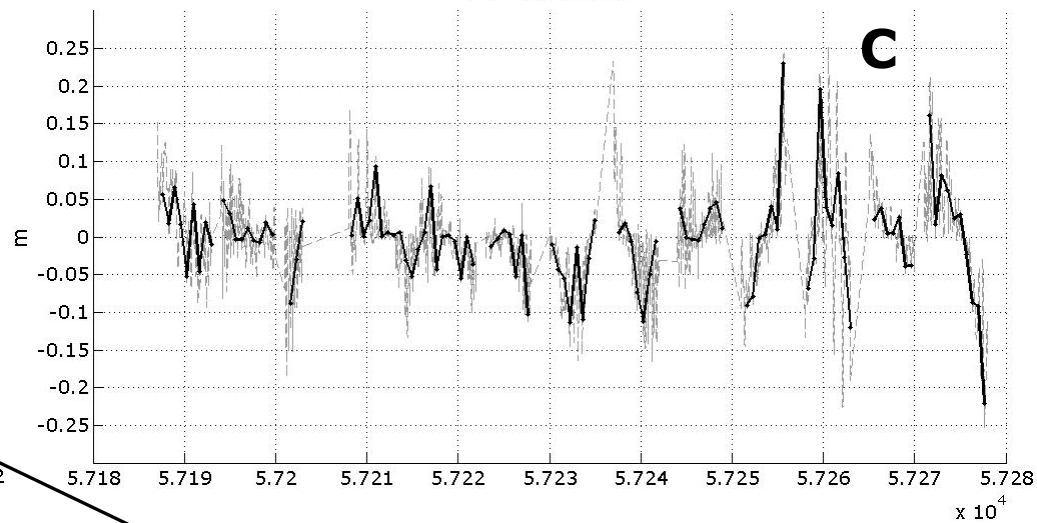
L53 ACs vs Combination

Test combination for L53 using **ASI**, ESA, NSGF

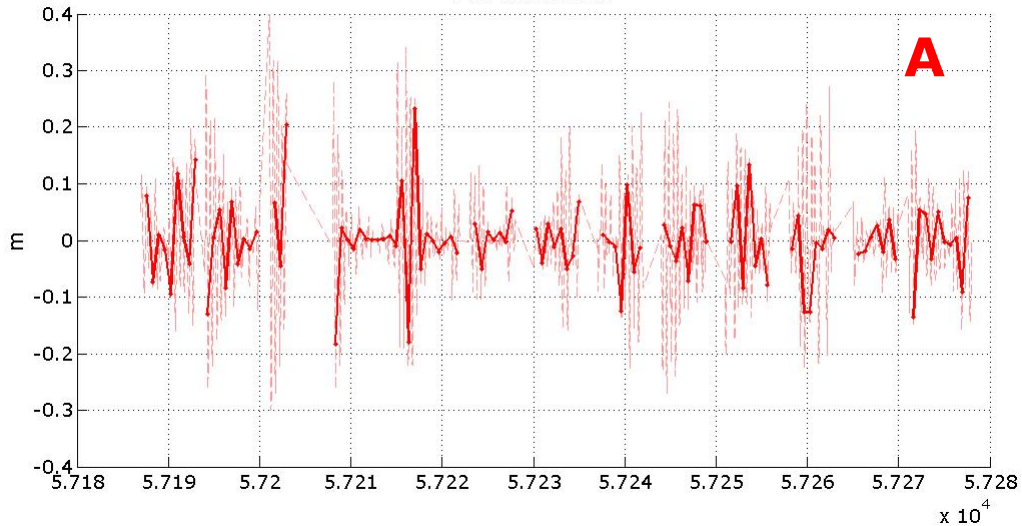
ASI-COMB L53



ASI-COMB L53

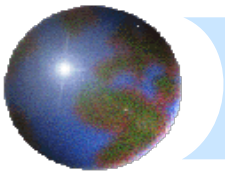


ASI-COMB L53



Gaps to investigate for all ACs
 (#AC < 3: NSGF excluded, BKG not considered for wrong epochs)

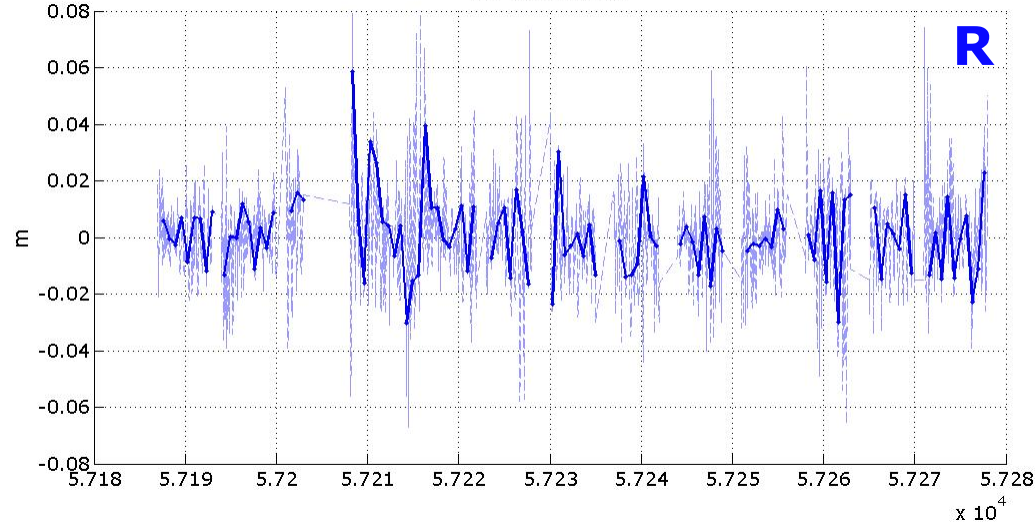
	MEAN [mm]	STD [mm]
R	3.5	14.6
A	3.1	78.5
C	-1.3	59.3



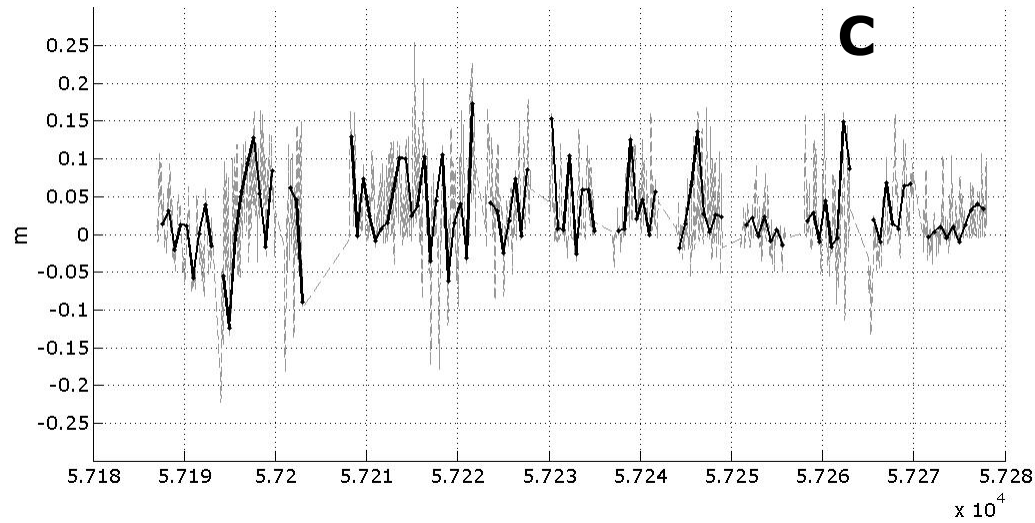
L53 ACs vs Combination

Test combination for L53 using ASI, **ESA**, NSGF

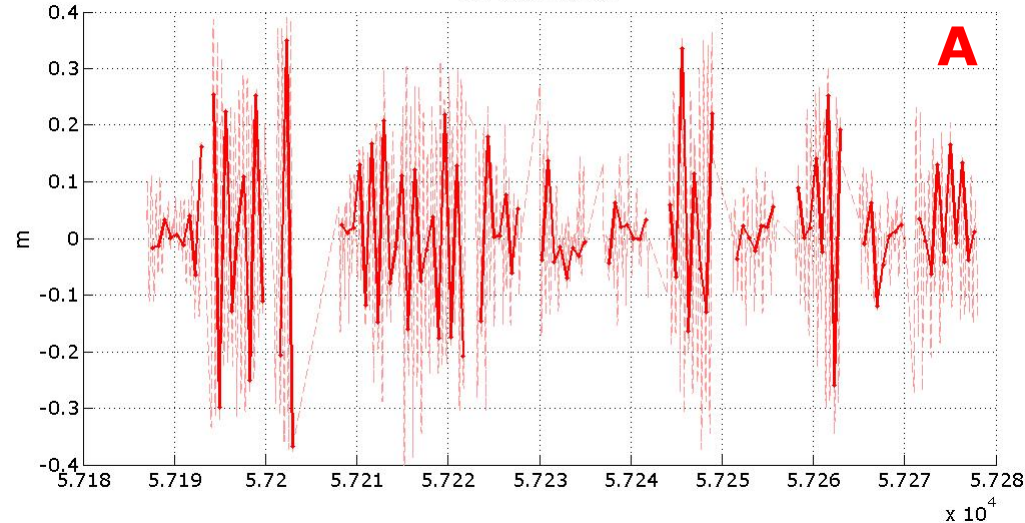
ESA-COMB L53



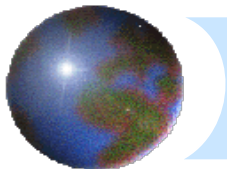
ESA-COMB L53



ESA-COMB L53



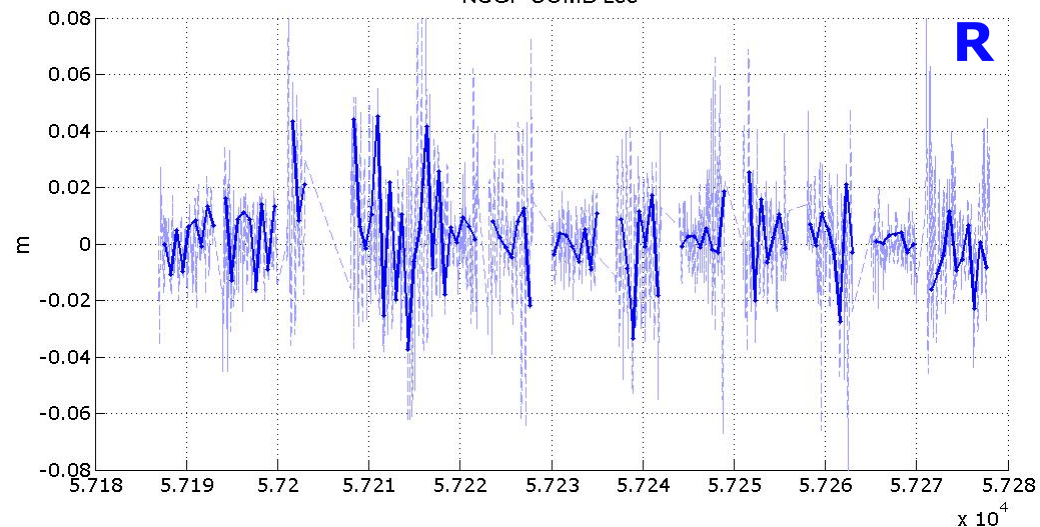
	MEAN [mm]	STD [mm]
R	1.6	17.4
A	0.7	107.0
C	-35.5	91.0



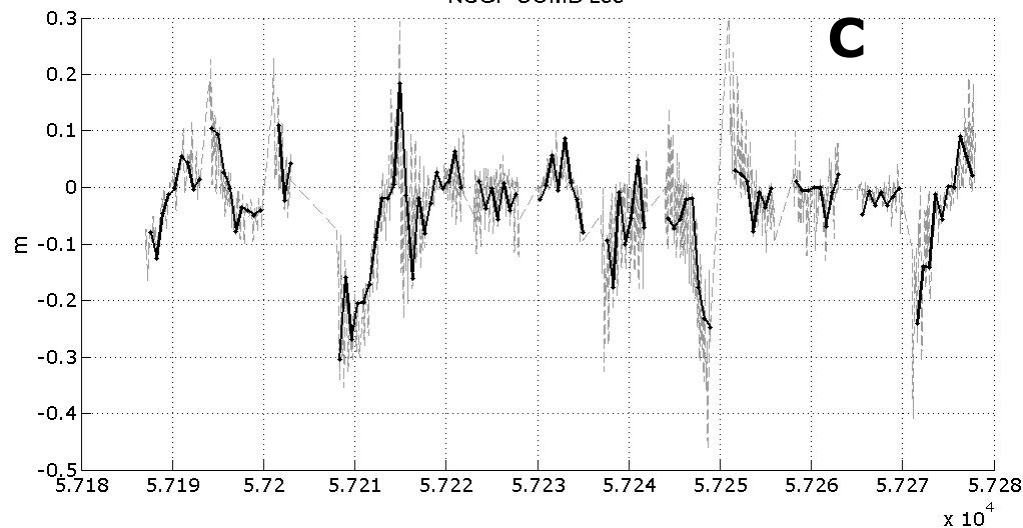
L53 ACs vs Combination

Test combination for L53 using ASI, ESA, **NSGF**

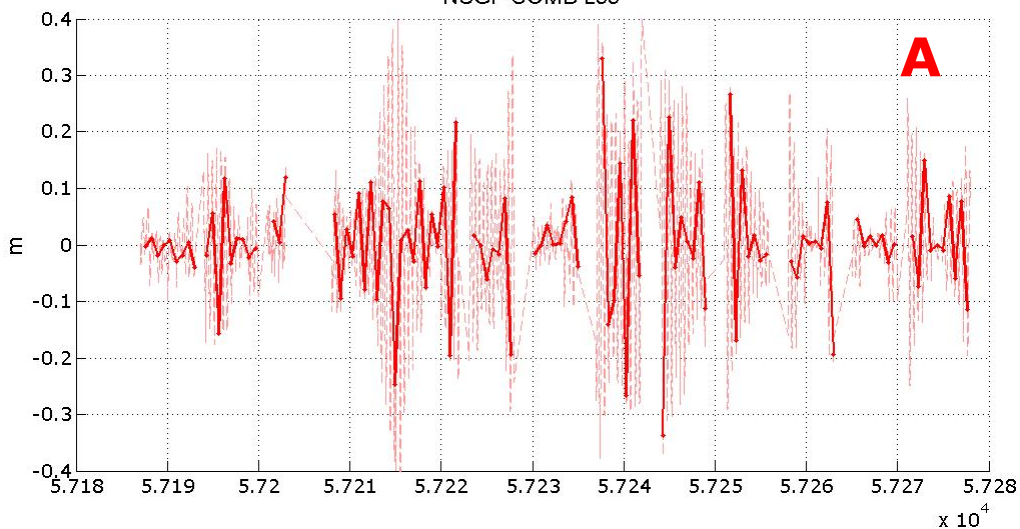
NSGF-COMB L53



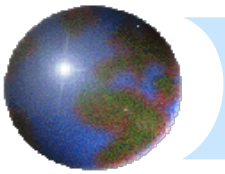
NSGF-COMB L53



NSGF-COMB L53



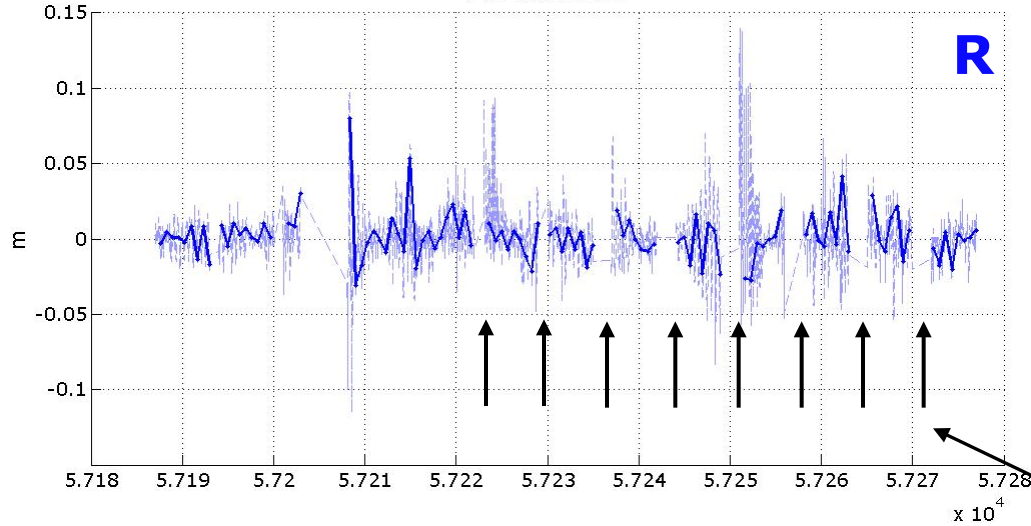
	MEAN [mm]	STD [mm]
R	0.1	15.6
A	-5.7	132.0
C	-35.5	102.0



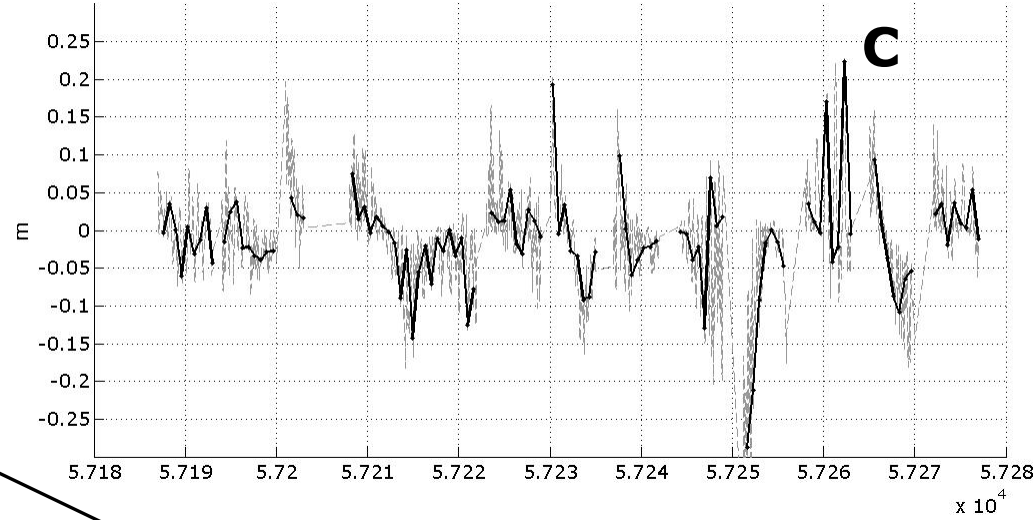
L54 ACs vs Combination

Test combination for L54 using **ASI**, ESA, NSGF

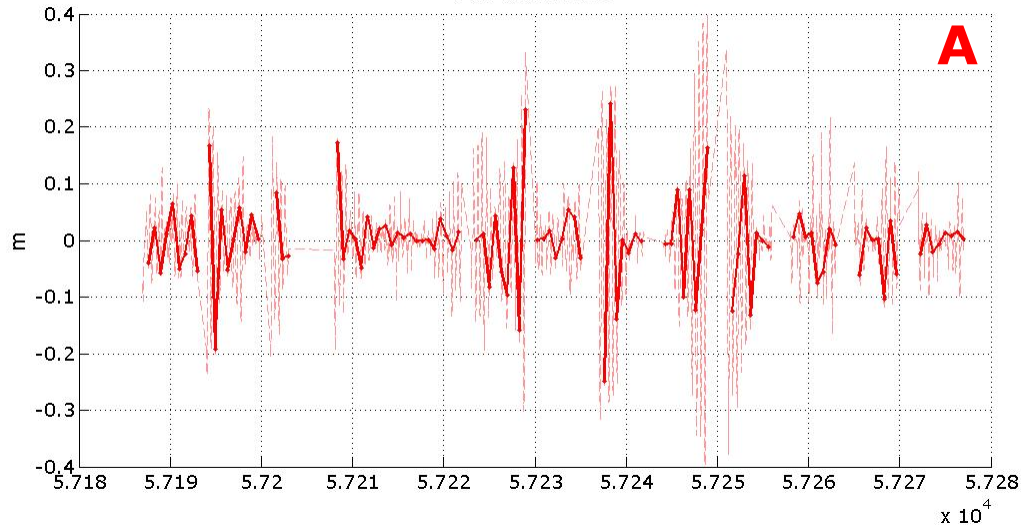
ASI-COMB L54



ASI-COMB L54

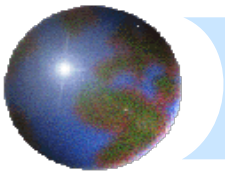


ASI-COMB L54



Gaps to investigate for all ACs
(#AC < 3: NSGF excluded, BKG not considered for wrong epochs)

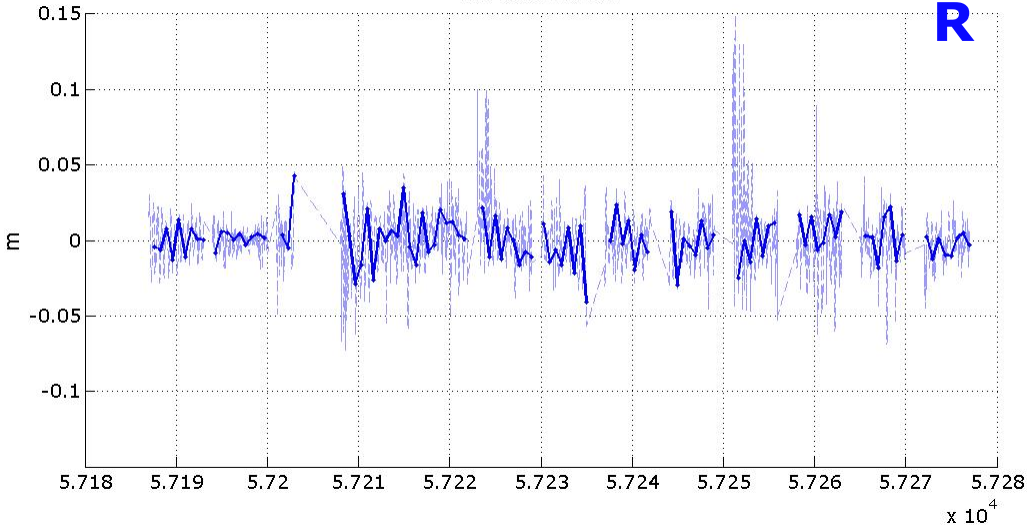
	MEAN [mm]	STD [mm]
R	1.0	17.7
A	-1.0	80.7
C	-12.5	66.9



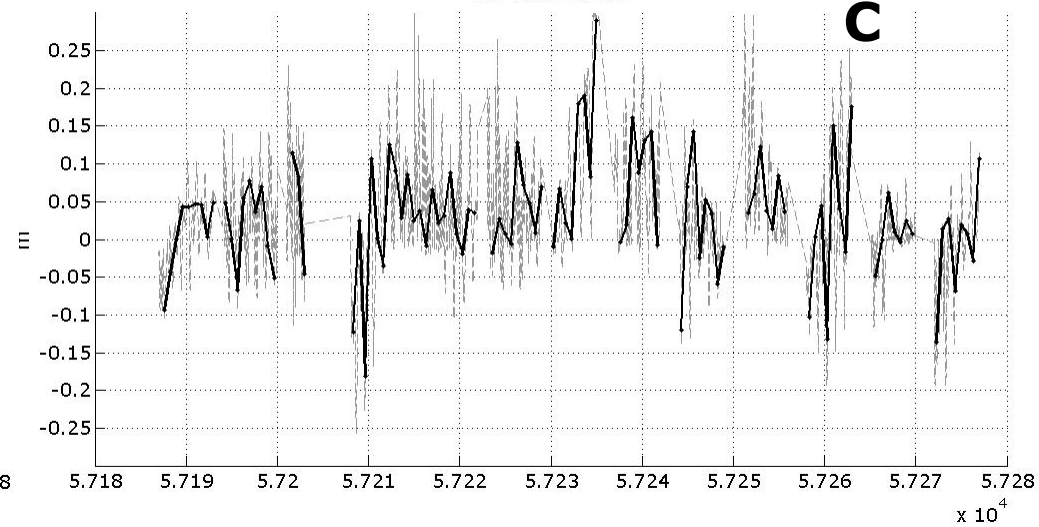
L54 ACs vs Combination

Test combination for L54 using ASI, **ESA**, NSGF

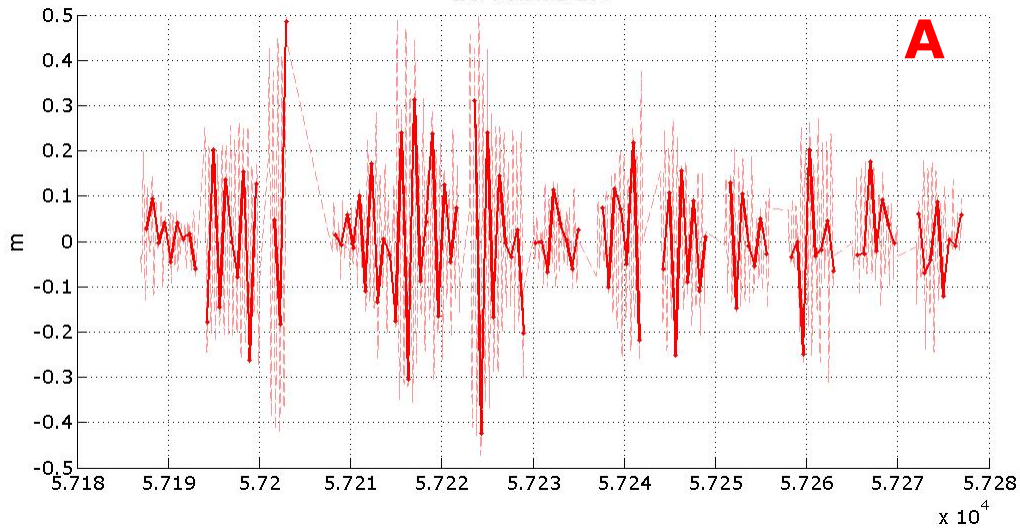
ESA-COMB L54



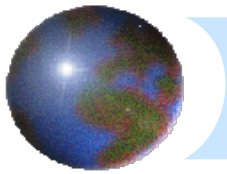
ESA-COMB L54



ESA-COMB L54



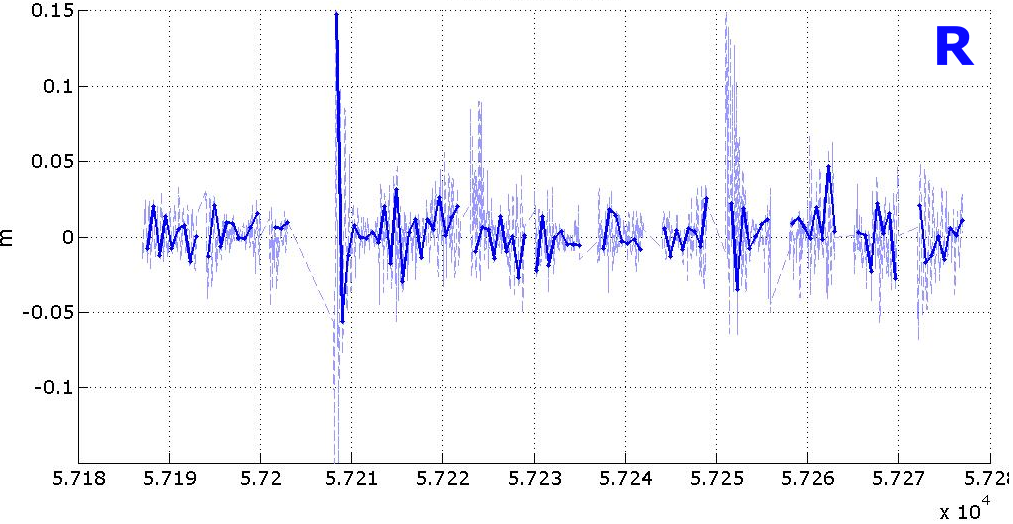
	MEAN [mm]	STD [mm]
R	1.6	21.5
A	-1.8	108.0
C	-11.2	61.8



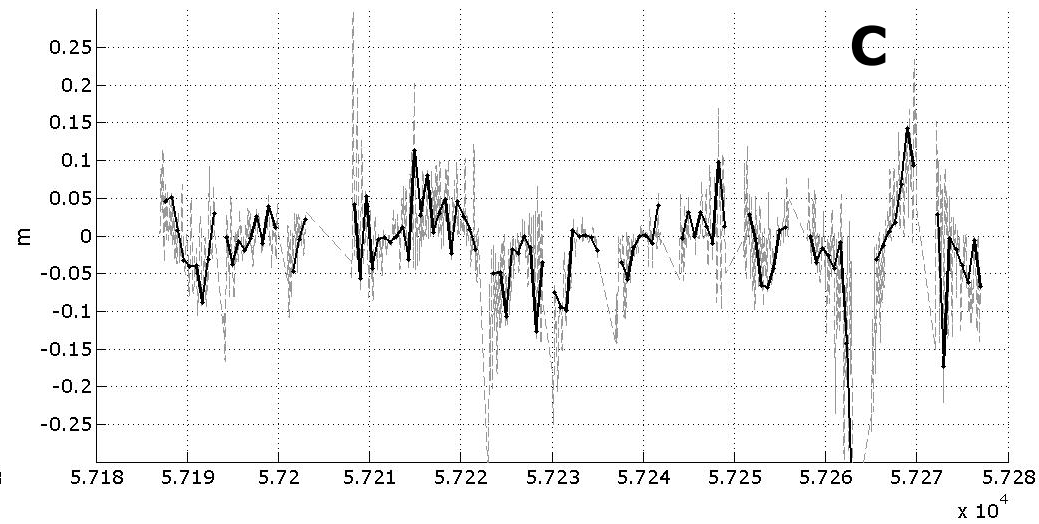
L54 ACs vs Combination

Test combination for L54 using ASI, ESA, **NSGF**

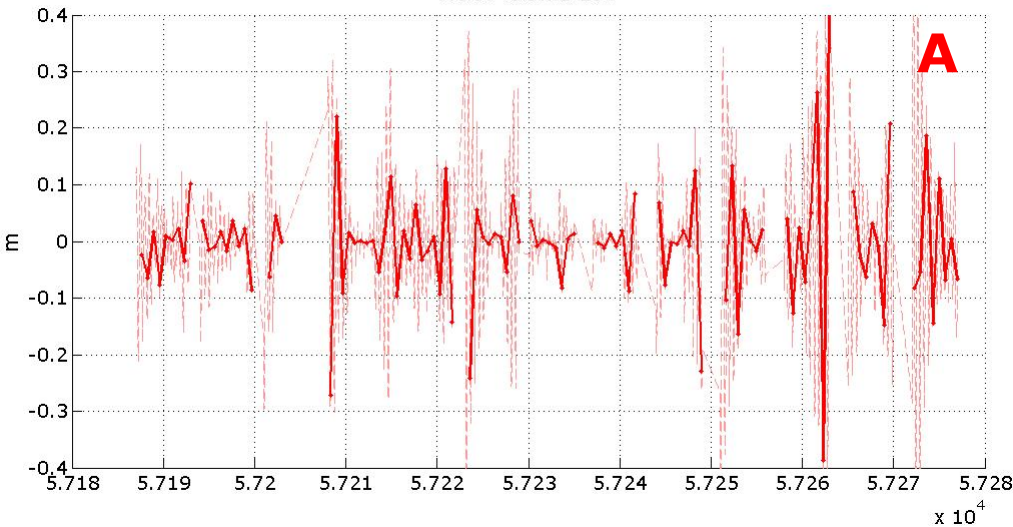
NSGF-COMB L54



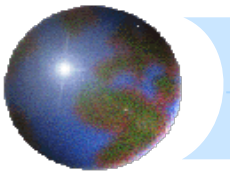
NSGF-COMB L54



NSGF-COMB L54



	MEAN [mm]	STD [mm]
R	0.5	20.2
A	6.6	119.0
C	-10.6	72.0



Next steps

- Check JCET and GRGS orbit solutions;
- Produce weekly combined orbit files;
- Produce sum files;
- Evaluate the quality and stability of this solution.

DGFI AC Report

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Munich

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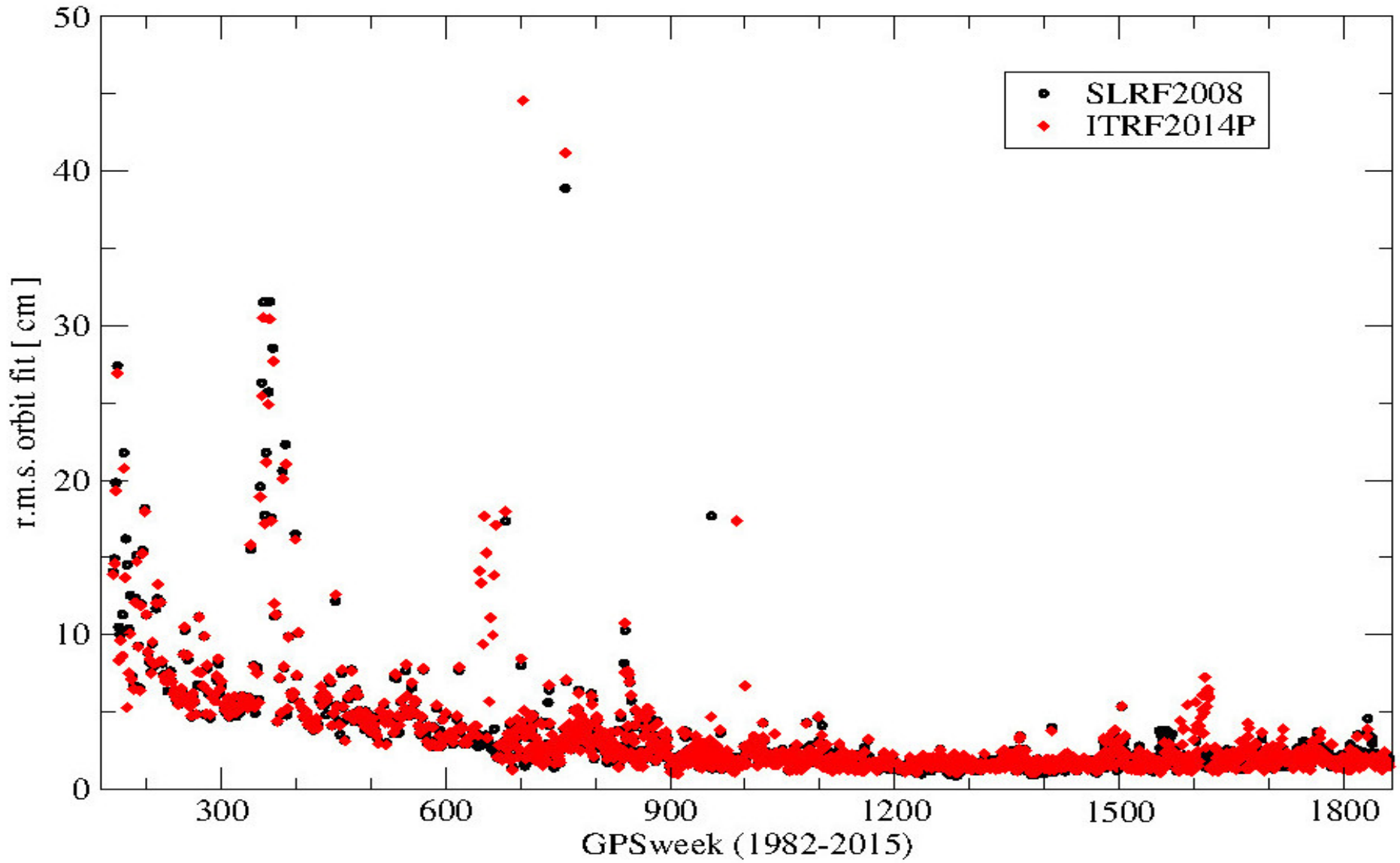
DGFI contribution ITRF2014P evaluation

- Version v70 delivered October 09 2014, updated Oct. 12
- ITRF2014P stations coordinates with non linear station velocities
 - Weekly sinex files from 2009 to 2015
 - Using fixed ITRF2014P station coordinates to compute orbit from 1983 to 2015
 - Comparison with the same orbit processed using SLRF2008

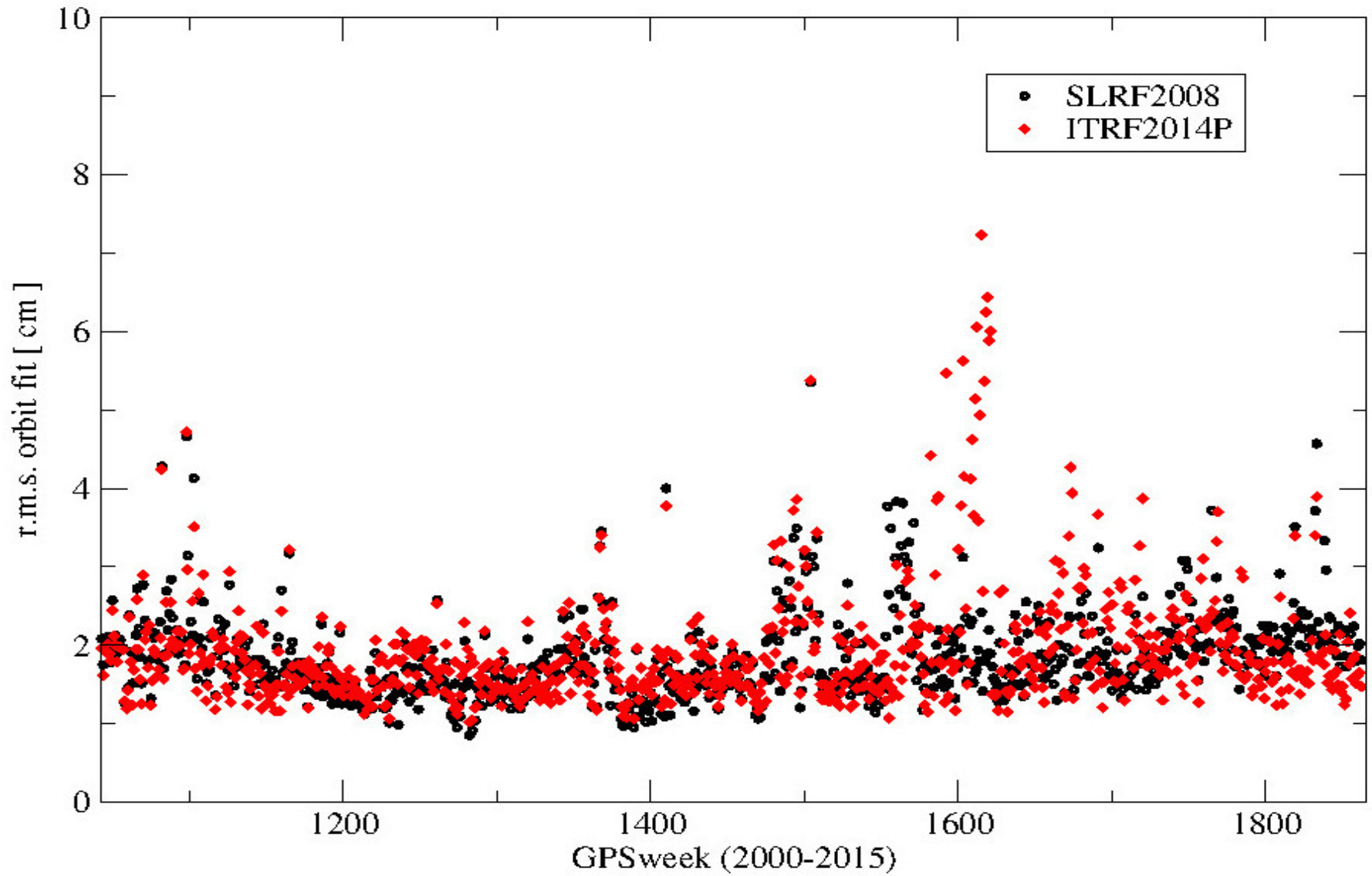
ITRF2014P evaluation

- Processing of Lageos arcs with fixed coordinates (including non linear station velocities)
 - Same input as for delivered sinex files
 - ITRF2014P is generally better than SLRF2008
 - Only Problems in GPSweeks 1580 1620 with Concepcion
 - ITRF2014P coordinates produce
- Main difference 20 weeks after the earthquake in Chile 2010
- Mean r.m.s. orbit fit: Lageos1: (1983-2015) 3.17 +- 3.37 3.02 +- 3.14
(2000-2015) 1.92 +- 0.74 1.84 +- 0.54
Lageos2: (1993-2015) 2.23 +- 1.17 2.14 +- 0.95

ITRF2014P evaluation



ITRF2014P evaluation



Data Handling File Update

Regular update if necessary:

Last update: Sep 30 2015, new stations

Comment block contains reason for update

ILRS AWG meeting ESOC status

T. Springer, C. Flohrer,
R. Zandbergen, W. Enderle
Matera, Italy 24-10-2015

- Routine ILRS solutions:
 - Weekly solutions (V35)
 - Daily rapid solutions (V130)
- Were also are a full analysis centre for the IDS and IGS
 - IGS: Final, Rapid, Ultra-rapid, and real-time
 - IDS: Final solutions
- Reprocessing for ILRS, IGS, and IDS becoming almost “routine”
- Initial developments for becoming an IVS analysis centre

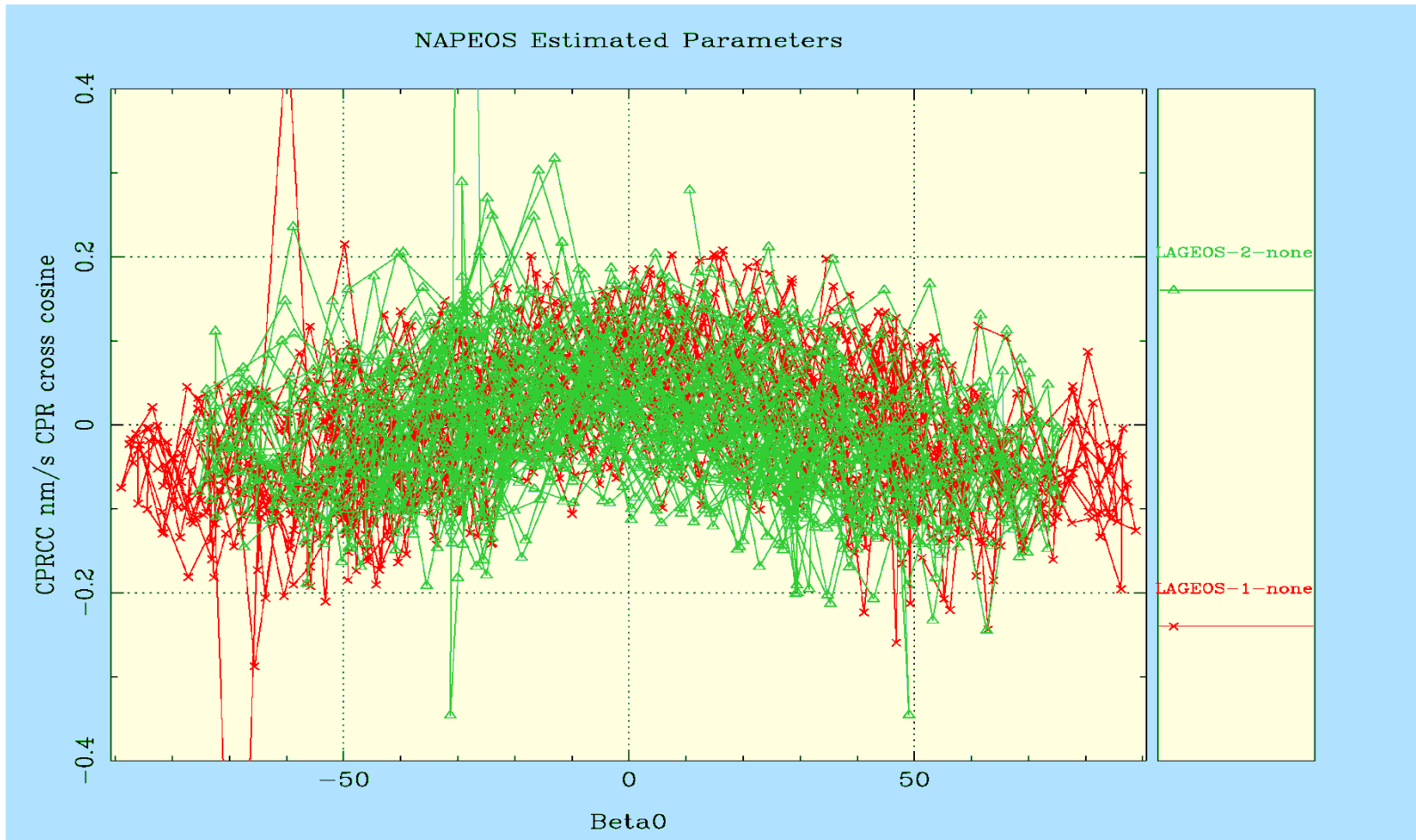
- Build in the handling of the Post Seismic Displacements (PSD) functions
- Reprocessed 1983 to 2015 because all results were lost due to disk crash (for ITRF2014P 1993 to 2015 used)
 - Reprocessed first using “old” setup (input for ITRF2014)
 - Reprocessed second time with ITRF2014P without PSD
 - Reprocessed third time with ITRF2014P with PSD
 - Results submitted last Thursday including a short document with our first impressions
- Further ITRF2014P evaluation plans:
 - Use for IDS and IGS reprocessing
 - Use for ILRS reprocessing for 1983 to 1992 timeframe
 - In this scope add missing stations to ESOC processing

- For reprocessing some improvements were made to our processing
 - Station specific weights
 - Handling of data issues (biases, exclusions) based on input SINEX
 - These improvements will become part of our routine processing when we switch to the ITRF2014
- Updated AC analysis description file send to ILRS and also description included in SINEX
- Need to add some missing stations (mainly the “recent” Russian stations)
 - We have made a software improvement allowing us to detect that there are stations in the tracking data which are not in our database, this feature was lacking
 - Stations will be added when switching to ITRF2014

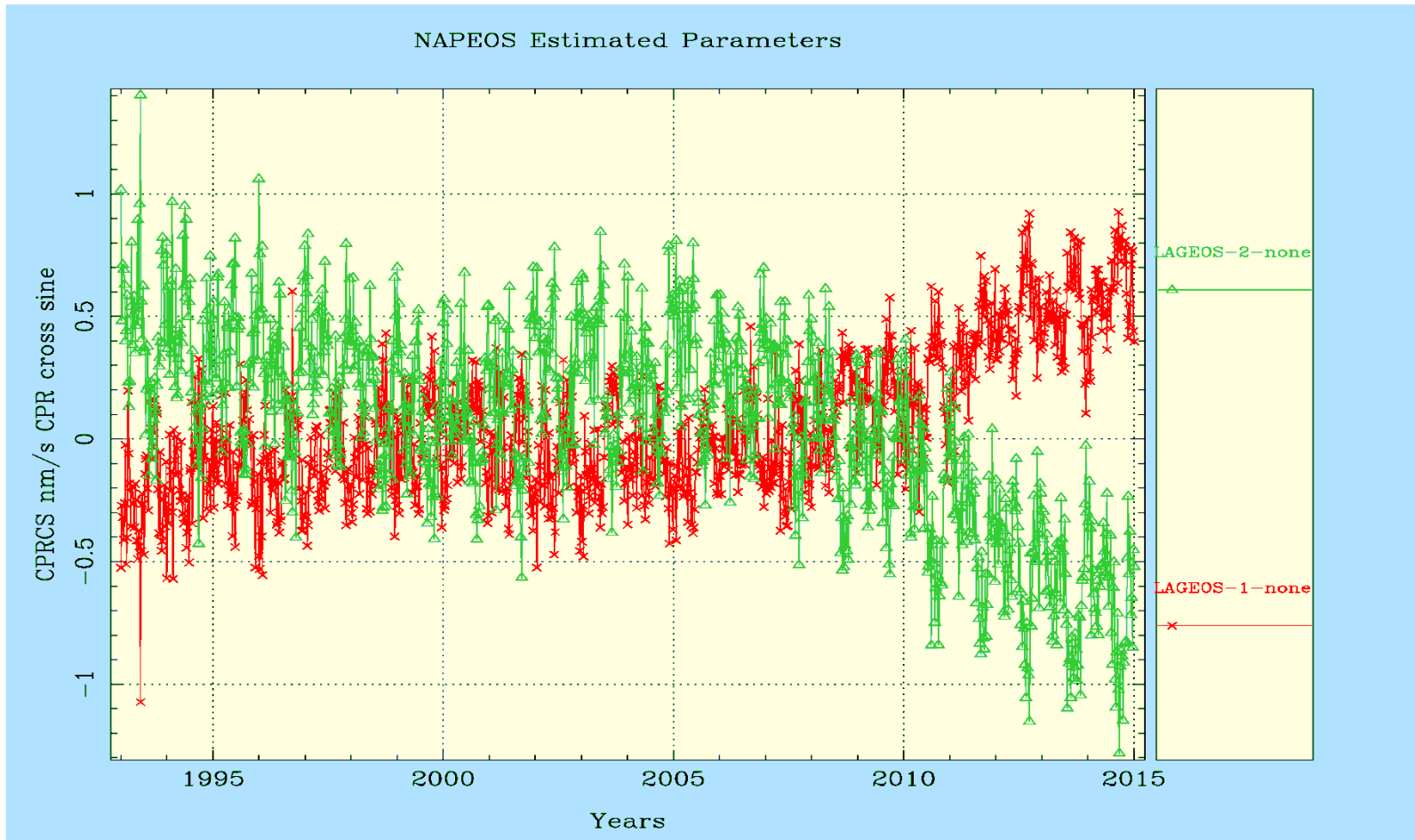
- Reprocessing Specials:
 - Mean pole handling
 - Software modification needed to make this fully automatic
 - C20, C21 and S21 coefficients
 - Software modification needed to make this fully automatic
- In both cases main issues that need to be defined:
 - Location of the input files
 - Format of the input files
 - Availability, accessibility and reliability have to be very good!

- Continue ITRF2014P evaluation
 - Using GNSS and DORIS
- Detailed analysis of our reprocessing time series
 - Station: coordinates, biases, residuals
 - Satellite: SRP parameter, CPR parameters
- Use of ETALON to get a better understanding of and handle on the SRP environment for the GNSS satellites in general and GLONASS in particular
- Interesting signals in the time series of the satellite dynamical parameters
 - Following slides show two examples
 - Most likely caused by the known thermal/rotation effects

LAGEOS Cross-track cosine term



LAGEOS Cross-track sine term



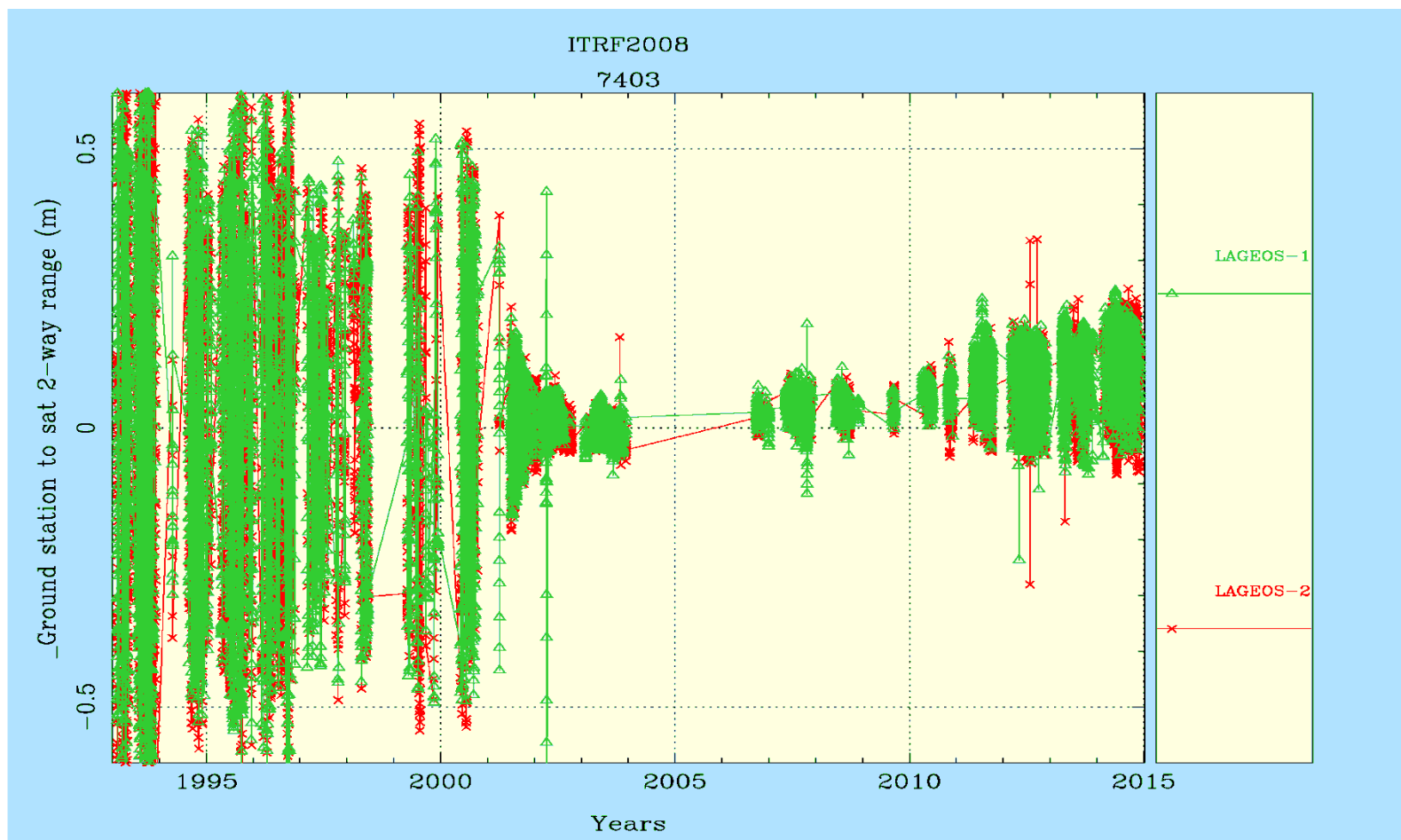
- ESA/ESOC very interested in SLR data
 - Efforts in our group are increasing
 - Focus still strongly on GNSS and ESA missions but SLR is getting more interest
- Will continue our ITRF2014P evaluation
 - Possibly some issues with the PSD functions
 - Could still be an implementation issue on our side
 - Need to do IGS/GNSS and IDS/DORIS analysis

ITRF2014P Evaluation

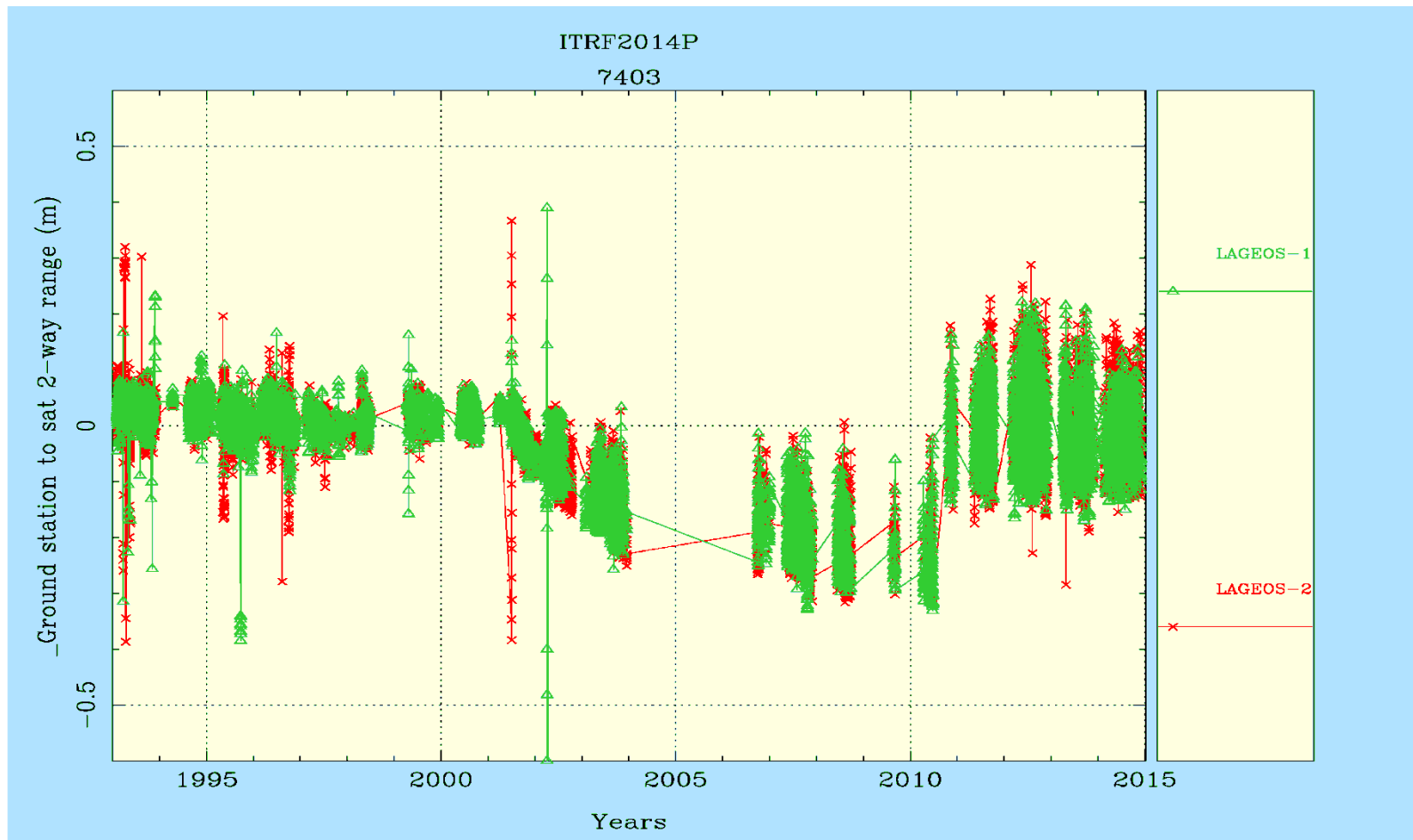
Tim Springer

- For 10 ILRS stations PSD functions are included in the ITRF2014P
- We have implemented the PSD functions in our software
- Cross checked with the examples as provided by Zuheir
- Validation based on our ILRS reprocessing
- In one of the steps of our ILRS reprocessing we keep the station positions fixed. The residuals from this run we have used as one of the means to further validate the PSD functions
 - For 8 out of 10 stations the residual RMS went down significantly.
 - For 2 stations (7403 and 7405) a significant increase is observed and for 7403 even a clear signal appears in the residuals
- For 7405 (CONZ) we observe an increase of the residuals over time which indicates that the station position accuracy may be degrading over time
- For 7403 (AREQ) the situation is more interesting, see next slides....

7403 (AREQ) PSD Issue?



7403 (AREQ) PSD Issue?



- ITRF2008 solution
 - Incorrect coordinates used before 2001, consequently large residuals, due to an error in our set-up
 - From 2001 to 2015 one set of coordinates and velocities used which seemed to work OK, but the residuals are growing!
- ITRF2014P solution:
 - Period before 2001 looks fine! But 2001 to 2010/Sep not good
 - After 2010/Sept looks good
 - But note: from 2010/Sept Range bias estimated for 7403!
 - Average value of bias -43 mm
 - But also here residuals growing over time...

7403 (AREQ) Discontinuities



7403 A 1 L 00:000:00000 94:160:01996 P - EQ (PR)
7403 A 2 L 94:160:01996 96:317:61184 P - EQ (PR)
7403 A 3 L 96:317:61184 01:174:73994 P - EQ (PR)
7403 A 4 L 01:174:73994 01:188:34724 P - EQ (PR)
7403 A 5 L 01:188:34724 07:227:85258 P - EQ (PR)
7403 A 6 L 07:227:85258 14:091:85607 P - EQ (PR)
7403 A 7 L 14:091:85607 00:000:00000 P - (PR)
7403 A 1 L 00:000:00000 00:000:00000 V - (PR)

42202M003	7403	GPS 7403	1	1942808.274	-5804069.671	-1796915.273	0.004	0.004	0.004	I
42202M003				0.0125	0.0021	0.0147	0.000	0.000	0.000	I
42202M003	7403	GPS 7403	2	1942808.280	-5804069.678	-1796915.271	0.004	0.003	0.003	I
42202M003				0.0125	0.0021	0.0147	0.000	0.000	0.000	I
42202M003	7403	GPS 7403	3	1942808.274	-5804069.683	-1796915.272	0.003	0.002	0.002	I
42202M003				0.0125	0.0021	0.0147	0.000	0.000	0.000	I
42202M003	7403	GPS 7403	4	1942807.835	-5804069.713	-1796915.559	0.034	0.018	0.025	I
42202M003				0.0125	0.0021	0.0147	0.000	0.000	0.000	I
42202M003	7403	GPS 7403	5	1942807.800	-5804069.709	-1796915.592	0.002	0.001	0.002	I
42202M003				0.0125	0.0021	0.0147	0.000	0.000	0.000	I
42202M003	7403	GPS 7403	6	1942807.793	-5804069.714	-1796915.599	0.001	0.001	0.001	I
42202M003				0.0125	0.0021	0.0147	0.000	0.000	0.000	I
42202M003	7403	GPS 7403	7	1942807.797	-5804069.726	-1796915.609	0.003	0.005	0.003	I
42202M003				0.0125	0.0021	0.0147	0.000	0.000	0.000	I

7403 (AREQ) PSD Issue?



- Results before 2001 improved significantly
 - Due to error in our 2008 set-up we used incorrect coordinates and velocities
- Results after 2001 seem to be worse
 - Our 2008 set-up used only a single position and velocity vector for the period and seemed to perform OK, but residuals are increasing over time indicating some issue with the accuracy of the station position/velocity
 - The ITRF2014P set-up uses 4 position vectors and 1 velocity vector from 2001 and two PSD functions. Clear signal shows up in our residuals. After 2010 the signal disappears due to the estimation of a (weekly) range bias
- Conclusions
 - Handling 7403 using just a single position and velocity vector of the SLR2008 worked better than handling the station with the current ITRF2014P set-up!
 - We will carefully validate the AREQ station in our IGS/GNSS analysis and see if something similar may be observed there. If for the GNSS analysis things are fine the issue must be with the SLR data. If something similar is observed for IGS/GNSS it must be an ITRF2014P issue.

ITRF2014P Evaluation

T.A. Springer

European Space Operations Centre, Darmstadt, Germany

1 Comments

1.1 Introduction

Below some comments regarding the ITRF2014P based on the experience gathered with the implementation into the NAPEOS software and the evaluation of the results. I have two main comments. Firstly, the equation given for the station position over time is incomplete. On first glance this is just a minor issue but on second glance it actually reflects the fundamental difference of the ITRF2014 w.r.t. previous ITRF releases. And this aspect does (did) have a significant impact when implementing the ITRF2014P into our software.

Below we first discuss the issue of the incomplete equation. This is followed by a discussion of the more fundamental change (or should we say issue or even problem?) we noticed in this ITRF2014P.

1.2 Equation problem

The equation (1) as given in the document ITRF2014P-psd-model-eqs-IGN.pdf is obviously not completely correct. It is given as:

$$X(t) = X(t_0) + \dot{X}(t - t_0) + \delta X_{psd}(t) \quad (1)$$

This, however, would mean that for $t = t_0$ we get:

$$X(t_0) = X(t_0) + \delta X_{psd}(t_0)$$

Which clearly leads to the contradiction that $X(t_0) \neq X(t_0)$. So the correct equation, also making it more similar to the way the velocity is handled, seems to be:

$$X(t) = X(t_0) + \dot{X}(t - t_0) + \delta X_{psd}(t) - \delta X_{psd}(t_0) \quad (2)$$

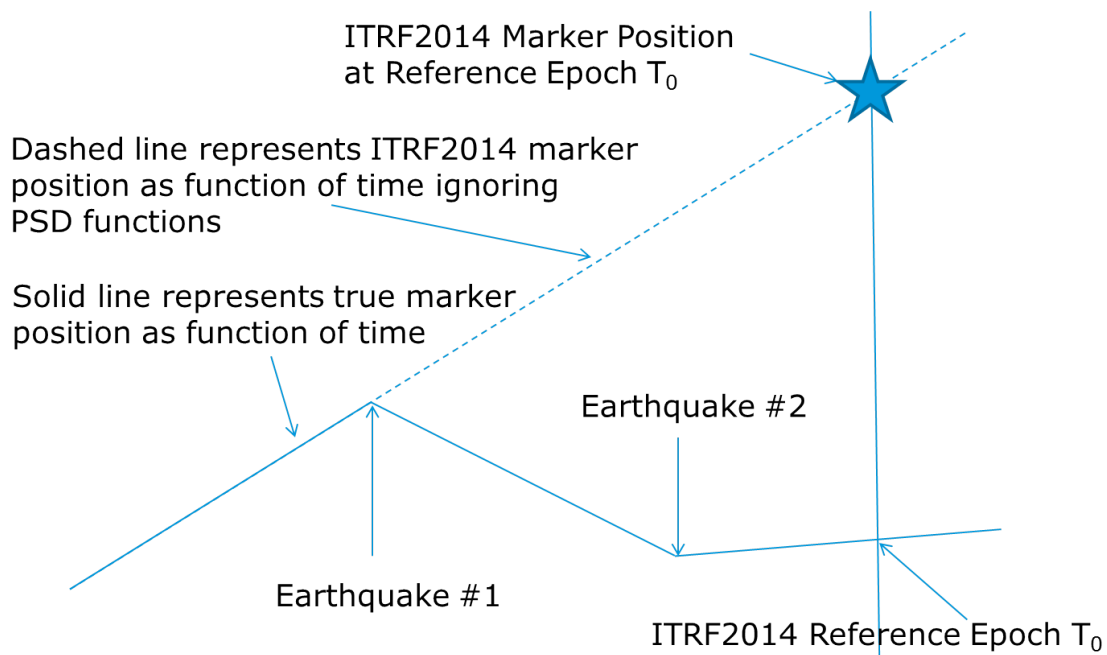


Figure 1: Example of station position evolution over time with earthquakes

With this equation we then also get the correct answer for $t = t_0$, namely:

$$X(t_0) = X(t_0)$$

However, is this really correct now!? The discussion below will show that this equation does not deliver what we (may) want!

1.3 Fundamental Change

With the introduction of the post seismic deformation (PSD) functions there is a fundamental change in the ITRF namely that the coordinates as given in the ITRF SINEX file are no longer necessarily close to the actual physical location of the marker. Differences in the order of meters are present, but only for Earthquake sites, i.e. sites for which PSD functions are given. The reason for this is illustrated in figure 1.

Figure 1 shows the schematic time evolution of an fictious station suffering from two earthquakes. The way the ITRF2014 represents such a station is by estimating:

- At least one station position vector, but more likely three
- One single velocity vector

- Two PSD functions, one valid from the time of Earthquake #1 and a second one valid from the time of Earthquake #2

As a consequence the estimated velocity vector will be based solely on the time series of the station until the first Earthquake. From the first Earthquake any deviation from the estimated velocity vector will be absorbed (modeled) by the estimated PSD function. And after Earthquake 2 the PSD function #2 will reflect the velocity difference compare to the velocity given by the velocity vector and PSD function #1. As a consequence the marker position as given in the ITRF2014 SINEX may deviate significantly from the actual physical location. With figure 1 I have tried to schematically reflect what is going one. In this figure the "star" reflects the marker position as given by the ITRF2014 at its reference epoch (2010.0), the solid line represents the true physical position and the dashed line represent the time evolution of the position based on the ITRF2014 position and velocity but ignoring the PSD functions. The ITRF2014 position, velocity and PSD functions together should (and do) coincide with the solid line of course. So the disturbing issue here is that there may be very significant differences between the location as given in the ITRF2014 SINEX files compare to the true physical location, even at the reference epoch of the ITRF2014. This is not really a problem but it is a completely new feature which may (and I think actually will) surprise many users!

So knowing this lets turn back to our equation 2.

$$X(t) = X(t_0) + \dot{X}(t - t_0) + \delta X_{psd}(t) - \delta X_{psd}(t_0)$$

We already established that for t_0 this will give us the position $X(t_0)$. However, this would give us the location of the "star" in figure 1 whereas we would like to get a point on the solid line. So although our equation is mathematically correct it does not really deliver what it should. The issue is that with the ITRF2014 the $X(t)$ and the $X(t_0)$ have become fundamental different things. The $X(t_0)$ now represent the position of the station on the "dashed" line whereas the $X(t)$ is intended to represent the station position on the solid line. Consequently, the error is by naming these two things the same (X) where they are actually fundamentally different. So we have to define a new variable, lets call it I , and with that we may write:

$$X(t) = I(t_0) + \dot{I}(t - t_0) + \delta I_{psd}(t)$$

Note that the variable I was selected as it both reflects "ITRF" as well as "imaginary" (punn intended).

So essentially with the ITRF2014 we need the following equation to convert ITRF2014 positions to true positions (and visa versa):

$$X(t) = I(t_0) + \dot{I}(t - t_0) + \delta I_{psd}(t) \tag{3}$$

From this equation we may derive the equation to convert a true station position at time t_1 to a true station position at time t_2 , which gives:

$$X(t_2) = X(t_1) + \dot{I}(t_2 - t_1) + \delta I_{psd}(t_2) - \delta I_{psd}(t_1)$$

Although this is all trivial and straight forward, mathematically speaking, this may not be so simple when implementing it into your software. With the new "definition" used for the ITRF2014 we have "gained" and additional complexity in that besides the fact that we have to distinguish between "marker" and "instrument" coordinates we now also have to distinguish between the "true" marker position and the "ITRF" (or "imaginary") marker position. For all people not dealing with software implementation this will not matter but for all the software engineers out there I urge you all to take a careful look at what ITRF2014 is now giving you and how you will handle that in your software... The biggest pitfall being the case where you use your own a priori coordinate set, which are typically "true" coordinates, but then you convert them from "imaginary" to "true" (applying the PSD effect). So you will have to add an identifier to specify what type your coordinates are: "true" or "imaginary" to avoid incorrectly applying the PSD correction(s).

2 Conclusions

We believe to have successfully implemented the ITRF2014P in the ESA/ESOC NAPEOS software. However, the switch from "true" position to "imaginary" did cause significant issues in the implementation and some careful design considerations had to be made. The quality of the ITRF2014P seems to be fine based on rerunning our ILRS reprocessing (1993-2015). As next validation step we will use the ITRF2014P for our IGS reprocessing.

Our main comments/concerns are:

- Fundamental change in that ITRF2014 now provides "imaginary" positions rather than "true" positions, which is particularly important from a software implementation point of view
- The PSD functions do contain a velocity component, the velocity given in the ITRF2014 for earthquake sites reflects only the velocity of the site for the time before the first Earthquake
- For Earthquake sites the coordinates found in the SINEX file for the reference epoch 2010.0 do NOT reflect the true position of the site, the PSD function(s) must be taken into account
- The PSD functions have infinite duration. Would make more sense to only have them valid from earthquake n to earthquake $n+1$.

So although the ITRF2014P may be used in the way it has been distributed I would have preferred it if it would have more closely followed the "old" scheme of providing "true" station positions. Basically for Earthquake sites I would have preferred a "model" that for a station with n earthquakes would consist out of $n+1$ sets of coordinates, velocities, and (where necessary) PSD functions. Each of these three components (coordinate, velocity, and PSD) being valid only for the period between Earthquake n and $n+1$. Of course I am very well aware that the involvement of PSD functions will automatically mean that the given positions become "imaginary" positions rather than "true" positions. But the effect would be much smaller than it is with the current implementation/definition. It would basically be an enhancement of the velocity model from a "constant" velocity model to a higher order model.

Last but not least I would like to state that the significant change in the ITRF "model" should have been communicated well in advance of the (preliminary) release of the ITRF2014. Especially in view of the large delay there was in generating the ITRF2014 there was ample time to provide an example of what was planned. The amount of time given for the evaluation of the ITRF2014 might have been enough if it would just have been a mere change of the coordinate and velocity values, but with the inclusion of the new PSD model the time given was not enough.

AWG GRGS ILRC AC

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and David Coulot^{3,1}

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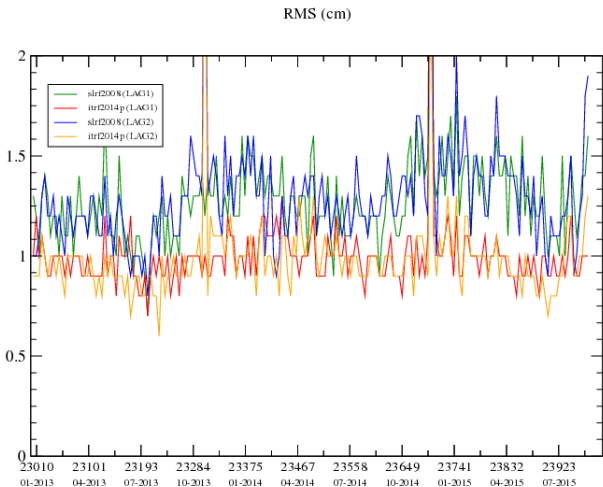
² Centre National d'Etudes Spatiales/GRGS, Toulouse, France

³ IGN/LAREG/GRGS, Université Paris Diderot, Paris, France

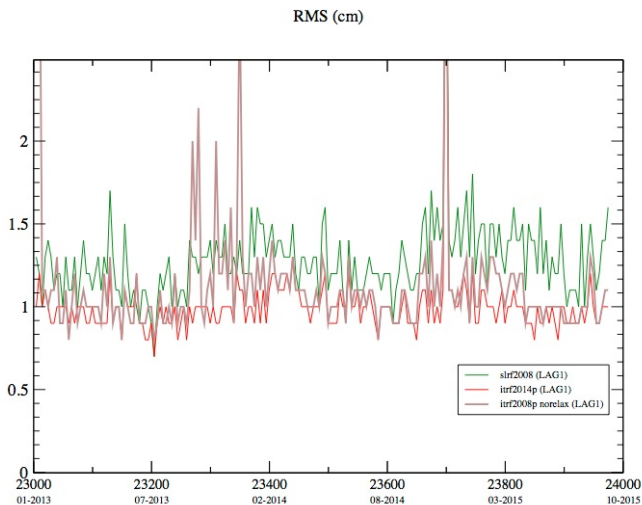
24th October, 2015



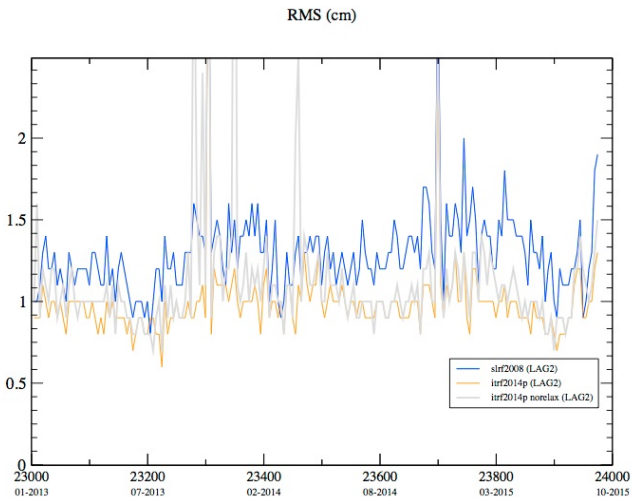
ITRF2008 (SLRF2008) / ITRF2014P: global results



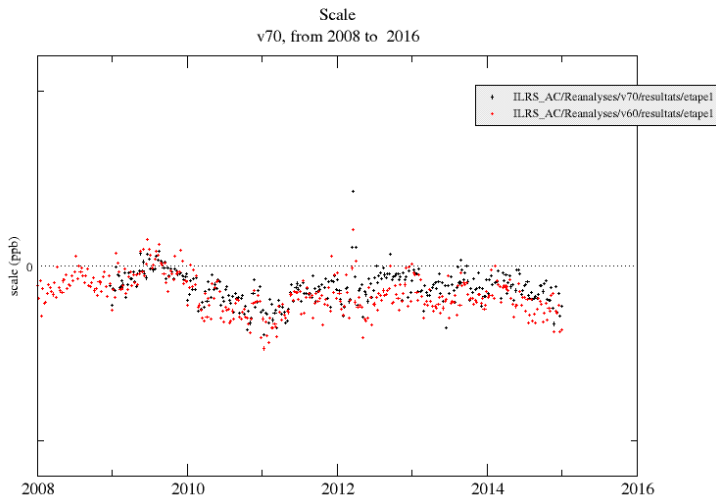
ITRF2008 (SLRF2008) / ITRF2014P: LAG1 w.&w/o PSD



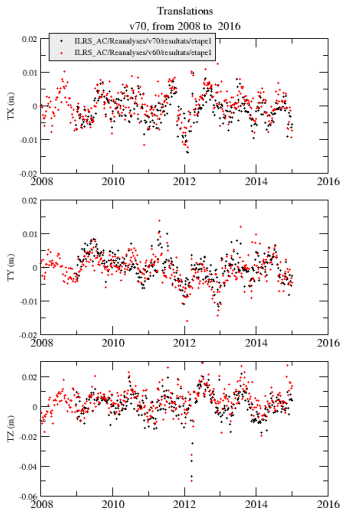
ITRF2008 (SLRF2008) / ITRF2014P: LAG2 w.&w/o PSD



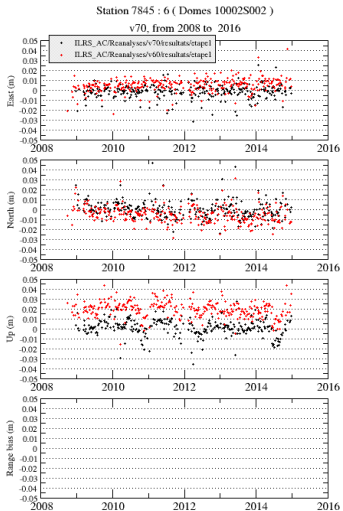
ITRF2008 (SLRF2008) / ITRF2014P: scale



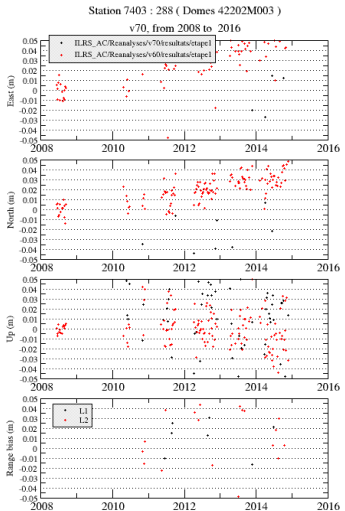
ITRF2008 (SLRF2008) / ITRF2014P: translations

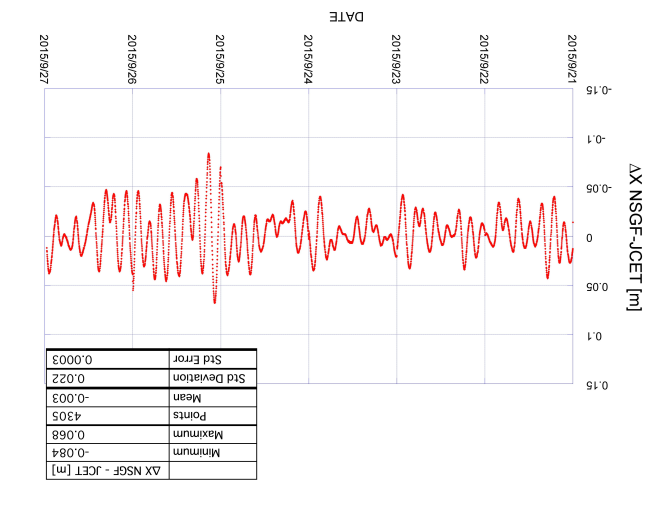
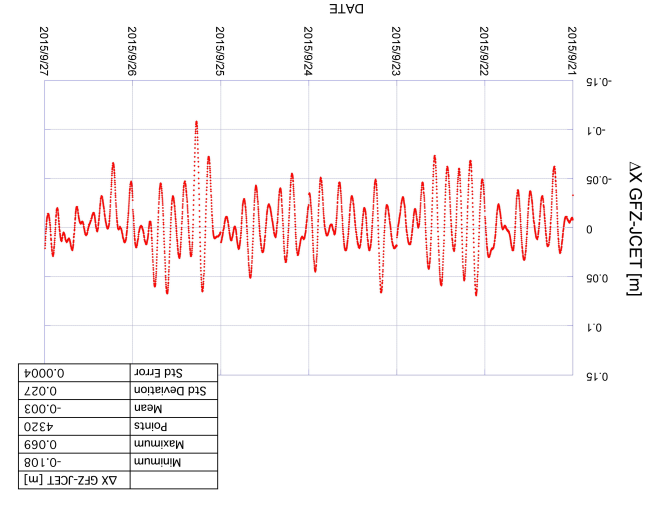
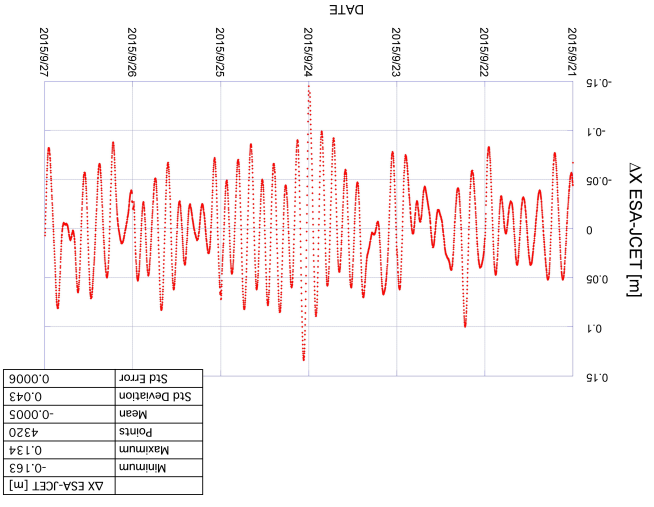
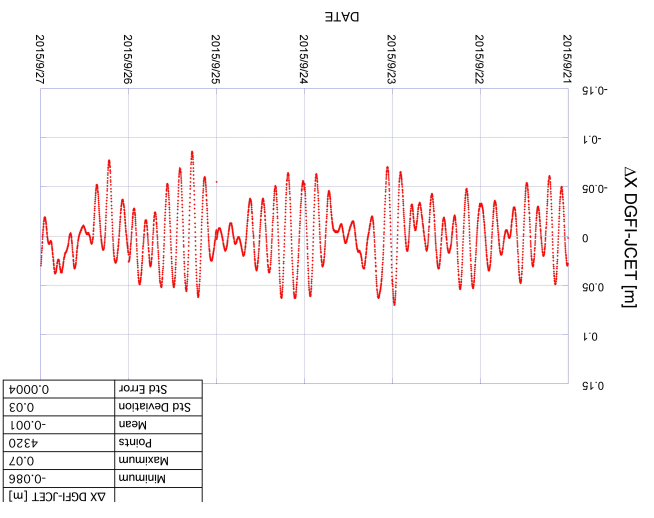
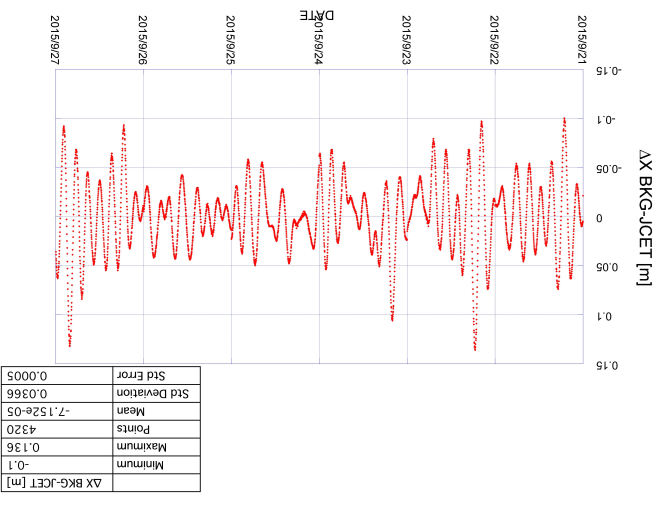
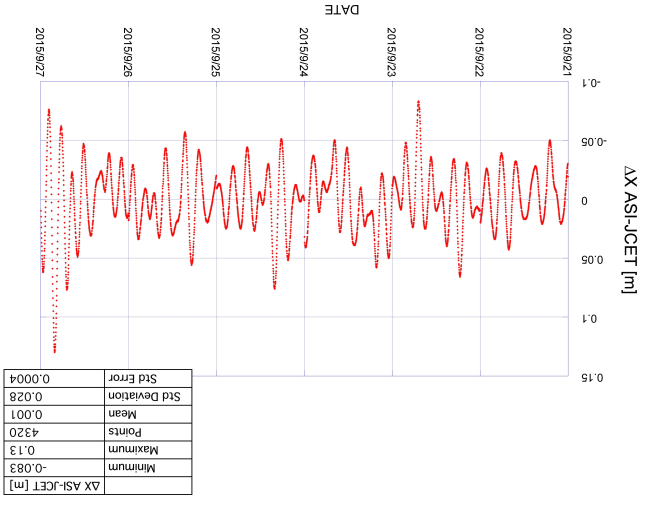


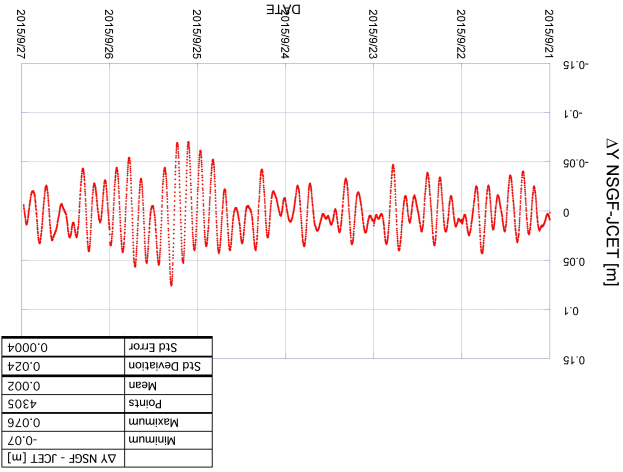
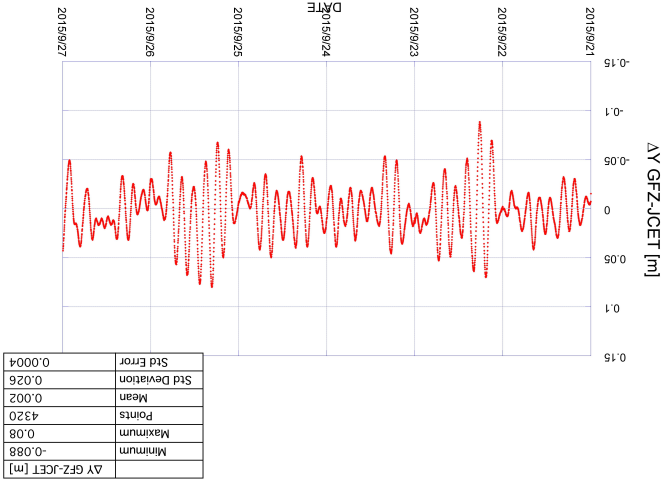
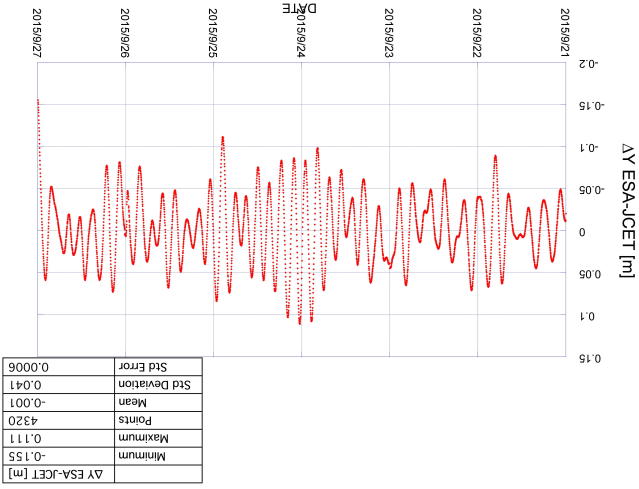
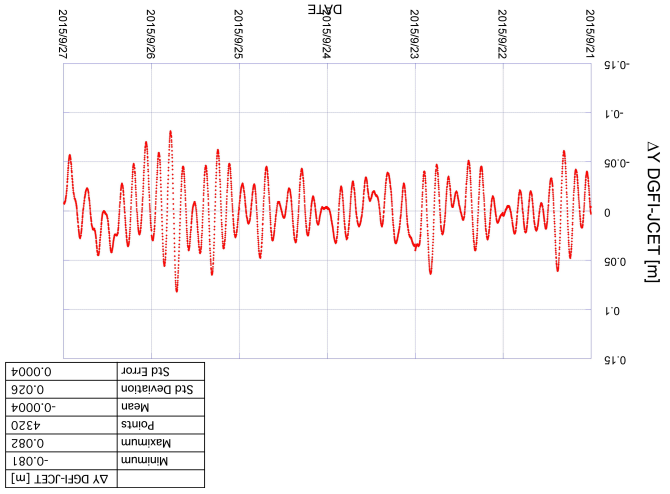
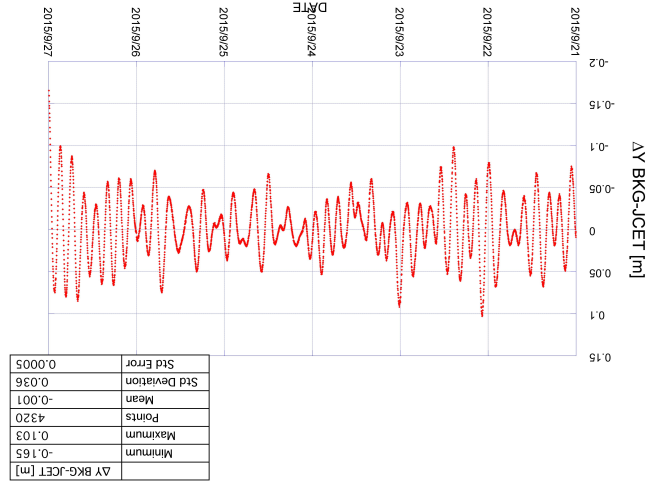
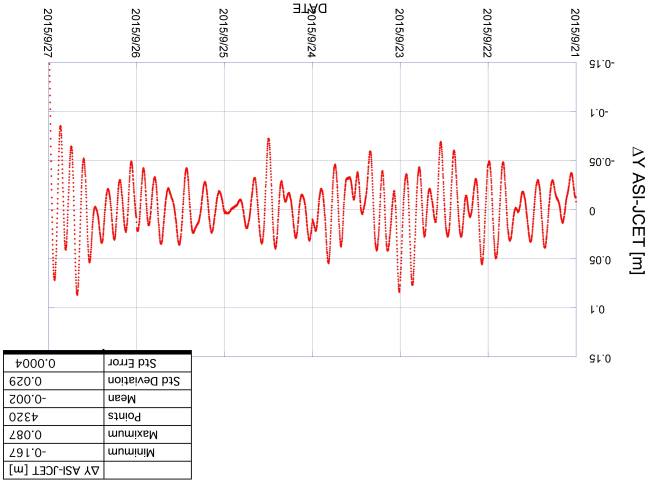
ITRF2008 (SLRF2008) / ITRF2014P: SSC

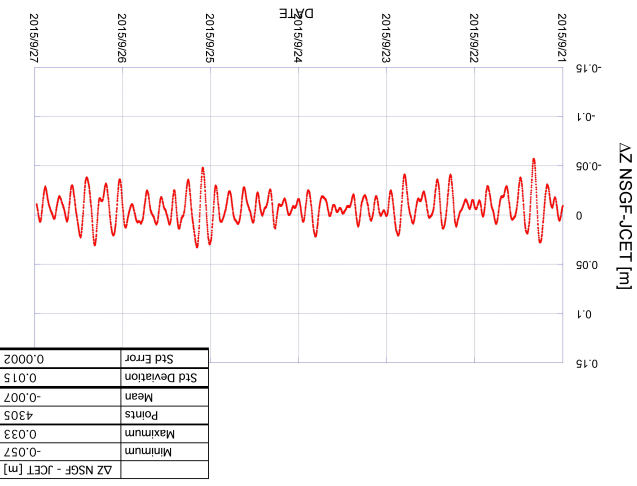
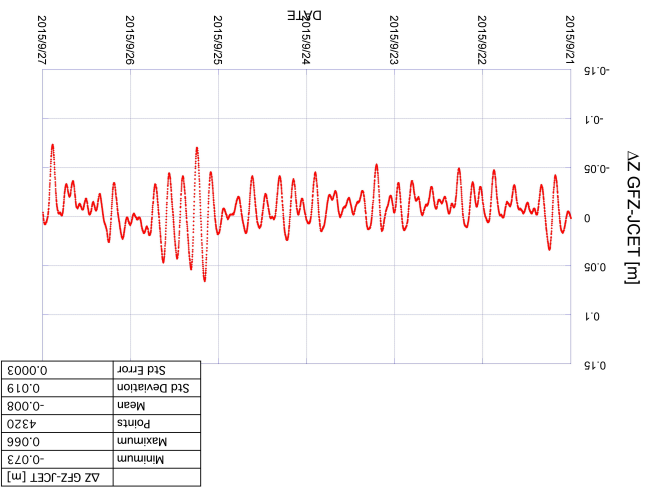
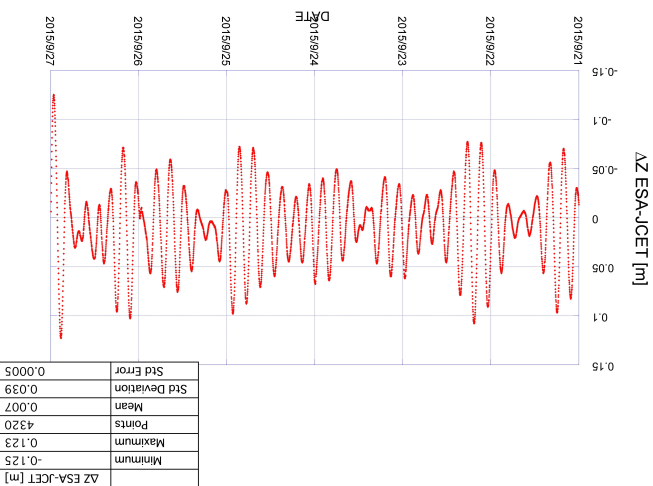
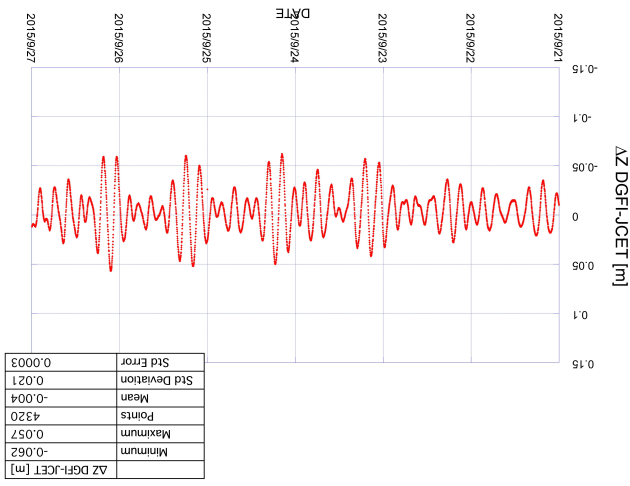
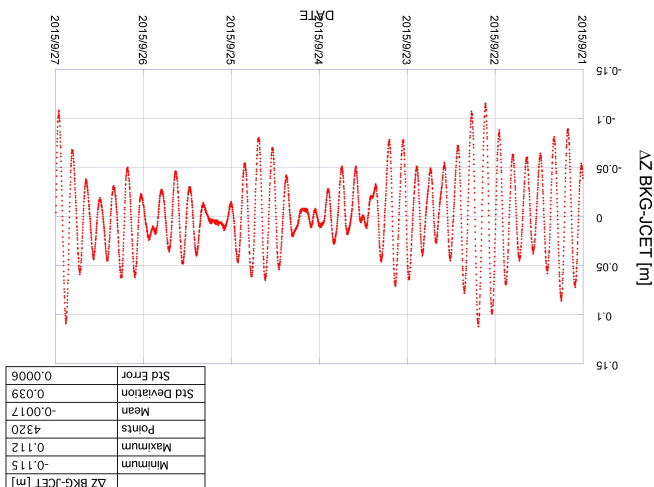
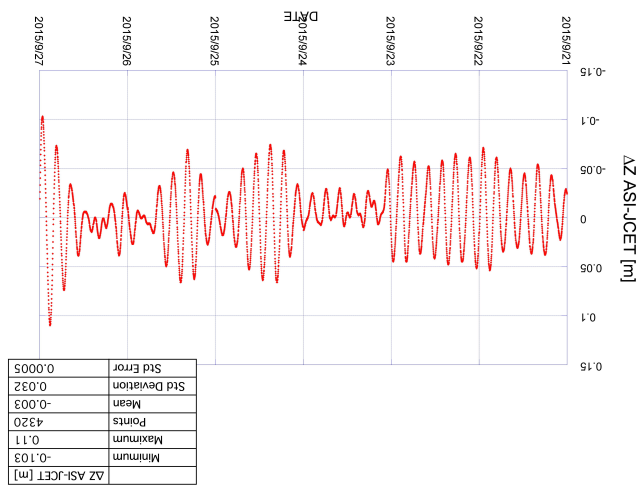


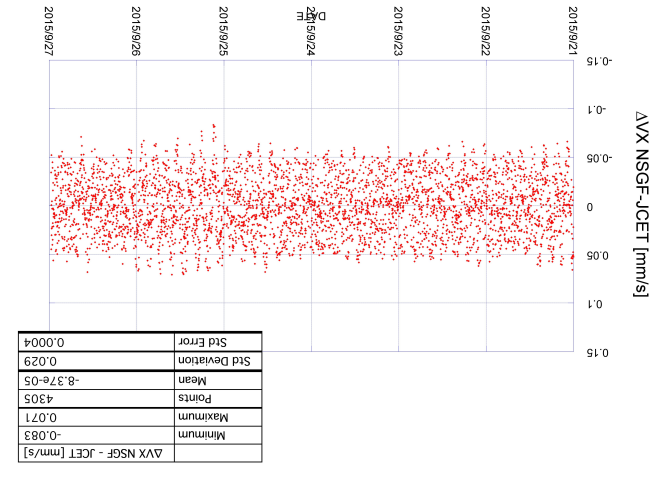
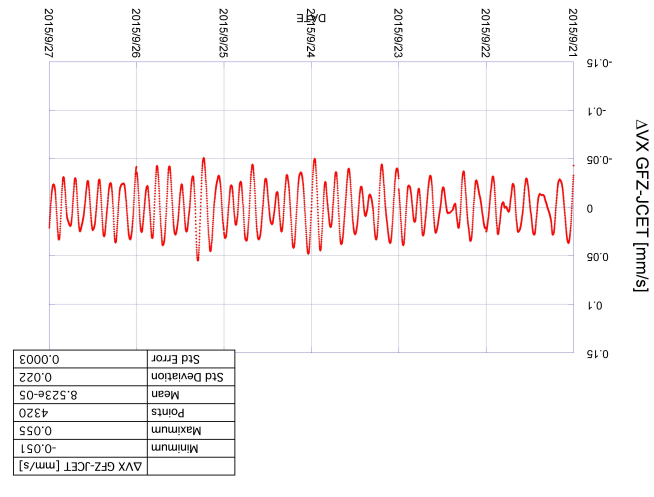
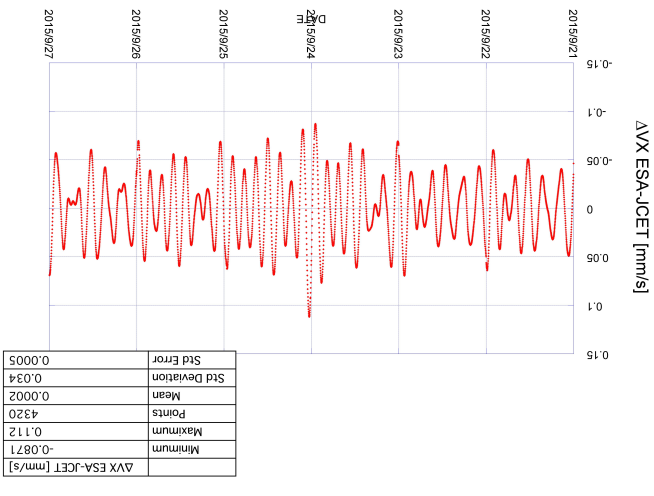
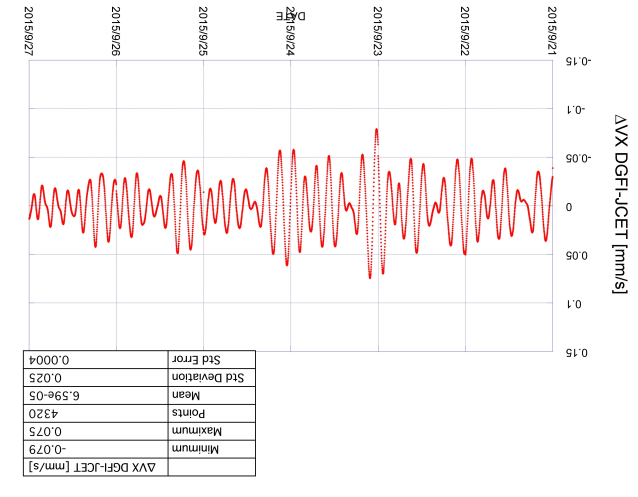
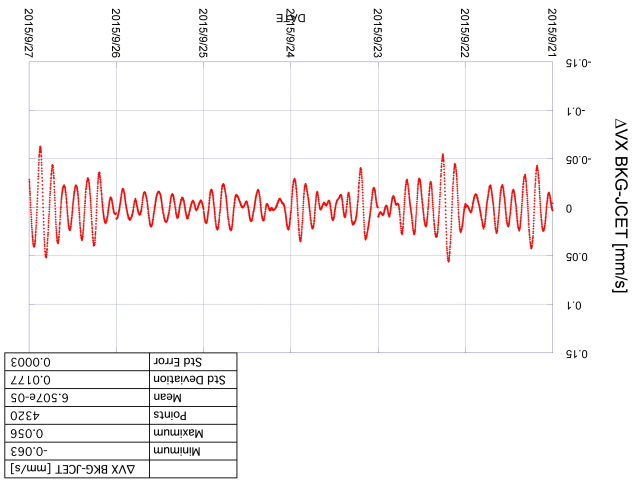
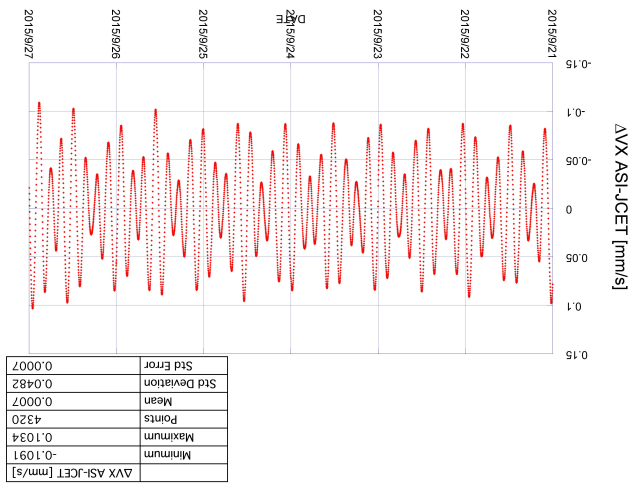
ITRF2008 (SLRF2008) / ITRF2014P: SSC

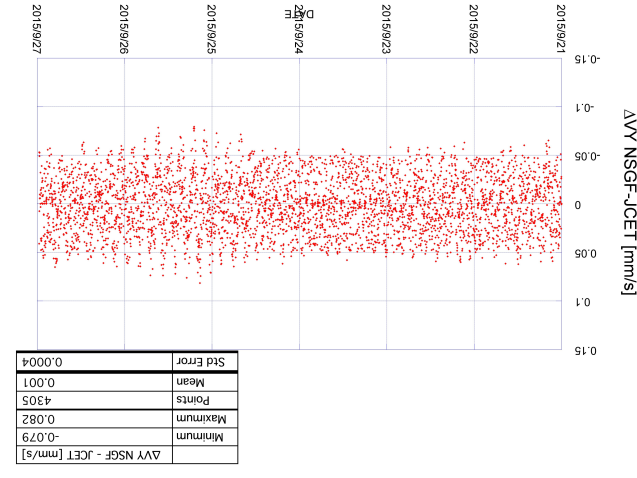
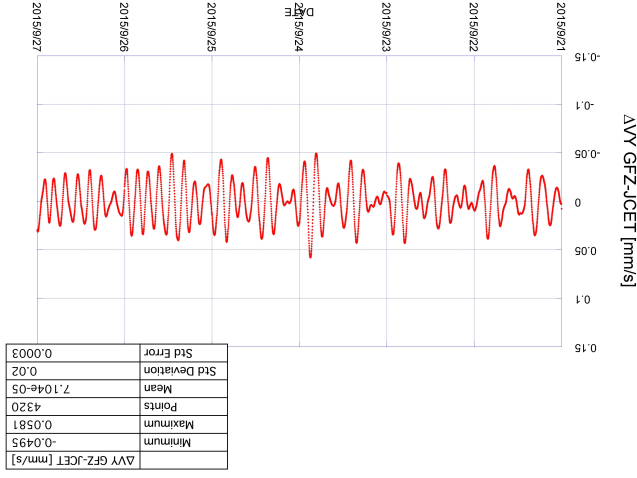
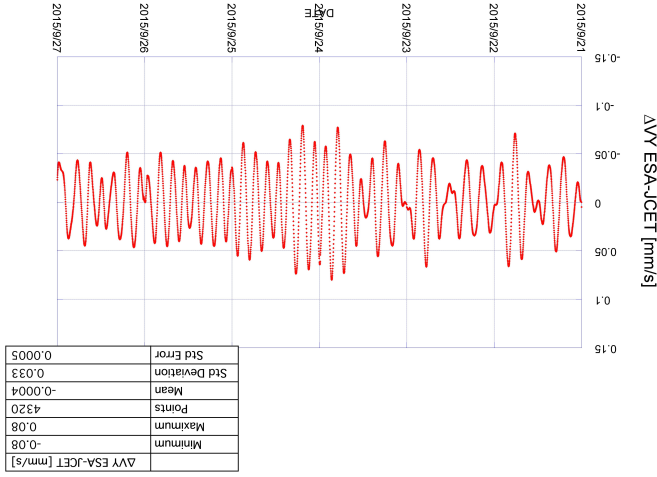
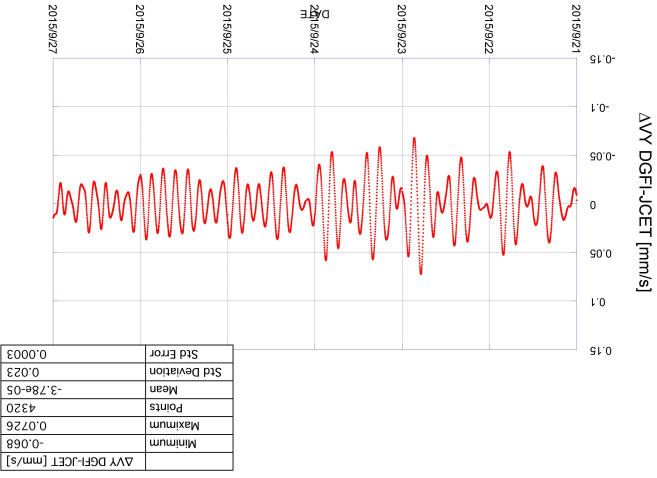
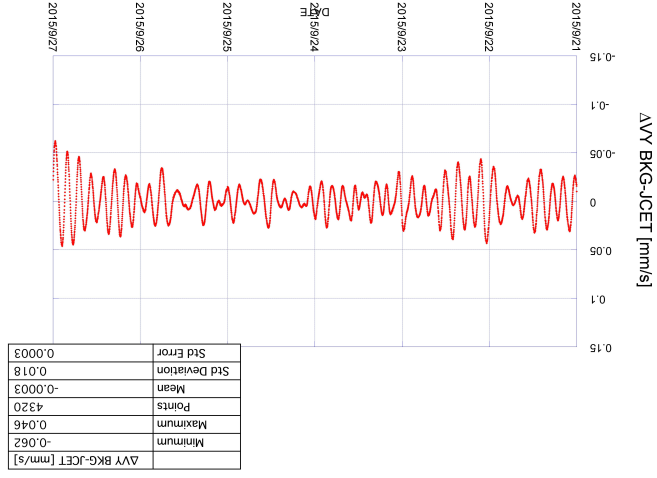
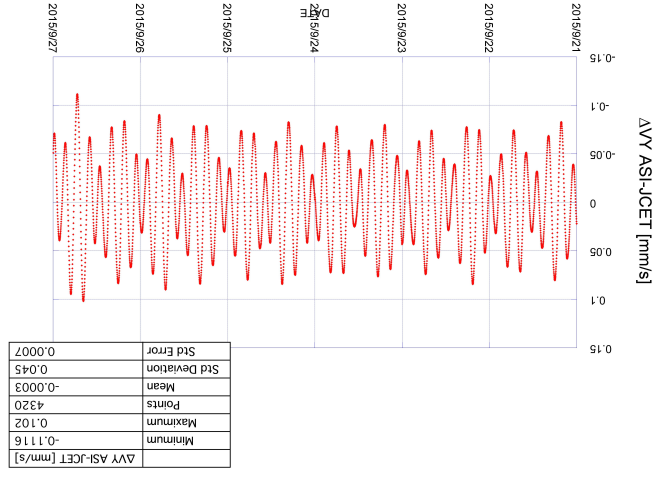


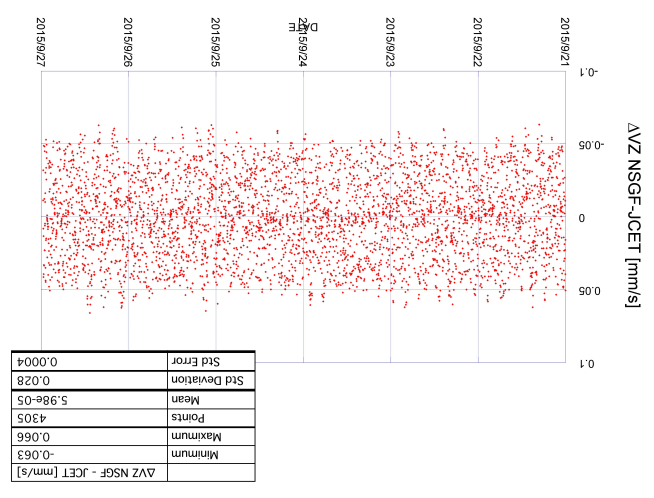
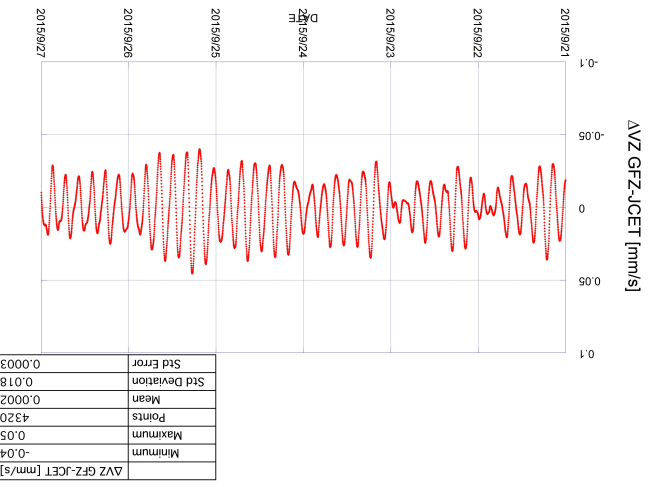
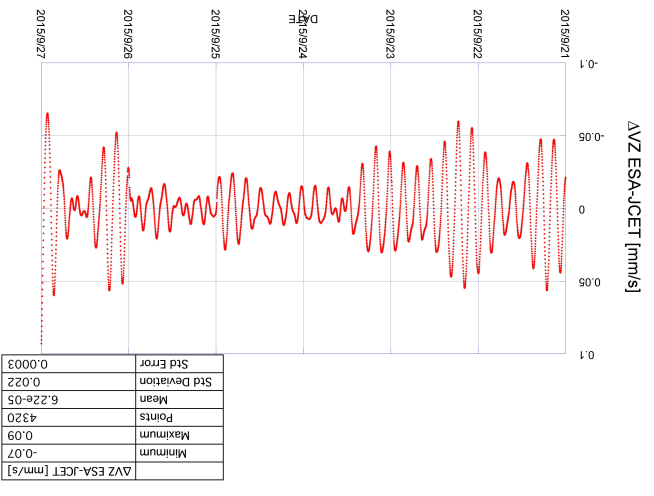
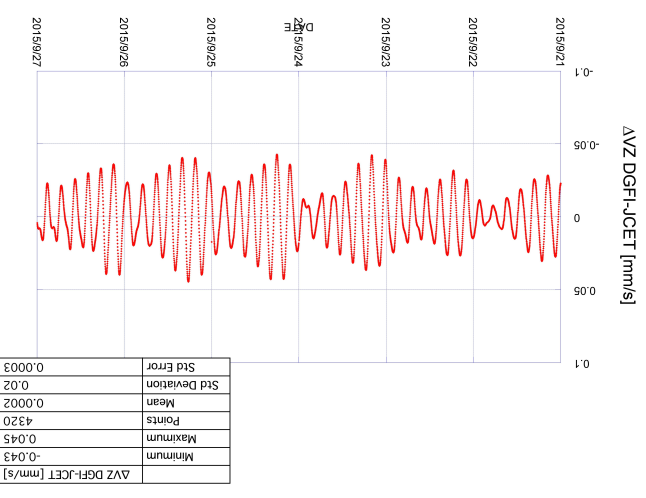
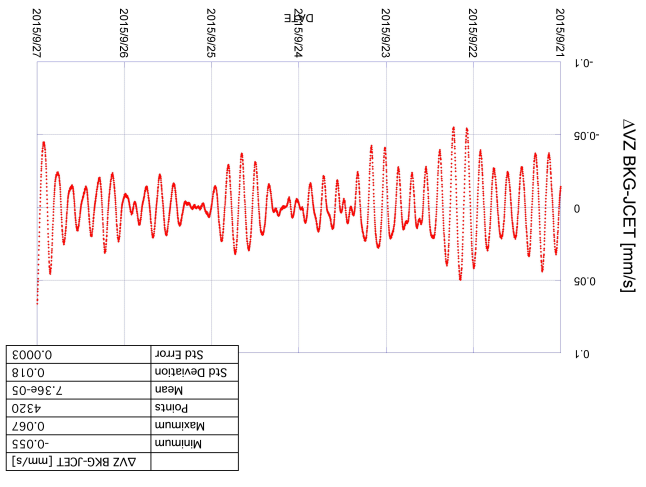
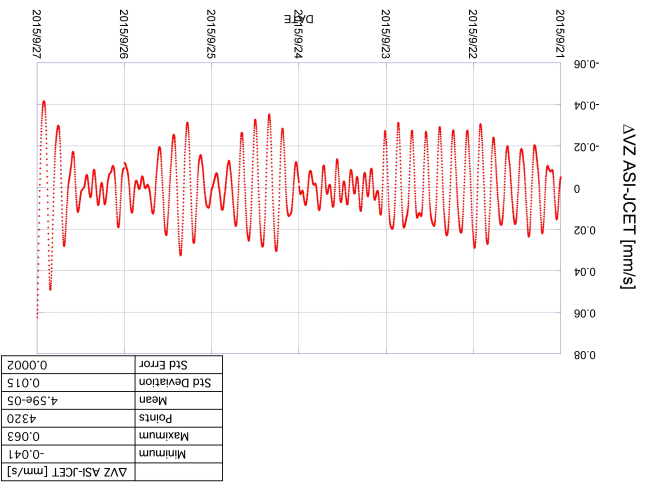


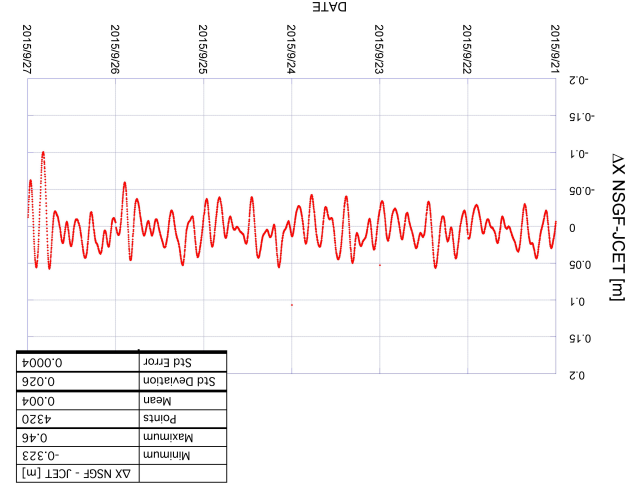
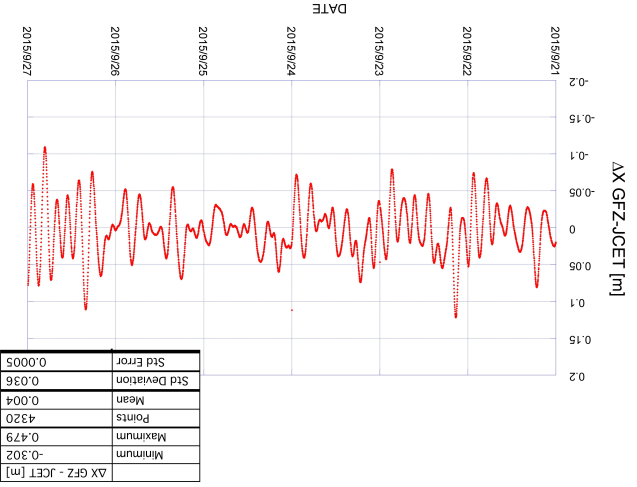
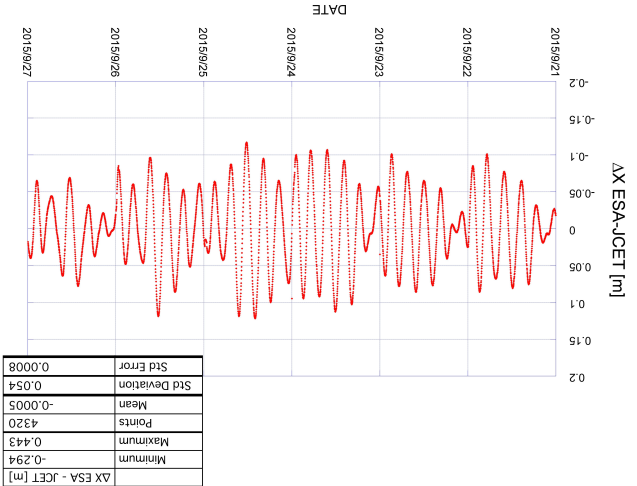
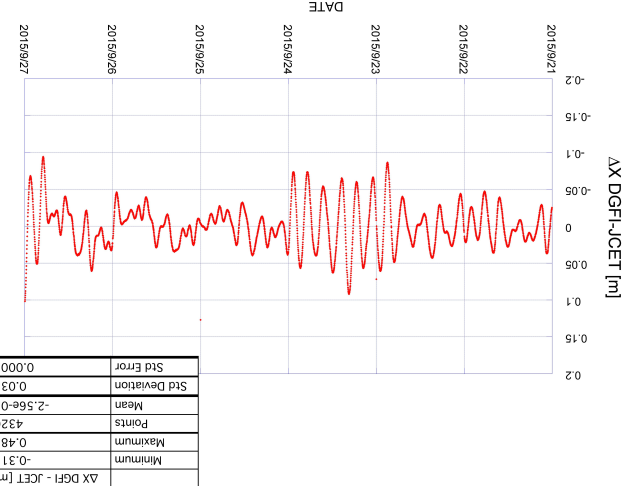
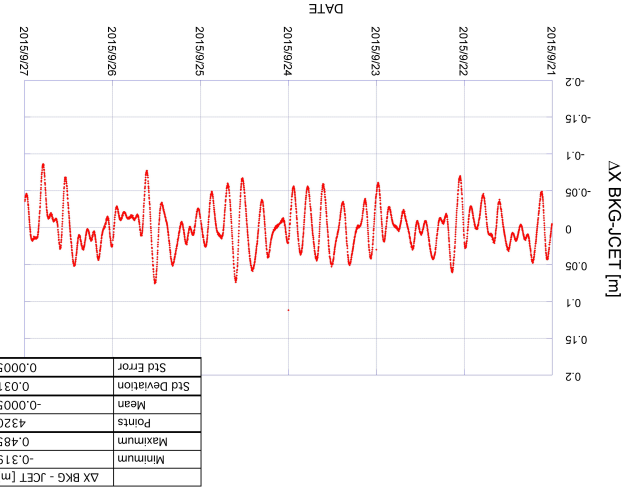
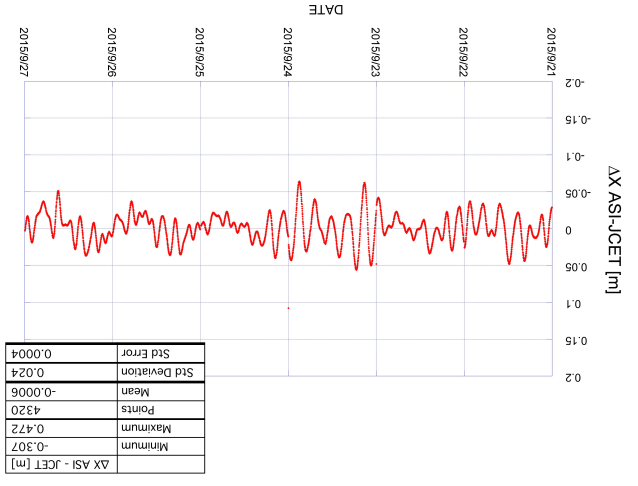


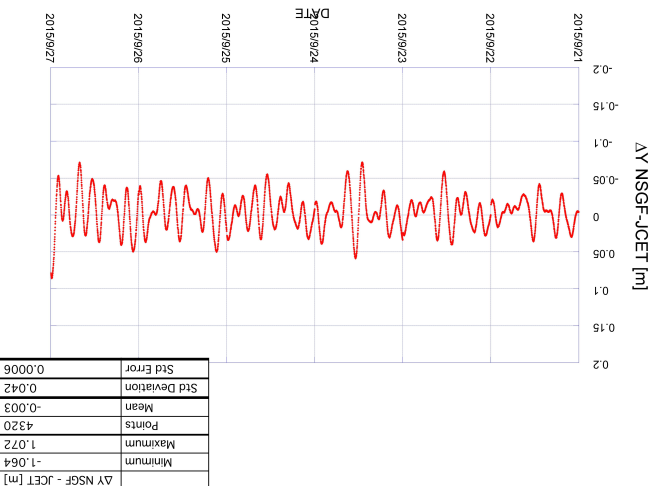
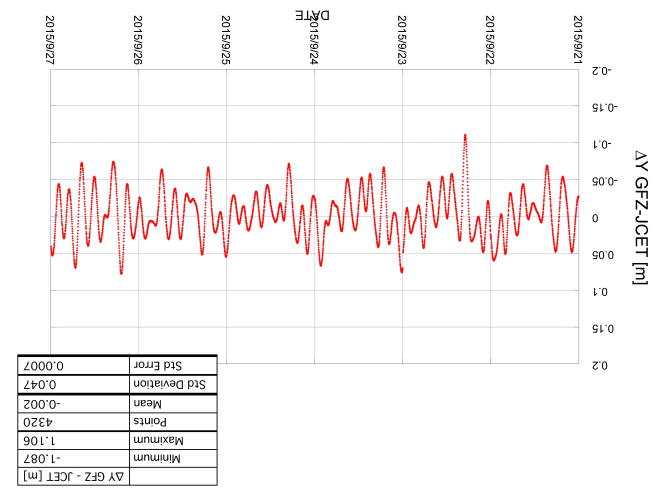
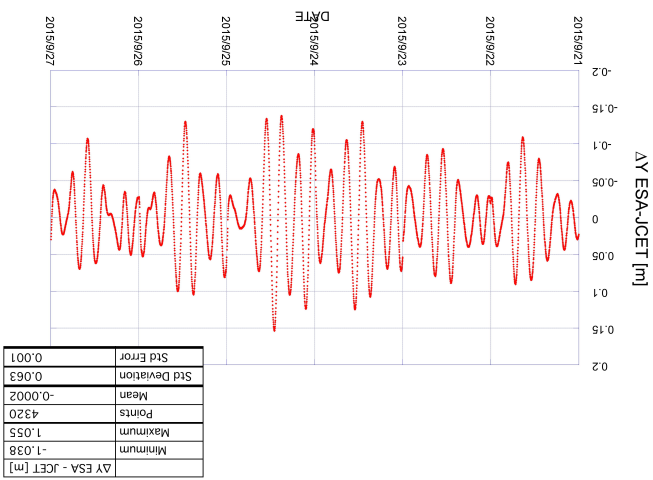
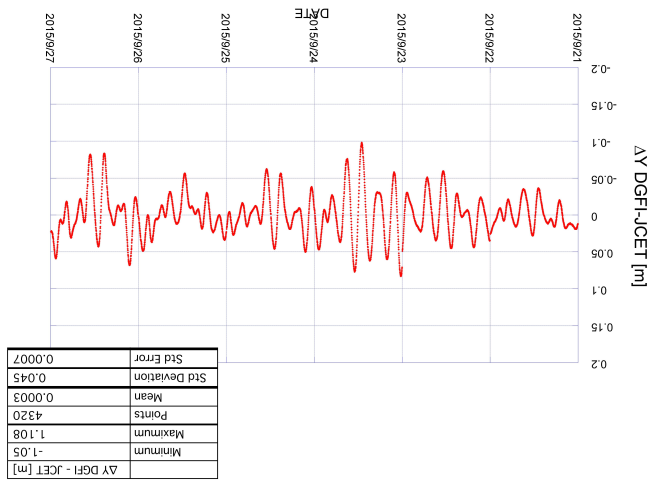
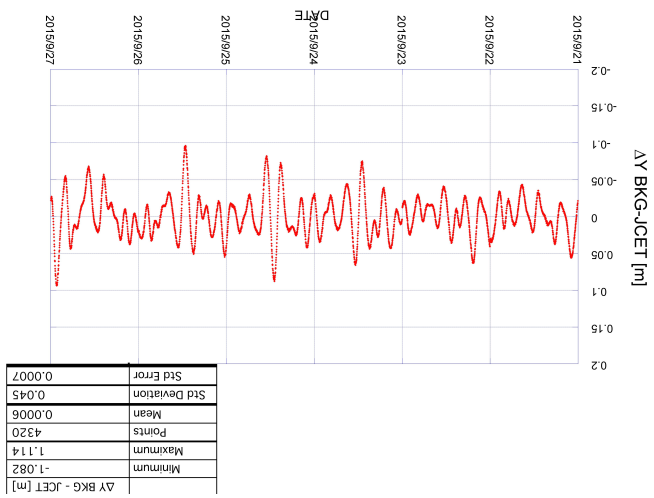
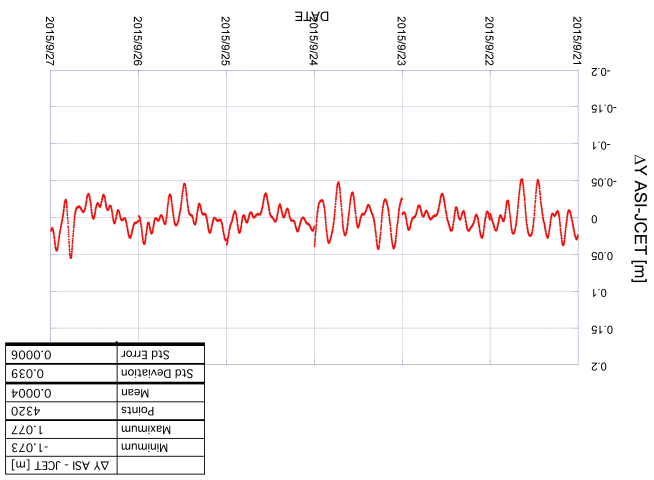


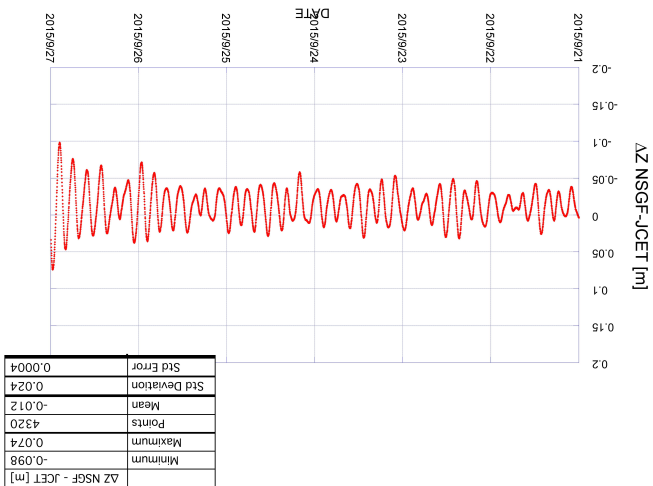
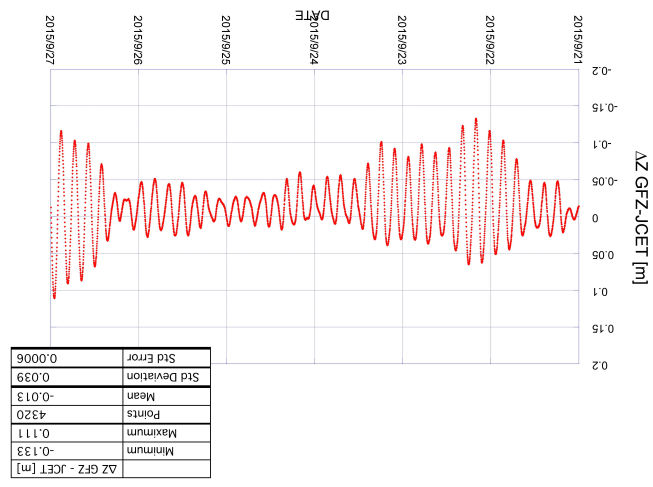
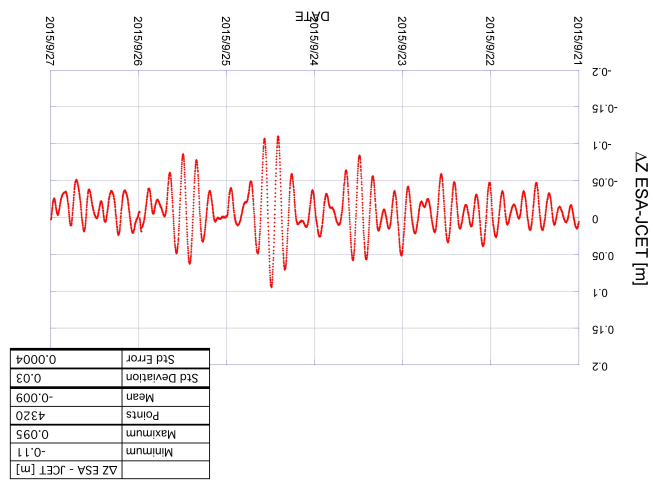
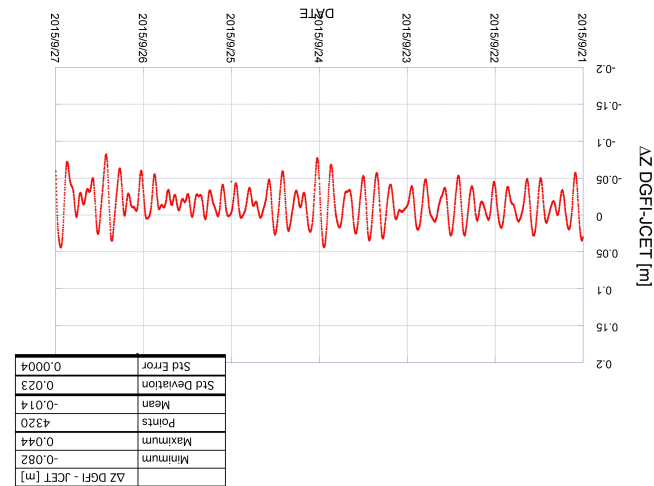
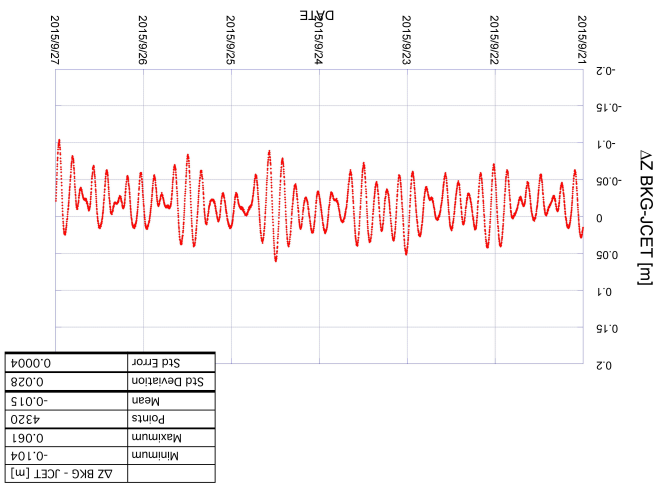


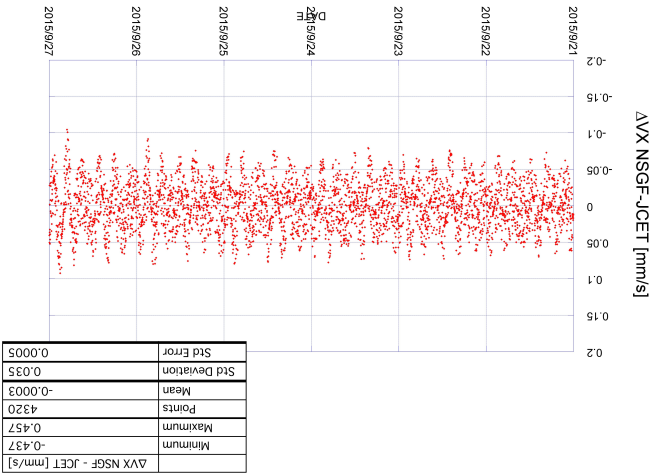
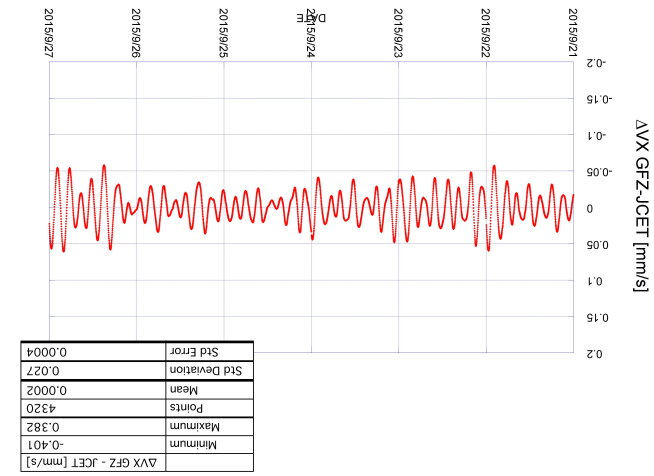
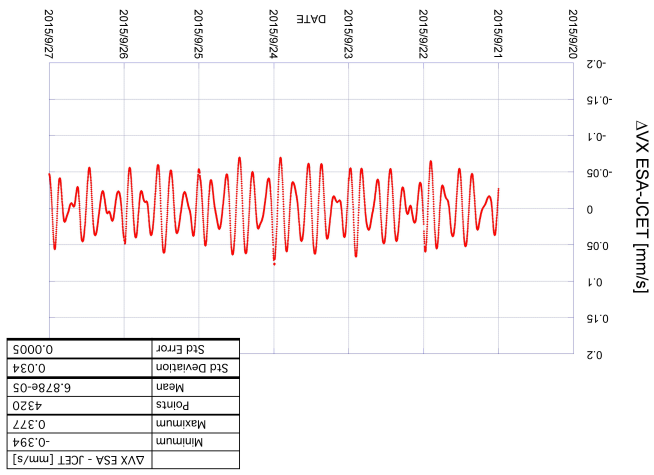
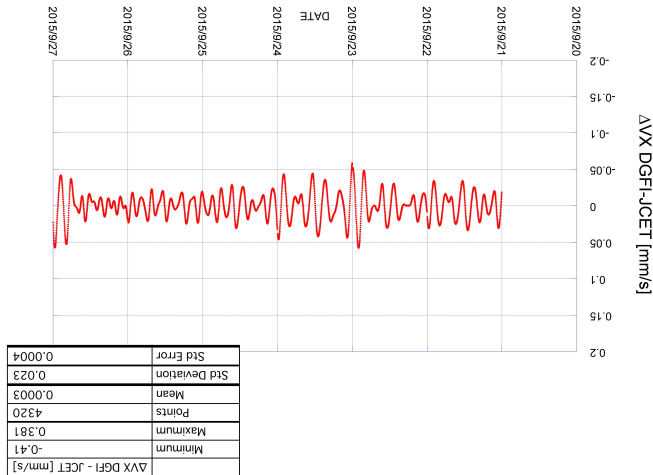
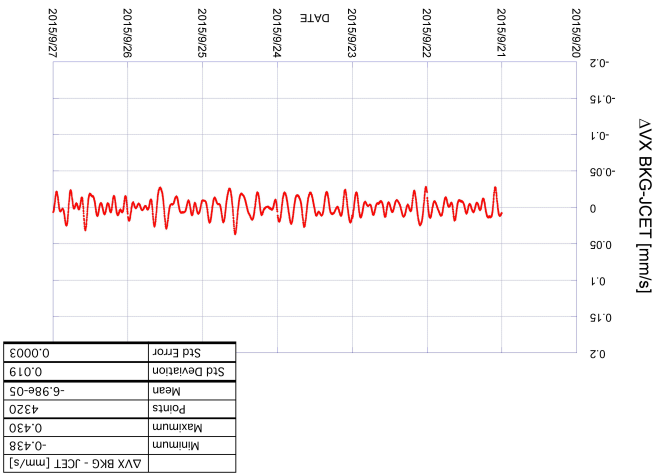
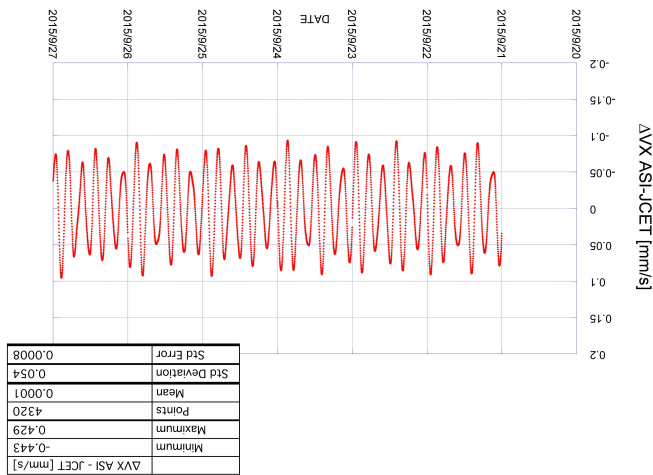


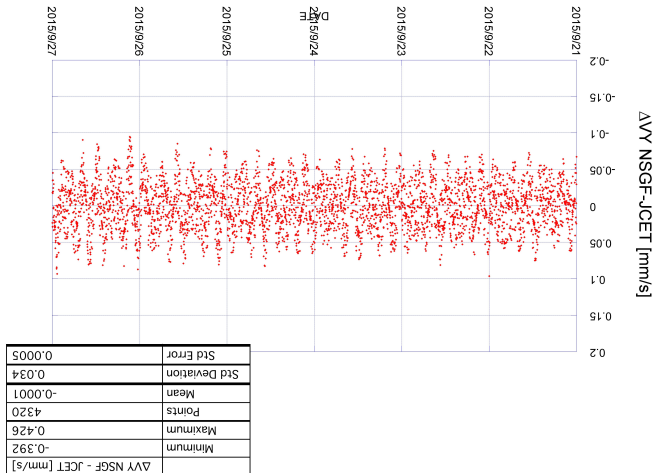
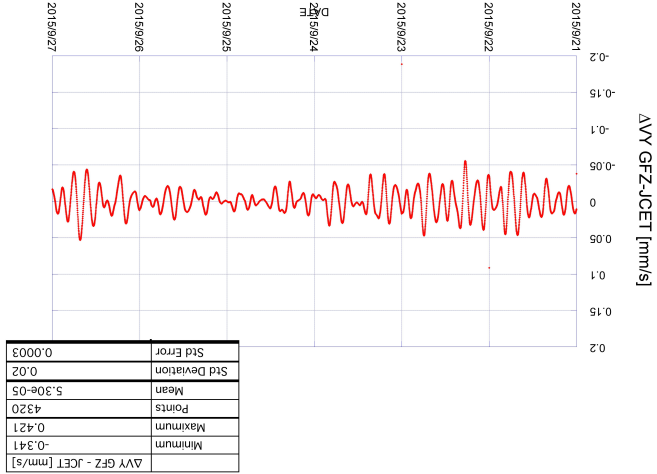
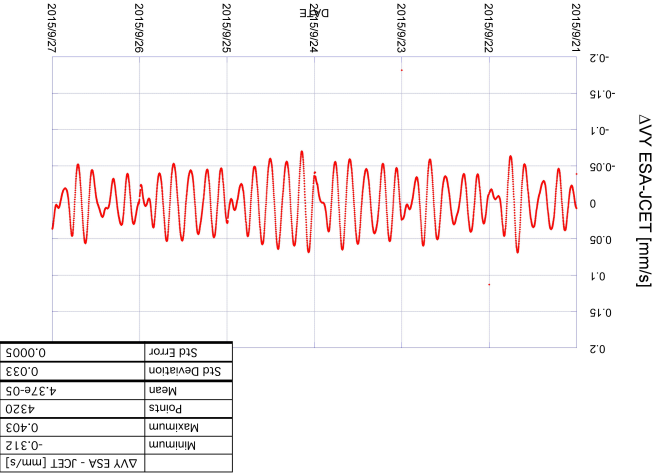
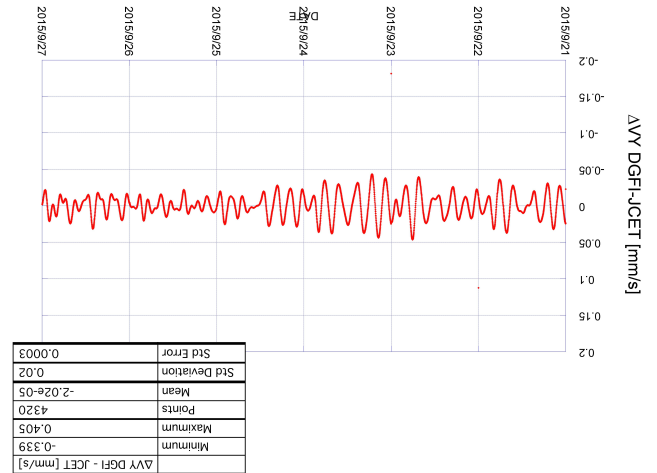
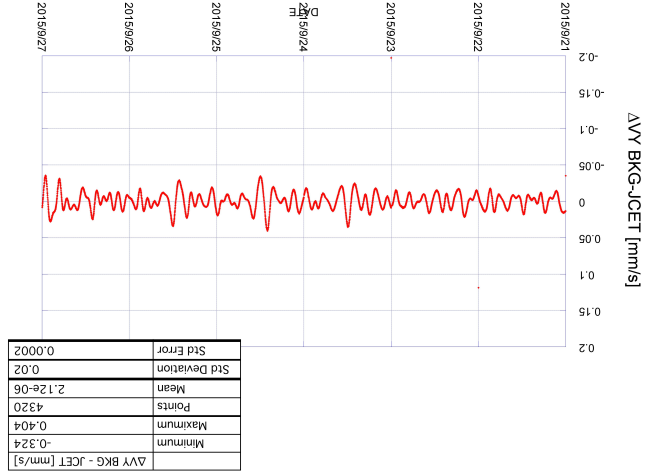
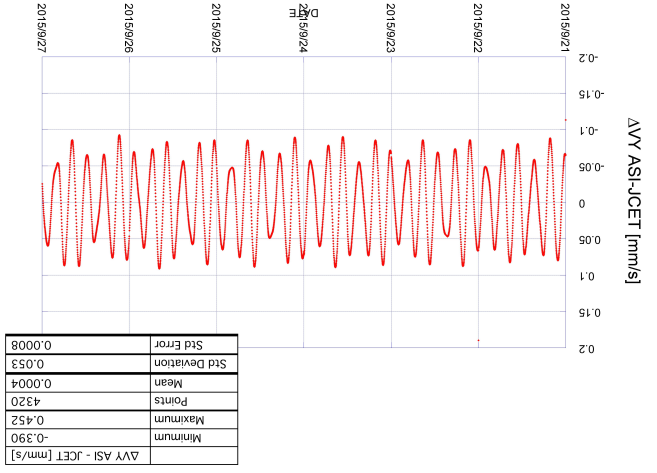


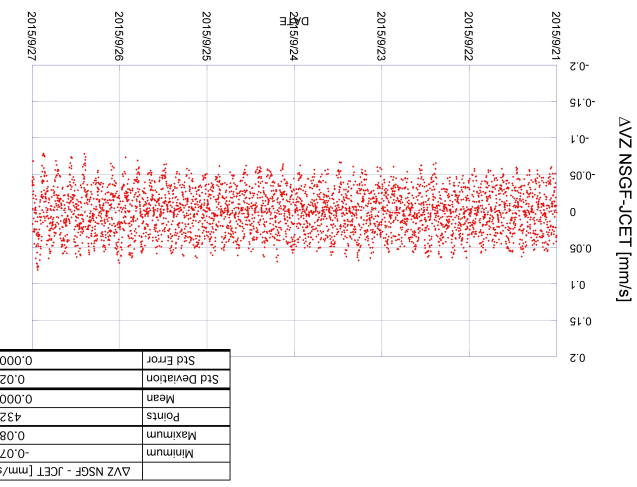
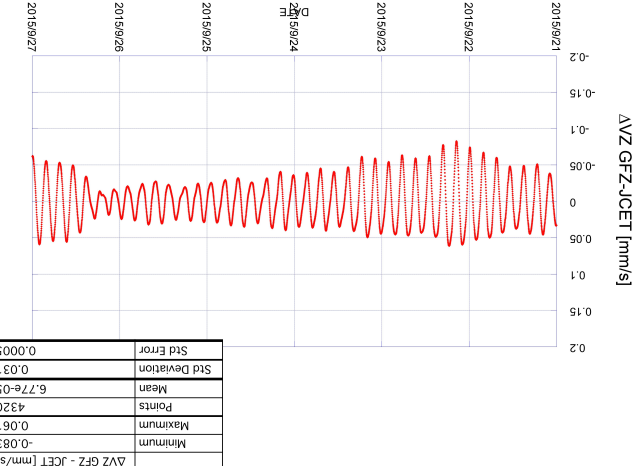
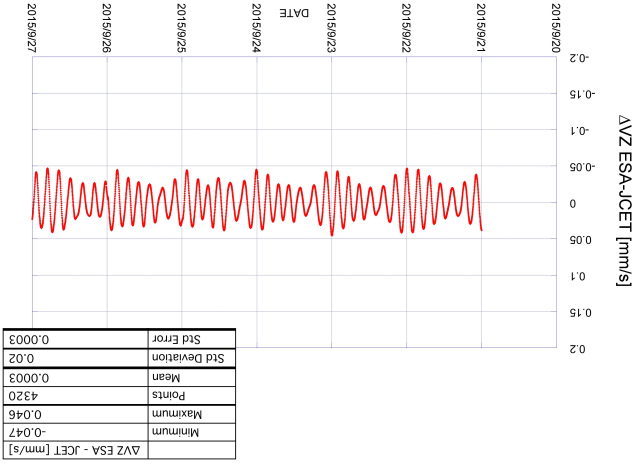
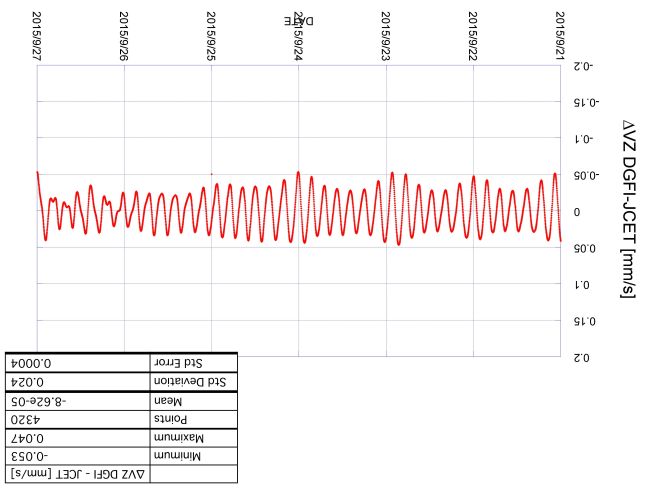
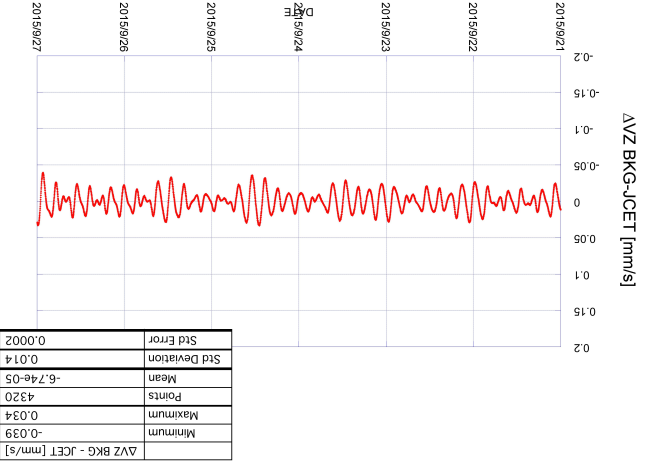
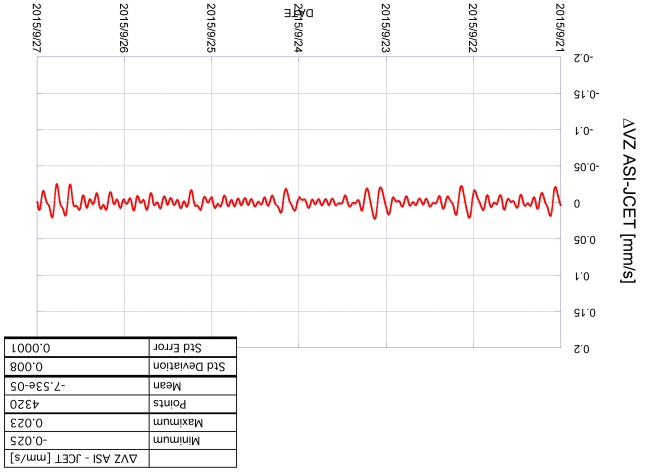












SP3C Δ Orbit [AC_i – JCET]

Week of 9/21 – 9/27 2015

LAGEOS - 1												
AC	X [m]		Y [m]		Z [m]		VX [mm/s]		VY [mm/s]		VZ [mm/s]	
	Mean	Std. Dev	Mean	Std. Dev	Mean	Std. Dev	Mean	Std. Dev	Mean	Std. Dev	Mean	Std. Dev
ASI - JCET	0.001	0.028	-0.002	0.029	-0.003	0.032	0.001	0.048	-3.00E-04	0.045	4.59E-05	0.015
BKG - JCET	-7.15E-05	0.037	-0.001	0.036	-0.002	0.040	6.51E-05	0.018	-2.96E-04	0.018	7.36E-05	0.018
DGFI - JCET	-0.001	0.030	-4.25E-04	0.027	-0.004	0.021	0.000	0.025	-3.78E-05	0.023	2.19E-04	0.019
ESA - JCET	-0.001	0.043	-0.001	0.041	0.008	0.039	2.29E-04	0.034	-3.70E-04	0.033	6.22E-05	0.022
GFZ - JCET	-0.003	0.027	0.002	0.026	-0.008	0.020	8.52E-05	0.022	7.10E-05	0.020	1.64E-04	0.018
NSGF - JCET	-0.003	0.022	0.002	0.024	-0.007	0.015	-8.37E-05	0.029	0.001	0.029	5.98E-05	0.028
LAGEOS - 2												
AC	X [m]		Y [m]		Z [m]		VX [mm/s]		VY [mm/s]		VZ [mm/s]	
	Mean	Std. Dev	Mean	Std. Dev	Mean	Std. Dev	Mean	Std. Dev	Mean	Std. Dev	Mean	Std. Dev
ASI - JCET	-0.0006	0.024	0.0004	0.039	-0.0137	0.016	0.0001	0.054	0.0004	0.053	-0.0001	0.008
BKG - JCET	-0.0005	0.031	0.0006	0.045	-0.0153	0.028	-0.0001	0.019	2.20E-06	0.015	-0.0001	0.014
DGFI - JCET	-2.50E-05	0.032	0.0003	0.045	-0.0139	0.023	0.0003	0.023	-2.02E-05	0.019	-0.0001	0.024
ESA - JCET	-0.0005	0.054	-0.0002	0.063	-0.0086	0.029	0.0001	0.034	4.37E-05	0.033	0.0003	0.022
GFZ - JCET	0.0042	0.036	-0.0025	0.047	-0.0134	0.039	0.0002	0.027	0.0001	0.020	0.0001	0.031
NSGF - JCET	0.0044	0.026	-0.0033	0.042	-0.0123	0.024	-0.0003	0.035	-0.0001	0.034	0.0009	0.029

ILRS AC work at SGF Herstmonceux

Graham Appleby, Jose Rodriguez
SGF Herstmonceux, UK



Test of ITRF2014P

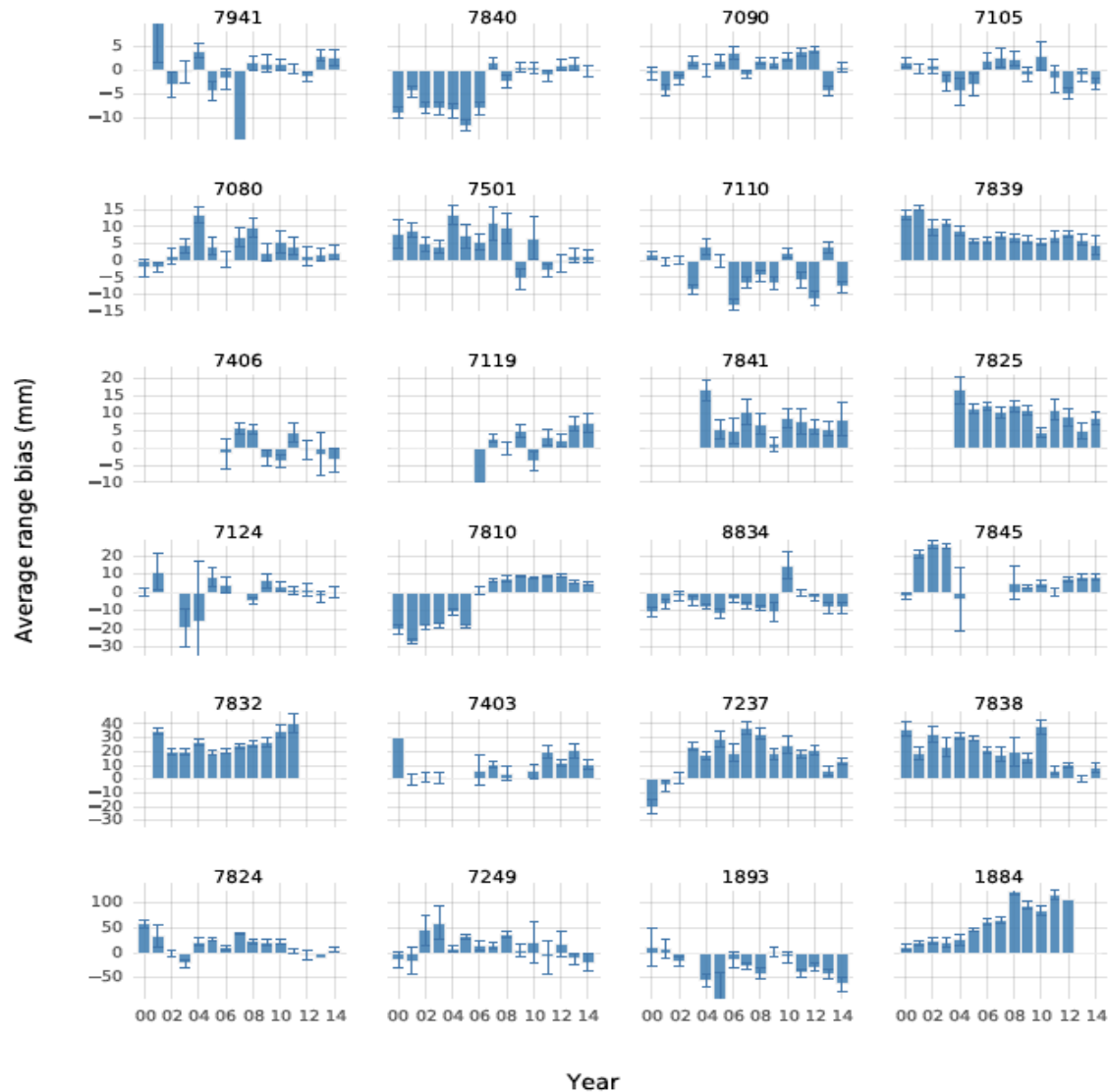
- PSD s/w and data tables implemented in SATAN
- Solutions computed for 2006-2015 with ITRF2014P a-priori
 - Small problem (with 7810) under investigation
- Otherwise, no problems encountered
 - Should be able to deliver SINEX very soon
- Gravity field – estimation implemented, SINEX-write to be done

SGF Herstmonceux

Additional test of ITRF2014P

- Laser ranging solutions from 2000 to 2015.0 were previously computed using both ILRS-recommended RB and all-station RB estimation
- A-priori coordinates: SLRF2008
- Summary of RB results from all-RB solutions:

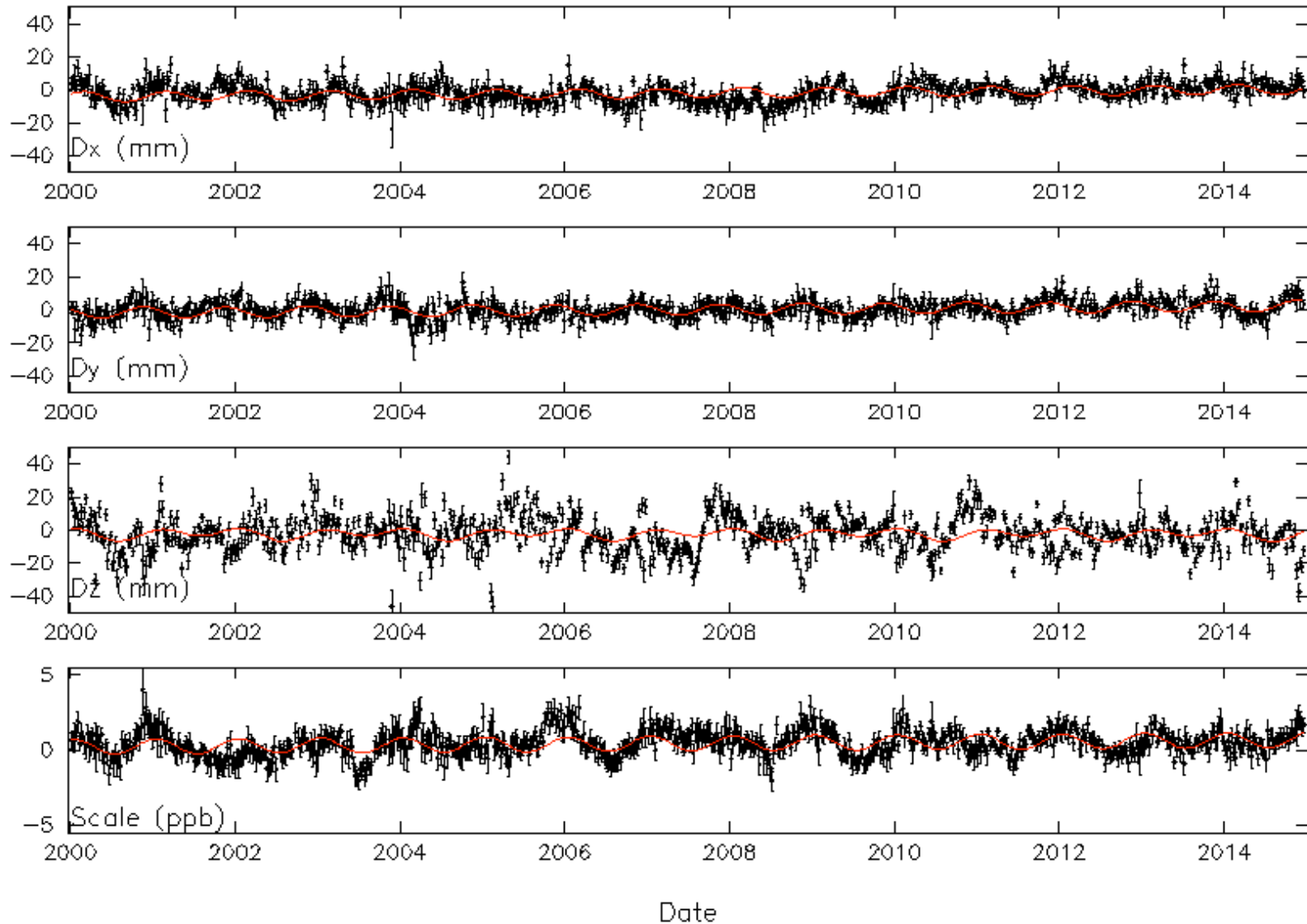
One-year av RB solutions for major sites – zero a-priori



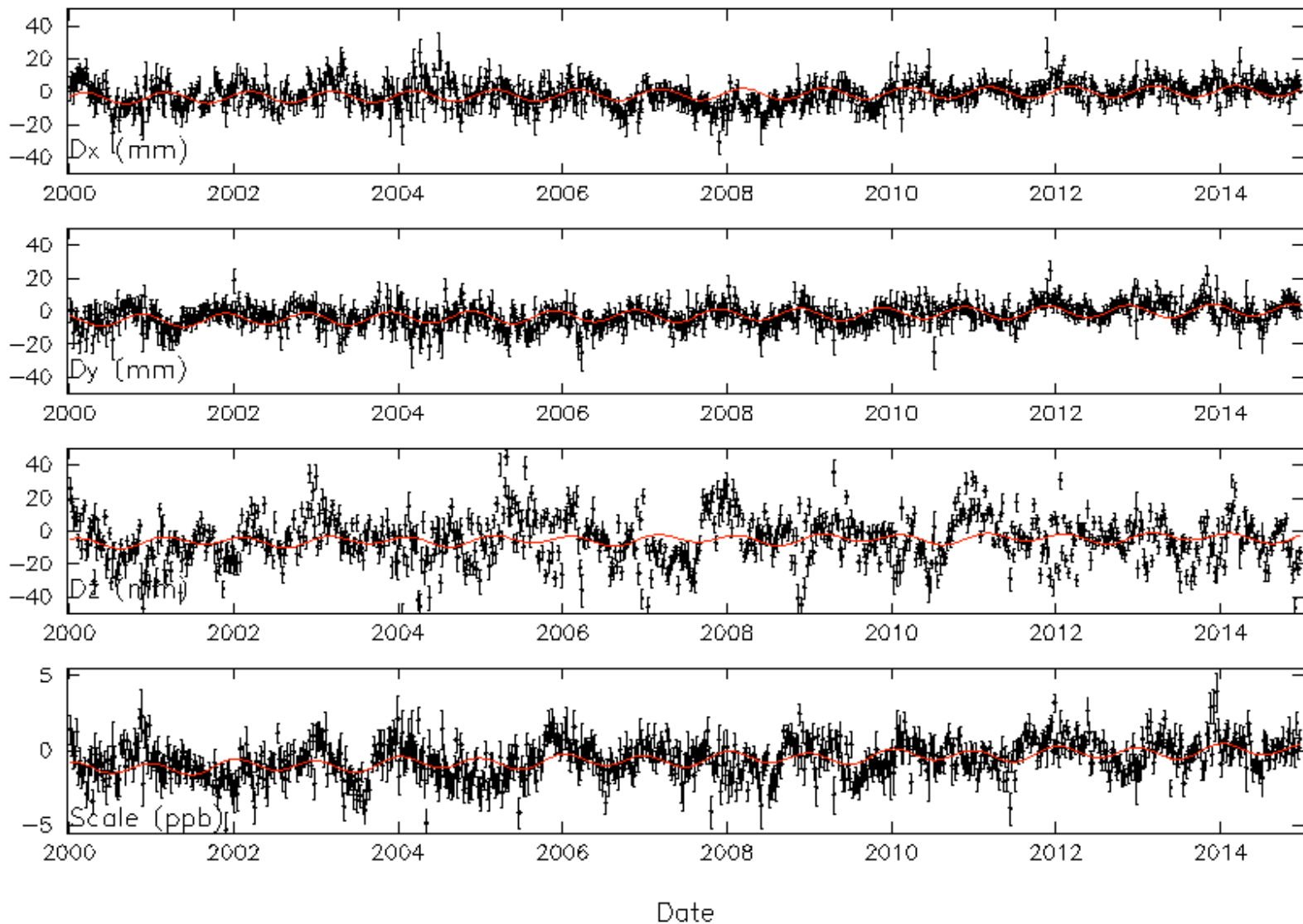
Comparison with ITRF2014P

- Then weekly SINEX solutions mapped onto ITRF2014P
 - 7-parameter iterative solutions
 - comparing each week each station XYZ with that computed at weekly epoch from ITRF2014P
- Sense of comparison is ITRF2014P – NSGF
- Plots of translations and scale for ILRS-RB and ALL-RB comparisons:

Translations and scale wrt ITRF2014P: 'ILRS standard'



Translations and scale wrt ITRF2014P: 'all RB' solutions



Numerical results (ppb)

(constant, linear, annual and semi-annual terms fitted to time series)

	ILRS-RB		ALL-RB	
Scale	+0.22	0.05	-1.21	0.08
Scale rate	+0.03	0.006	+0.09	0.009

Conclusion

- Weekly L1 & L2 Solutions for 2000-2015.0
- ‘standard’ AWG-agreed RB solutions
 - scale agrees with ITRF2014P (0.2ppb diff)
- ‘all RB’ solutions:
 - Scale difference 1.2ppb => ITRF2014P ‘too small’
- Very similar results to our previous comparison with ITRF2008