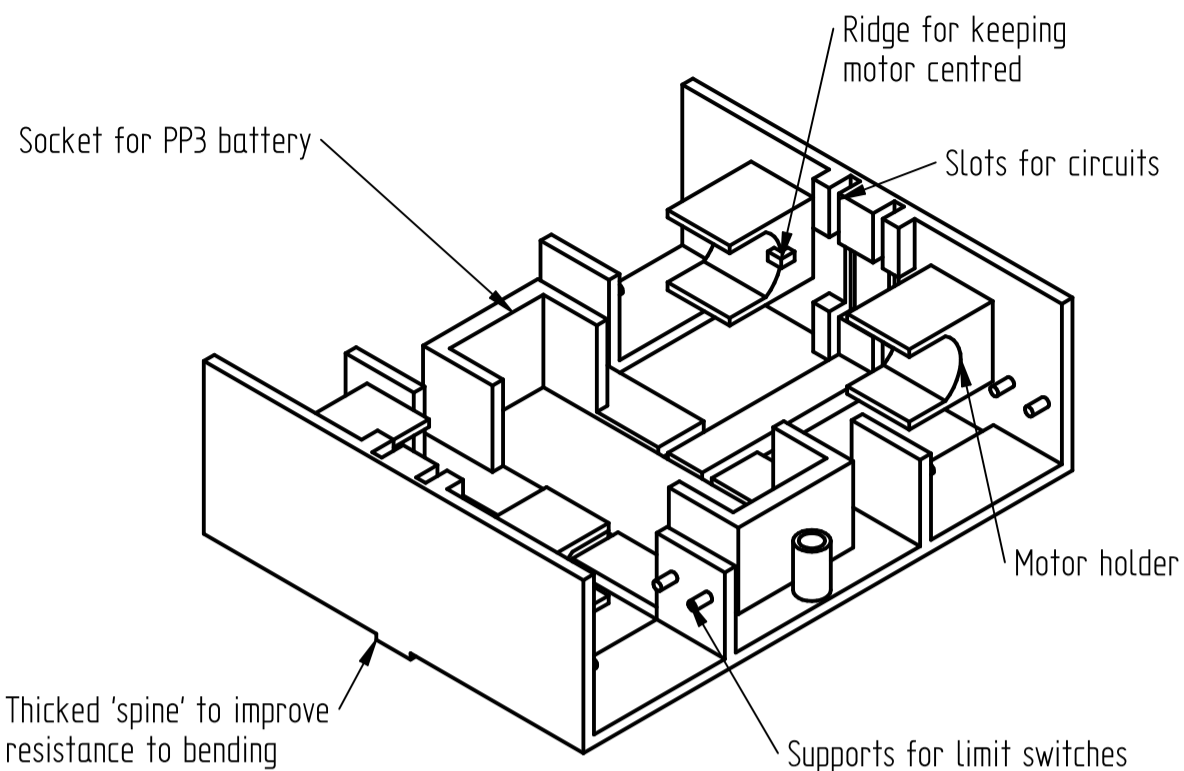
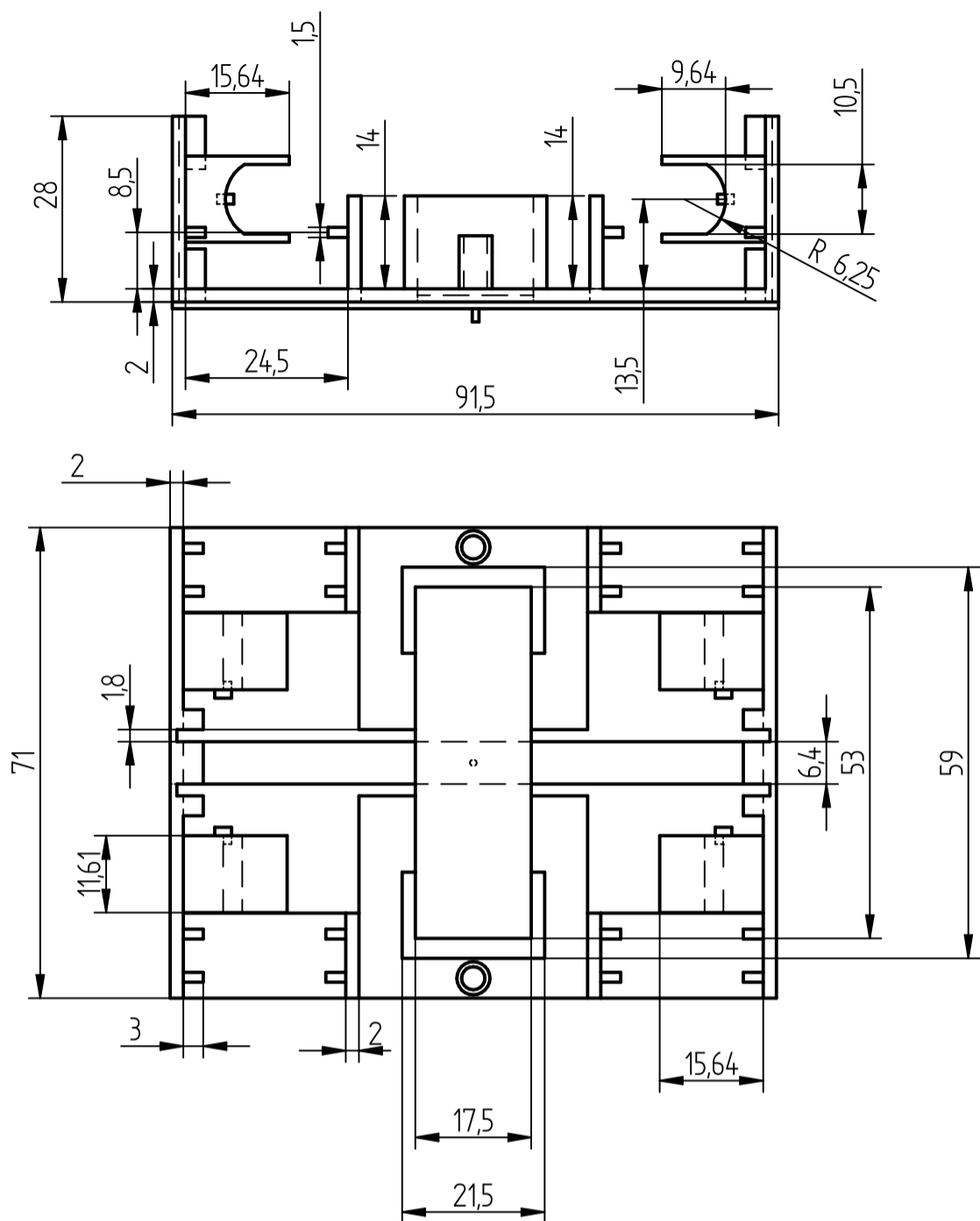


(a) Robot body. All dimensions in mm



(b) Robot leg. The 'shoulder' is asymmetrical to allow greater range of movement in one direction; this leg is used on the front left and hind right legs, the other two legs are mirrored. All dimensions in mm or degrees.

